Advanced Modeling of Particle Accelerators

J.-L. Vay, T. Drummond, A. Koniges, B. Loring, C. Mitchell, J. Qiang, O. Ruebel, R. Ryne, H. Vincenti

Lawrence Berkeley National Laboratory, CA, USA

D. P. Grote

Lawrence Livermore National Laboratory, CA, USA

Axel Hübl

Helmholtz-Zentrum Dresden Rossendorf, Germany

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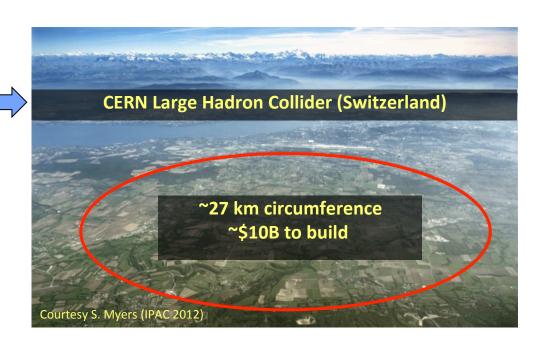


Accelerators are essential tools of science and tech.

There are > 30,000 particle accelerators in operation around the world,

serving:

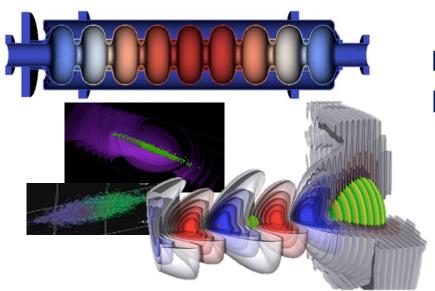
- discovery science,
- medicine,
- industry,
- energy,
- the environment,
- national security.



Size and cost are a limiting factor for many applications

→ active research worldwide to conceive smaller & cheaper accelerators.

Computer modeling is key to progress



Essential for increasing performance, bringing size and cost down:

- optimizing existing accelerators,
- cost effective design,
- game changing technologies.

Trend requires team work for large multi-physics simulations

increasingly complex accelerators call for increasingly sophisticated simulation software

BLAST* (Berkeley Lab Accelerator Simulation Toolkit)



BeamBeam3D

BeamBeam3D is a parallel, <u>electrostatic</u> particle-in-cell (PIC) code for modeling strong-strong or strong-weak beam-beam interaction in high-energy colliders.

IMPACT

IMPACT is a 3-D parallel electrostatic PIC framework, incorporating maps, for modeling high-intensity, high-inghtness beams in accelerators.

WARP

WARP is a 2- and 3-D, parallel, <u>electrostatic</u> and <u>electromagnetic</u> PIC framework, aware of the accelerator lattice, that is used to model the generation, transport, and neutralization of charged-particle beams. It also has uses in modeling ion traps and laser-plasma accelerators.

Posinst

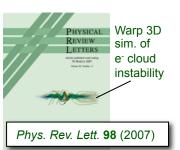
Posinst is a 2-D <u>electrostatic</u> PIC code for studying the buildup of electron clouds.

Many algorithms invented, improved or pioneered in BLAST codes

Algorithm/method	Reference	Originated	Adopted by
Damped EM & particle pushers	Friedman, JCP 1990	Warp	LSP, Elixirs
Warped coordinates PIC in bends	Friedman et al, Phys. Fluid 1992	Warp	
Integrated Maps for rf cavity dynamics	Ryne, LANL Report 1995	ML/IMPACT	D. Abell (nonlinear model)
Stochastic Leap-Frog for Brownian motion	Qiang & Habib, PRE 2000	IMPACT	
Spectral-finite difference multigrid solver	Qiang & Ryne, CPC 2001	IMPACT	
Improved Perfectly Matched Layers	Vay, JCP 2000/JCP 2002	Warp	Osiris
AMR-PIC electrostatic	Vay et al, LPB2002/PoP2004	Warp	
Secondary emission of electrons algorithm	Furman & Pivi, PRST-AB 2003	Posinst	TxPhysics, Warp, spacecraft charging codes
AMR-PIC electromagnetic	Vay et al, CPC 2004	Emi2D	Warp
3D Poisson solver with large aspect ratio	Qiang & Gluckstern, CPC 2004	IMPACT	
Shift-Green function method	Qiang et al, CPC 2004	BBeam3D	
Integrated Green function	Ryne & Qiang	ML/IMPACT	BB3D, IMPACT
Hybrid Lorentz particle pusher	Cohen et al, NIMA 2007	Warp	

