

Codee Training Series

April 25-26, 2023

The NERSC logo consists of the letters "NERSC" in a bold, white, sans-serif font, centered within a dark blue rounded rectangle.

NERSC



Shift Left Performance

Automated Code inspection for Performance

ZPIC: The code “em2d”

Website: <https://zpic-plasma.github.io/> [last checked: Apr 2023]

Github: <https://github.com/zpic-plasma/zpic> [last checked: Apr 2023]

- Particle-in-Cell (PIC) codes are used in almost all areas of plasma physics, such as fusion energy research, plasma accelerators, space physics, ion propulsion, and plasma processing, and many other areas.
- ZPIC is a suite of 1D/2D fully relativistic electromagnetic PIC codes, as well as 1D electrostatic.
- Code written in the C programming language.
- The directory structure is organized as follows:
 - em1d - 1D electromagnetic (finite difference)
 - em1ds - 1D electromagnetic (spectral)
 - em2d - 2D electromagnetic (finite difference)
 - em2ds - 2D electromagnetic (spectral)
 - es1d - 1D electrostatic
 - mods - Modified versions of the base codes
 - python - Python interface to ZPIC codes

Benchmark “ZPIC/em2d”

14 files

193 functions

141 loops

4035 lines of code (SLOC)

Build, run & verify ZPIC with Weibel workload

```
$ cd em2d-0-serial
$ make clean
$ make CC=gcc CFLAGS="-Ofast"
$ ./zpic
Starting simulation ...
```

```
n = 0, t = 0.000000
n = 1, t = 0.070000
n = 2, t = 0.140000
n = 3, t = 0.210000
...
n = 497, t = 34.790001
n = 498, t = 34.860001
n = 499, t = 34.930000
n = 500, t = 35.000000
```

Simulation ended.

```
Time for spec. advance = 10.339094 s
Time for emf advance = 0.066140 s
Total simulation time = 10.431528 s
```

```
Particle advance [nsec/part] = 78.723580
Particle advance [Mpart/sec] = 12.702674
```

```
$ cat -n input/simulation_test.c
1  /**
2   * ZPIC - em2d
3   *
4   * Weibel instability
5   */
6
7  #include <stdlib.h>
8  #include "../simulation.h"
9
10 void sim_init( t_simulation* sim ){
11
12      // Time step
13      float dt = 0.07;
14      float tmax = 35.0;
15
16      // Simulation box
17      int nx[2] = { 128, 128 };
18      float box[2] = { 12.8, 12.8 };
19
20      // Diagnostic frequency
21      int ndump = 10;
22
23      // Initialize particles
24      const int n_species = 2;
25      t_species* species = (t_species *) malloc( n_species * sizeof( t_species ));
26
27      // Use 4x2 particles per cell
28      int ppc[] = {4,2};
29
30      // Initial fluid and thermal velocities
31      t_part_data ufl[] = { 0.0, 0.0, 0.6 };
32      t_part_data uth[] = { 0.1, 0.1, 0.1 };
33
34      spec_new( &species[0], "electrons", -1.0, ppc, ufl, uth, nx, box, dt, NULL );
35
36      ufl[2] = -ufl[2];
37      spec_new( &species[1], "positrons", +1.0, ppc, ufl, uth, nx, box, dt, NULL );
38
39      // Initialize Simulation data
40      sim_new( sim, nx, box, dt, tmax, ndump, species, n_species );
41
42  }
43
44 void sim_report( t_simulation* sim ){
45
46      // All magnetic field components
47      emf_report( &sim->emf, BFLD, 0 );
48      emf_report( &sim->emf, BFLD, 1 );
49      emf_report( &sim->emf, BFLD, 2 );
50
51  }
```

Experimental setup of ZPIC:

- Weibel
- Grid 128x128 cells
- 500 time-steps
- 8 particles per cell
- uniform distribution

Profiling: Find the hotspots of ZPIC/em2d

```
// Build and add profiling
// flag -pg to the ZPIC code
$ make CC=gcc CFLAGS="-Ofast -pg" clean zpic
```

```
// Run the ZPIC code
$ ./zpic
```

```
// Output gprof information
$ gprof zpic
```

Gprof flat profile

| % | cumulative | self | | self | total | |
|-------|------------|---------|-----------|---------|---------|------------------|
| time | seconds | seconds | calls | ms/call | ms/call | name |
| 55.80 | 7.96 | 7.96 | 1002 | 7.95 | 14.12 | spec_advance |
| 22.43 | 11.16 | 3.20 | 131334144 | 0.00 | 0.00 | interpolate_fld |
| 19.00 | 13.87 | 2.71 | 131334144 | 0.00 | 0.00 | dep_current_zamb |
| 1.89 | 14.14 | 0.27 | 62 | 4.36 | 4.36 | spec_sort |

Gprof call graph for function *spec_advance()*

| index | % time | self | children | called | name |
|-------|--------|------|----------|---------------------|-----------------------------|
| | | 7.96 | 6.18 | 1002/1002 | sim_iter [2] |
| [1] | 99.1 | 7.96 | 6.18 | 1002 | spec_advance [1] |
| | | 3.20 | 0.00 | 131334144/131334144 | interpolate_fld [3] |
| | | 2.71 | 0.00 | 131334144/131334144 | dep_current_zamb [4] |
| | | 0.27 | 0.00 | 62/62 | spec_sort [5] |
| | | 0.00 | 0.00 | 2004/3006 | timer_ticks [13] |
| | | 0.00 | 0.00 | 1002/1504 | timer_interval_seconds [15] |

Profiling: Find the hotspots of ZPIC/em2d (cont'd)

- The profiler *gprof* reports hotspots at the function-level
 - ie. functions are ranked by % time consumed.
- We need more information to select the target hotspots.
- We need to analyze the function/procedure calls and the loops altogether (at least).

particle.c:889:spec_advance() [55.80%]

-> contains 1+ loops with function calls

—————→ This loop in *spec_advance()* is a good parallelization opportunity (coarse-grain parallelism).

-> calls particle.c:840:interpolate_fld() [22.43%]

-> does not contain any loops

—————→ This hotspot *interpolate_fld()* does not contain loops, so it is not a (loop-level) parallelization opportunity.

-> calls particle.c:605:dep_current_zamb() [19.00%]

-> contains 1 loop without function calls

—————→ This loop in *dep_current_zamb()* is a good parallelization opportunity (fine-grain parallelism).

- The selected hotspot is loop at line 677 in function *spec_advance()* [up to 97.23% of the runtime]
 - Note it includes runtime of the other two hotspots as well.
 - Ignore *interpolate_fld()* because it does not contain any loop.
 - Try to parallelize *dep_current_zamb()*, but you will slow down ZPIC (65M calls at ~0 seconds/call).

Parallel ZPIC/em2d: from serial to CPU & GPU...



EM2D #7a (Basic GPU+OpenACC Atomic)

EM2D #6a (Basic GPU+OpenMP Atomic)

EM2D #5a (Basic CPU+OpenMP Atomic)

EM2D #4 (loop fission)

EM2D #3 (change Array of Structs by separate arrays)

EM2D #2 (inlining deb_current_zamb)

EM2D #1 (outlining, gather-scatter data)

EM2D #0 (serial version)

EM2D #0 (serial version)

- Start by running `pwreport --screening` to get an assessment of the hotspot function.
- Reported a total of 3 checks, but none of the related to parallelism (Vector, Multi and Offload).

```
$ cd em2d-0-serial/

$ pwreport --screening --include-tags all particles.c:spec_advance --brief -- -Ofast -lm
[C] target compiler: <none> (Compiler Agnostic Mode)

SCREENING REPORT

Target                Lines of code Optimizable lines Analysis time # checks Effort Cost Profiling
-----
particles.c:spec_advance 749          6              131 ms          3        9 h  294€ n/a
-----
Total                749          6              131 ms          3        9 h  294€ n/a

CHECKS PER STAGE OF THE PERFORMANCE OPTIMIZATION ROADMAP
Target                Scalar Control Memory Vector Multi Offload
-----
particles.c:spec_advance 1          0          2          0          0          0
-----
Total                1          0          2          0          0          0

TOTAL NUMBER OF LOOPS FOR CODEE AUTO AND GUIDED MODES
----- # checks -----
Codee mode # Loops Scalar Control Memory Vector Multi Offload
-----
Auto      0          0          0          0          0          0
Guided    1          0          1          0          0          0

1 file successfully analyzed and 0 failures in 131 ms
```