and adopted by other codes

Algorithm/method (cont.)	Reference	Originated	Adopted by
Lorentz boosted frame	Vay, PRL 2007	Warp	INF&RNO, JPIC, Osiris, Vorpal
Explicit Lorentz invariant particle pusher	Vay, PoP 2008	Warp	Tristan (astro), QED, Photon-Plasma
New convolution integral w/ smooth kernel	Qiang, CPC 2010	N/A	
Mixed Particle-Field decomposition method	Qiang & Li, CPC 2010	BBeam3D	
PIC with tunable electromagnetic solver	Vay et al, JCP 2011	Warp	Vorpal, Osiris
Efficient digital filter for PIC	Vay et al, JCP 2011	Warp	Vorpal, Osiris
Laser launcher from moving antenna	Vay et al, PoP 2011	Warp	Vorpal, Osiris
Domain decomposition for EM spectral solver	Vay et al, JCP 2013	Warp	



Example:

Lorentz boosted frame method (performing calculation in optimal frame – next slide)

- first developed at LBNL with application to FEL and e⁻ cloud instability,
- methods (developed in Warp) implemented in Osiris, Vorpal, etc. (Laser Plasma Acc.)
- results reported in DOE-OS news http://science.energy.gov/news/in-focus/2011/04-21-11-s

Berkeley Lab Accelerator Simulation Toolkit has a worldwide user base



Bl	_AS	T
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B – BeamBeam3D

I – Impact

P – Posinst

W – Warp

United States

Europe/Asia

1.ANL (B,I,P)	13.ORNL (I,P)	1. ASLS (I)	14.IMPCAS (I)

2.BNL (B,I,P,W) 14.SLAC (I,P,W) 2.CERN (P,W) 15.IRE (I)

3. Cornell (I,P) 15. Stanford (I) 3. CIAE (I) 16. KAERI (I)

4.FNAL (B,I,P,W) 16.Tech-X (P) 4.DESY (I,W) 17.KEK (I)

5.ISU (I) 17.Texas A&M (I) 5.Diamond (I) 18.Mumbai Univ. (I)

6. Jlab (B,I,P) 18. U. Chicago (I) 6. ESS (I) 19. PAL (I)

7. LANL (I,P) 19.UM (W) 7. Fermi/Elettra (I) 20. Peking Univ. (I)

8.LBNL (B,I,P,W) 20.UMD (W) 8.Frankfurt (I) 21.PSI (I)

9.LLNL (W) 21.UW (I) 9.GSI (I,W) 22.RRCAT (I)

10.MSU (I,W) 22.UCLA (I) 10.Hiroshima U. (W) 23.RAL (I)

11.NIU (I,W) 23.WSU (W) 11.Hong Kong U. (W) 24.SINAP (I)

12.ODU (I) 24.Yale U (B,I) 12.IBS (I) 25.Technion (W)

13.IHEP (I,P) 26.USTC (I)