EM2D #0 (serial version)

- Let's run `pwreport --non-analyzable` to get a report of the challenges identified by Codee in the code.
- We need to remove the unsupported C programming language feature from the source code.
 - Usage of structs
 - Calls to functions/procedures

```
$ cd em2d-0-serial/

$ pwreport --non-analyzable particles.c:spec_advance -- -Ofast -lm
Compiler flags: -Ofast -lm

[C] target compiler: <none> (Compiler Agnostic Mode)

Count Type
-----
1  Unsupported usage of different fields of a struct type variable
1  Potential aliasing in call to a function
1  Unsupported usage of variable inside unstructured code

Count : Number of occurrences of the unsupported feature
Type : Type of unsupported feature

1 file successfully analyzed and 0 failures in 112 ms
```


Parallel ZPIC/em2d: from serial to CPU & GPU...

EM2D #7a (Basic GPU+OpenACC Atomic)

EM2D #6a (Basic GPU+OpenMP Atomic)

EM2D #5a (Basic CPU+OpenMP Atomic)

EM2D #4 (loop fission)

EM2D #3 (change Array of Structs by separate arrays)

EM2D #2 (inlining deb_current_zamb)

EM2D #1 (outlining, gather-scatter)

EM2D #0 (serial version)



EM2D #1 (outlining, gather-scatter)

- Addressing the issues reported by Codee with respect to pointers to structs and function/procedure calls requires significant changes in the source code of ZPIC. It might even require to rethink the data types used across the entire project.
- So **let's adopt an incremental approach that is less intrusive and less time-consuming.**
- We will do the following actions:
 - **First, use the outlining technique** to isolate the hotspot loop at *em2d/particles.c:spec_advance:677* into a separate function that receives all the input data as function parameters (i.e., no global variables are used in the function body).
 - **Second, use the gather-scatter technique** to copy input data and output data into temporary arrays with a contiguous data layout in memory. This copies input data dispersed across memory into consecutive arrays (*gather*), makes the hotspot loop at *em2d/particles.c:spec_advance:677* operate on those temporary consecutive arrays, and finally copies the results into the output data dispersed across memory (*scatter*).
- **Note that these techniques will introduce an overhead that increases the runtime of the sequential ZPIC code and that must be amortized by exploiting parallelism in the hotspot loop** at *em2d/particles.c:spec_advance:677*.

EM2D #1 (outlining, gather-scatter) (cont'd)

- In computing, **outlining** is a manual or compiler optimization that **replaces a code section by a function call site and creates a new function with the code section as function body**.
- Benefits of outlining for the programmer:
 - Improve the readability and the structure of the source code.
 - Enable code transformations that otherwise would not be applicable.
- In ZPIC we use it to isolate the hotspot loop into a separate function promoting data hiding (i.e., all input data and output data passed as explicit function parameters), and increase the code coverage of Codee tools.

Code example

The following code might be obscure for static code analysis tools due to the dynamic allocation of a pointer-based struct data type in the C programming language:

```
1 | #include <stdlib.h>
2 |
3 | typedef struct
4 | {
5 |     double *A;
6 |     double *B;
7 | } data;
8 |
9 | void foo()
10 | {
11 |     data *S = (data *)malloc(sizeof(data));
12 |     S->A = (double *)malloc(sizeof(double) * 1000);
13 |     S->B = (double *)malloc(sizeof(double) * 1000);
14 |
15 |     for (size_t i = 0; i < 1000; i++)
16 |     {
17 |         S->A[i] = 0;
18 |     }
19 |
20 |     free(S->B);
21 |     free(S->A);
22 |     free(S);
23 | }
```