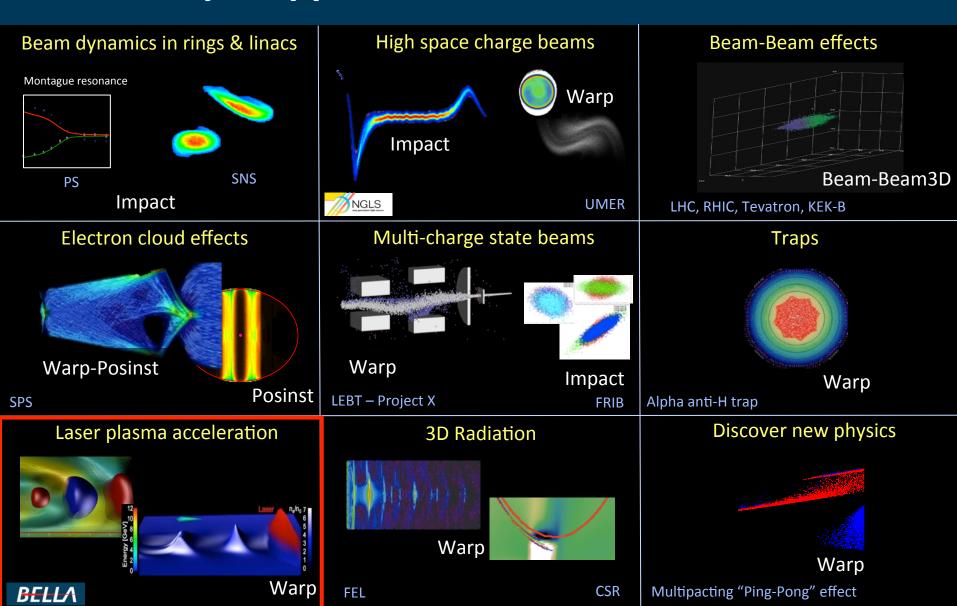


Over past year, code developers responded to

>500 emails received from >40 research institutes/universities & list is growing.

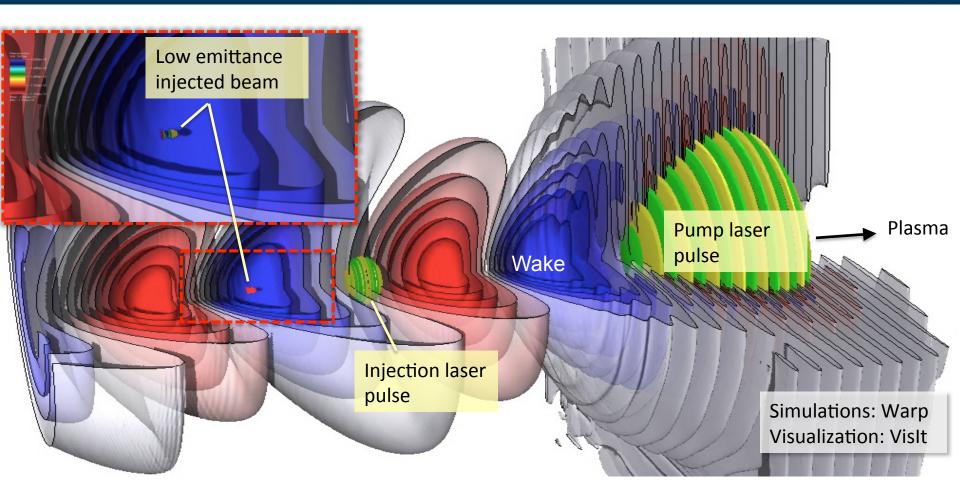
Need for development with minimal disruptions to users.

Sample applications of the BLAST codes



Large scale simulations validated a new concept of injection of ultra-low emittance beam*



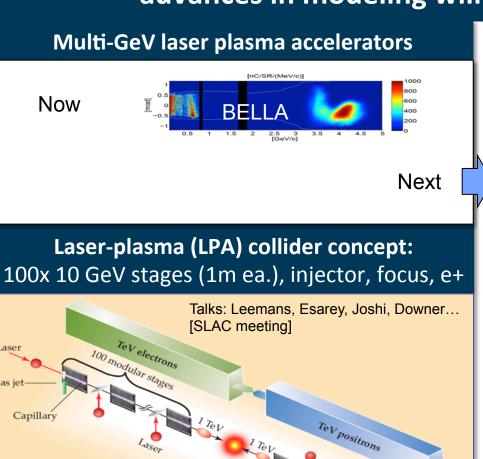


Parametric runs necessitated over a million hours; typical 3-D "medium res." run ~ 100k core-hours.

Larger simulations needed for high resolution modeling through entire stage.

^{*}L.-L. Yu, E. Esarey, C. B. Schroeder, J.-L. Vay, C. Benedetti, C. G. R. Geddes, M. Chen, and W. P. Leemans, Phys. Rev. Lett. 112, 125001 (2014)

future-generation accelerators at dramatically lower cost advances in modeling will offer new opportunities



Positron production targe

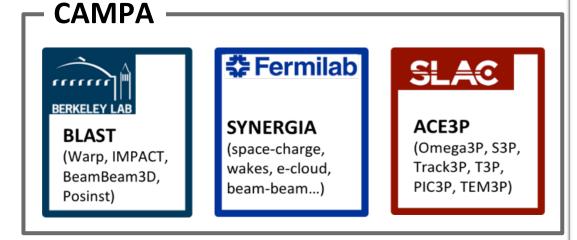


Advances in computers & algorithms:

- real-time of single stages on clusters,
- design of colliders on supercomputers.

New initiative:

Consortium for Advanced
Modeling of Particle
Accelerators



Points of contact:

LBNL: J.-L. Vay, J. Qiang

SLAC: C.-K. Ng, Z. Li

FNAL: J. Amundson, E.G. Stern



OpenSource Development (GPL/LGPL)



General Many-Core Algorithms (x86 & Xeon Phi port started)

7.2 PFlop/s reported in ACM Gordon Bell 2013

modular, general purpose, particle-mesh library

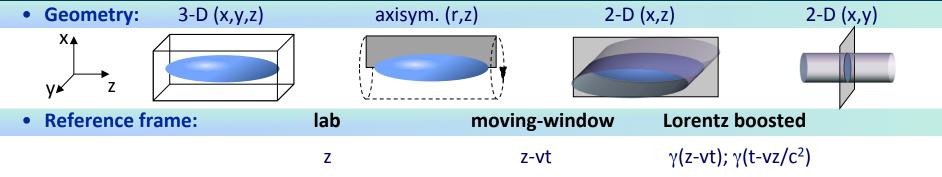
implements fully-relativistic 3D3V particle-in-cell algorithm

simulate **laser-plasma interactions** for next-gen. *particle accelerators*

In situ diagnostics

live rendering, high-throughput I/O with ADIOS, far-field radiation, multi-physics, interactive simulations

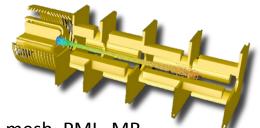
Warp: Particle-In-Cell framework for accelerator modeling



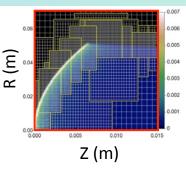
Field solvers

electrostatic/magnetostatic - FFT, multigrid; AMR; implicit; cut-cell boundaries

Versatile conductor generator accommodates complicated structures



Automatic meshing & around ion beam source emitter



- Fully electromagnetic Yee mesh, PML, MR
- Accelerator lattice: general; non-paraxial; can read MAD files
 - solenoids, dipoles, quads, sextupoles, linear maps, arbitrary fields, acceleration.

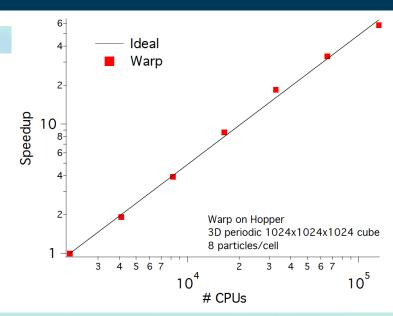
Particle emission & collisions

- particle emission: space charge limited, thermionic, hybrid, arbitrary,
- secondary e- emission (Posinst), ion-impact electron emission (Txphysics) & gas emission,
- Monte Carlo collisions: ionization, capture, charge exchange.

Warp is parallel, combining modern and efficient programming languages

• Parallellization: MPI (1, 2 and 3D domain decomposition)

Parallel strong scaling of Warp 3D PIC-EM solver on Hopper supercomputer (NERSC)



Python and FORTRAN*: "steerable," input decks are programs

From warp import *

Imports Warp modules and routines in memory

Sets # of grid cells

dt = 0.5*dz/vbeam

Initialize()

step(zmax/(dt*vbeam))

Initializes internal FORTRAN arrays

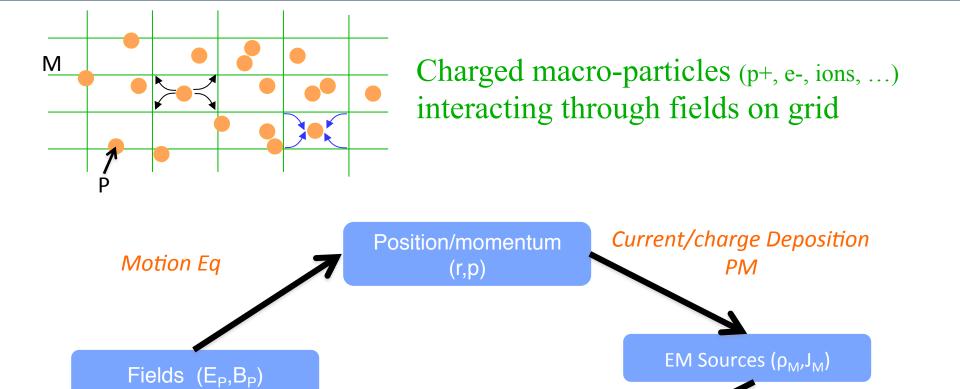
Pushes particles for N time steps with FORTRAN routines

Goal: identify hotspots that limit performances while porting to KL.

^{*}http://hifweb.lbl.gov/Forthon (wrapper supports FORTRAN90 derived types) – dpgrote@lbl.gov

PRINCIPLE OF A PARTICLE-IN-CELL CODE

Field Gathering
MP



Fields (E_M,B_M)

Maxwell's/Poisson Eq

GENERAL PERFORMANCE CONSIDERATION OF PIC CODES

In Hybrid MPI/Open MP schemes hot spots may come from:

1. Shared memory part of the code (OpenMP)

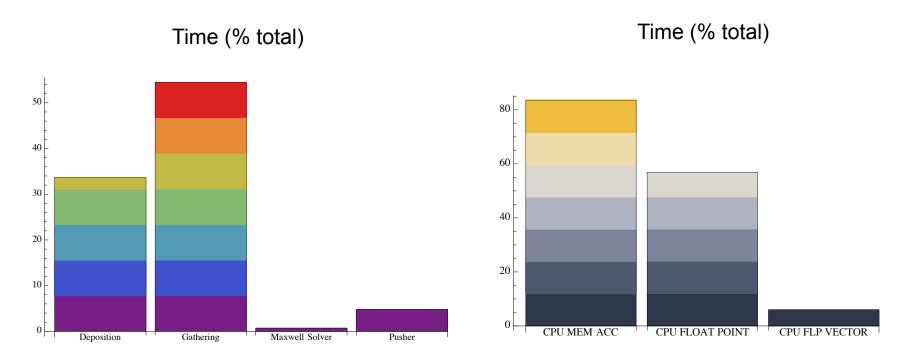
- Field Gathering/Current deposition: cache misses (particles not contiguous in memory). Particle sorting/tiling?
- Unvectorized loops (flow-dependency, function call etc.) : re-write/organize some parts of the PIC code?

2. Distributed memory level (MPI)

Uneven repartition of particles among processors: dynamic load balancing

- Parrallelization on Distributed memory architectures is very efficient.
 - Local method for solving Maxwell's equation,
 - One potential limitation: load balancing.
 Dynamic Load balancing strategies could be implemented in WARP.
- Here we focus on what could limit parallel performance on shared memory architecture (basically on each node with OpenMP>= 1thread).
 - Relevant for future KnightsLanding architecture at NERSC.
- Performance analysis of WARP kernel on EDISON/BABBAGE to identify potential hotspots:
 - First study: sequential mode (OMP_NUM_THREADS=1),
 - Second study: limitations in terms of scalability (OMP_NUM_THREADS>1).

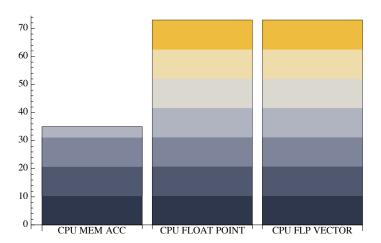
- First study: sequential mode (OMP_NUM_THREADS=1)
 - Total performance of the kernel (standard 2D3V laser-plasma acceleration case):



- Total time dominated by deposition/gathering subroutines
- High memory access and Low vectorization

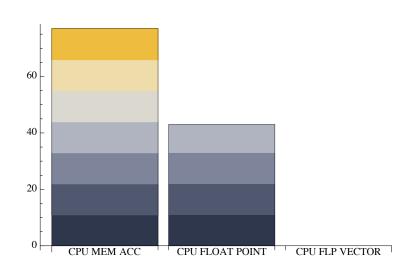
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 - Performance of particle pusher vs. deposition&gathering

Pusher (% total)



- Moderate memory access,
- loop is well vectorized:
- we can expect good OpenMP performance

Dep&Gat (% total)

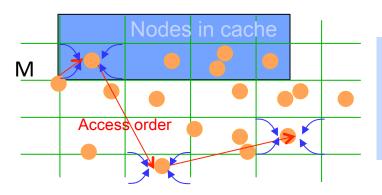


- High memory access (cache misses &/or inefficientlystructured code)
- loop is not vectorized
- poor future OpenMP performance?

1. First study: sequential mode (OMP_NUM_THREADS=1)

Possible improvements for deposition/gathering routines:

Ex: Field gathering process



Code structure

DO i=1,nparticles
DO inode=1,N_adjacentnodes
Field(particle)= Field(particle)+Weight*Field(inode)
END DO
END DO

- WITH CURRENT STRUCTURE, PARTICLE ACCESS ORDER INDUCE LOT OF CACHE MISSES
- PARTICLES MUST BE SORTED SO THAT CPU ACCESS CONTINUOUS DATA IN CACHE: « PARTICLE TILING »

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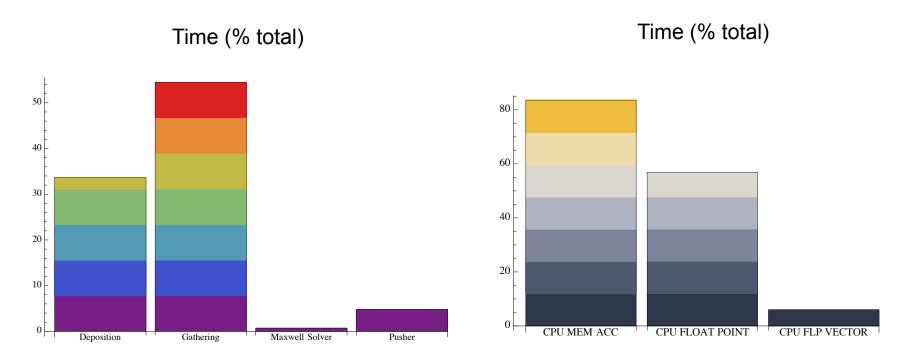
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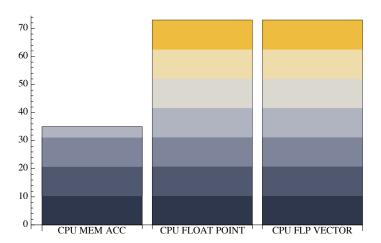
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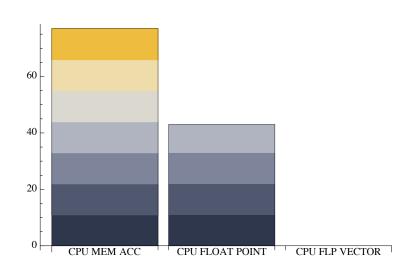
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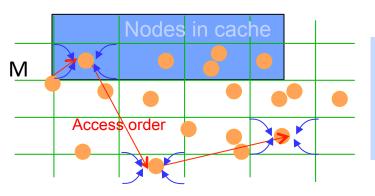


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2. Second study: parallel mode (OMP_NUM_THREADS>1)

Particle pusher: preliminary optimization

Initial structure of particle pusher

```
DO i=1,ntstep
! $OMP PARALLEL
! Push velocities
call pushv(particles) !loop on particles (OMP DO)
....
! Push positions
call pushx(particles) !loop on particles (OMP DO)
....
!$OMP END PARALLEL
End DO
```

New structure (Merged loops)

DO i=1,ntstep

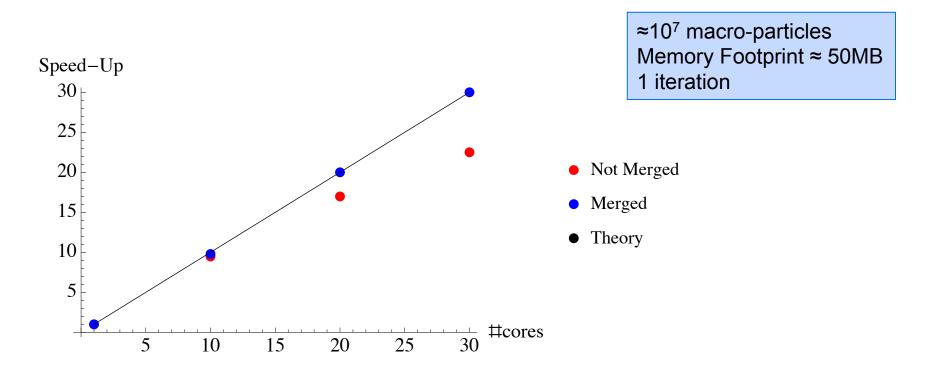
\$OMP PARALLEL
! Push velocities
call pushvx(particles) !merged loop on
particles

\$OMP END PARALLEL
END DO

- MERGE LOOPS TO AVOID OVERHEADS COSTS
- BIGGER LOOPS MAY ALSO INCREASE VECTORIZATION PERFORMANCE AND REDUCE MEM ACC

2. Second study: parallel mode (OMP_NUM_THREADS>1)

Particle pusher: scaling test after simple optimization



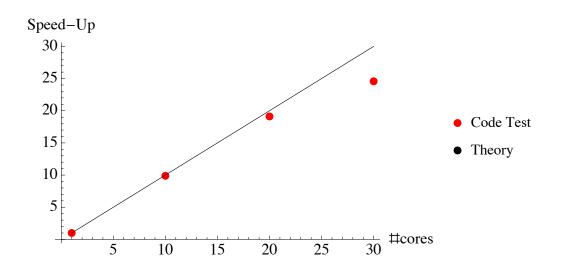
VERY GOOD SCALING ON A FEW TENS OF CORES ON BABBAGE

2. Second study: parallel mode (OMP_NUM_THREADS>1)

Field gathering routine:

Code structure for field gathering subroutine

```
!$OMP PARALLEL DO PRIVATE(i,inode)
DO i=1,nparticles
DO inode=1,N_adjacentnodes
Field(particle)= Field(particle)+Weight*Field(inode)
END DO
END DO
!$OMP END PARALLEL DO
```



≈10⁷ macro-particles Nx=Ny=512 Memory Footprint ≈ 50MB 1 iteration

 GOOD SCALING ON A FEW TENS OF CORES ON BABBAGE

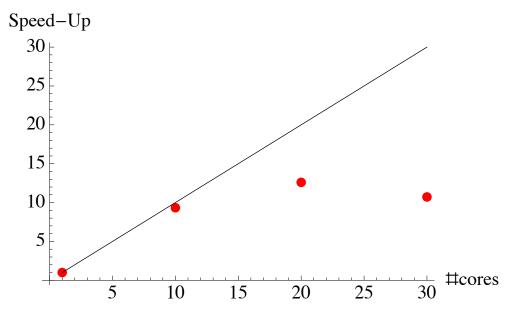
2. Second study: parallel mode (OMP_NUM_THREADS>1)

Current deposition routine: code structure

Code structure for current deposition subroutine

2. Second study: parallel mode (OMP_NUM_THREADS>1)

Current deposition routine: performance test



≈10⁷ macro-particles
Nx=Ny=512
Memory Footprint ≈ 50MB
1 iteration

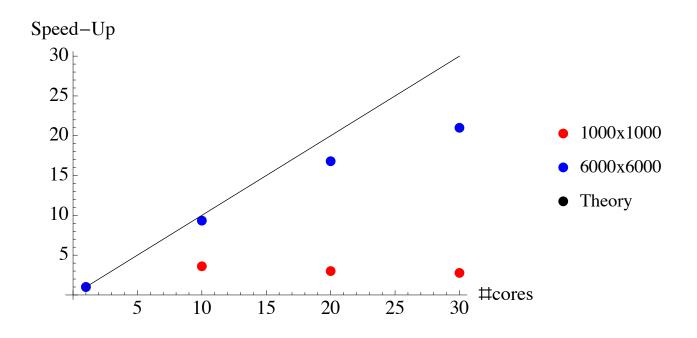
- Code Test
- Theory
 - ◆ BAD SCALING FOR LARGE NUMBER OF CORES (>10)
 - NEEDS FURTHER OPTIMIZATION: LOOP ON NODES INSTEAD OF PARTICLES?→ NO REDUCTION (LIKE FIELD GATHERING)

2. Second study: parallel mode (OMP_NUM_THREADS>1)

Maxwell solver: code structure

2. Second study: parallel mode (OMP_NUM_THREADS>1)

Maxwell solver: code performance



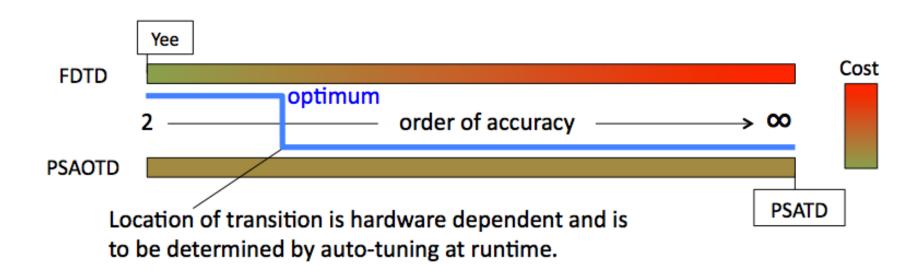
 GOOD SCALING ON A FEW TENS OF CORES FOR FIELD MATRIX>10MB

Long term: ultimate flexibility with runtime auto-tuning of order of accuracy vs locality

Larger stencils → higher order of accuracy but lower locality

Limit of infinite order with FFT.

FFT global but Maxwell local → local FFT on nodes or group of nodes*



Warp+VisIt

- The science problem we want to solve as part of NESAP
 - Reduce I/O cost (write/read data to/from persistent storage for storage/post-process.)
 - Analyze and visualize data while it is generated
- High level architecture/algorithm of code for the Intel and Cray people
 - Tightly coupled in situ visualization and analysis using VisIt
 - Vis. algo. required for accelerator application range from standard plotting functions to volume visualizations, surface extraction, particle advections and many more
- Potential challenges for getting the code to run well on KL
 - Vis. & analyses have greedy memory use. Limited memory per core and competition for memory between the sim and vis are a potential problem.
 - Need to address coordination & synchronization between simulation & vis which will
 use distinct thread pools (e.g. NUMA issues as data is transferred from one thread pool to the other).
 - Visit's threading is new & relatively untested. We expect to identify and address performance issues as we apply complex pipelines used by scientists.
 - Will work closely with SDAV on these issues. Not just an issue for VisIt but for highperformance visualization in general. SDAV has a NESAP proposal focusing on these issues.
 - Simulations have best case scenario for optimization on the MIC. Legacy C++ vis codes have the worst case scenario (e.g. fewer opportunities for vectorization exist. Need to narrow the performance gap)

Warp+VisIt

Performance data and code profiles:

- David Camp, Wes Bethel and Hank Childs. "Transitioning Data Flow-Based Visualization Software to Multi-Core Hybrid Parallelism". Proceedings of Data-Flow Execution Models for Extreme Scale Computing (DFM 2013) conference. LBNL-6363E. (bibtex) (PDF)
- http://vis.lbl.gov/Vignettes/TrillionZones/

How NERSC, Cray, Intel can help

- Performance and thread profiling
- Vis writes many small files. Burst buffers slated for Cori can be used for in-situ vis related I/O.
- In situ analysis can benefit from burst buffers as an active cache to save data needed for analysis out-of-core (e.g, for analyses across time-steps, acceleration structures for data search/query, topology graphs etc.)