By outlining the loop to a dedicated function (see *bar()* in the code below) the loop can be easily analyzed in isolation because the resulting code is free of uses of the pointer-based struct data type. The resulting code is as follows:

```
1 | #include <stdlib.h>
2 |
3 | typedef struct
4 | {
5 |     double *A;
6 |     double *B;
7 | } data;
8 |
9 | void bar(double *A)
10 | {
11 |     for (size_t i = 0; i < 1000; i++)
12 |     {
13 |         A[i] = 0;
14 |     }
15 | }
16 |
17 | void foo()
18 | {
19 |     data *S = (data *)malloc(sizeof(data));
20 |     S->A = (double *)malloc(sizeof(double) * 1000);
21 |     S->B = (double *)malloc(sizeof(double) * 1000);
22 |
23 |     bar(S->A);
24 |
25 |     free(S->B);
26 |     free(S->A);
27 |     free(S);
28 | }
```

EM2D #1 (outlining, gather-scatter) (cont'd)

- Let's **apply outlining to the hotpost loop** `em2d/particles.c:spec_advance:677` of function

```
void spec_advance( t_species* spec, t_emf* emf, t_current* current )
```

And create **a separate function named `spec_advance_outlining()`**.

```
void spec_advance_outlining(  
    // Spec data  
    const int spec_np, const t_part_data spec_q, const t_part_data qnx, const t_part_data qny, const t_part_data tem,  
    const t_part_data dt_dx, const t_part_data dt_dy, int *restrict spec_ix, int *restrict spec_iy, t_part_data *restrict spec_x,  
    t_part_data *restrict spec_y, t_part_data *restrict spec_ux, t_part_data *restrict spec_uy, t_part_data *restrict spec_uz,  
    // Emf data  
    const int emf_nrow, t_fld *restrict Ex, t_fld *restrict Ey, t_fld *restrict Ez, t_fld *restrict Bx, t_fld *restrict By,  
    t_fld *restrict Bz,  
    // Current data  
    const int current_nrow, t_fld *restrict current_Jx, t_fld *restrict current_Jy, t_fld *restrict current_Jz)
```

- This is time-consuming so we provide you the new source code to make better use of your time.**

EM2D #1 (outlining, gather-scatter) (cont'd)

- In computing, **gather-scatter** is a manual optimization that **changes memory addressing enabling to replace indexed read/write operations by consecutive memory accesses**.
- Benefits for the programmer:
 - It is often used in sparse linear algebra operations to gather indexed reads and scatter indexed writes.
 - It is also used to improve locality by enabling loops to benefit from consecutive memory accesses.
 - It is also important in SIMD/vector programming, as SIMD/vector CPUs often provide hardware support for gather-scatter operations.
- **In ZPIC we use it**
 - To **“pack” data spread across memory through pointer-to-structs into consecutive arrays**
 - And **increase the code coverage of Codee tools by promoting data hiding** (removing pointer-to-structs).

The code has a vector y holding n elements stored at memory locations given by *index*, so they are not guaranteed to be at consecutive memory locations. The **gather** copies all those array elements into a consecutive array x .

```
for(int i=0; i<n; ++i) {  
    x[i] = y[index[i]];  
}
```

The code now computes the results using array x . At the end, the **scatter** copies the consecutive array entries of x into the corresponding entries of y .

```
for(int i=0; i<n; i++) {  
    y[index[i]] = x[i];  
}
```

EM2D #1 (cont'd)

- Let's apply gather-scatter to the hotpost loop
em2d/particles.c:spec_advance:677
- The following pointers-to-struct are used in the source code:

```
t_species /* particles.h */  
t_emf /* emf.h */  
t_current /* current.h */
```

- In ZPIC there are multiple parameters of type pointer to Array-of-Structs (AoS) that must be “packed”:

```
t_part * t_species.part  
t_vfld * t_current.J_buf
```

```
1 /*  
2  * particles.h  
3  * zpic  
4  *  
5  * Created by Ricardo Fonseca on 11/8/10.  
6  * Copyright 2010 Centro de Física dos Plasmas. All rights reserved.  
7  *  
8  */  
52 typedef struct {  
53  
54     char name[MAX_SPNAME_LEN];  
55  
56     // Particle data buffer  
57     t_part *part;  
58     int np;  
59     int np_max;  
60  
61     // mass over charge ratio  
62     t_part_data m_q;  
63  
64     // total kinetic energy  
65     double energy;  
66  
67     // charge of individual particle  
68     t_part_data q;  
69  
70     // Number of particles per cell  
71     int ppc[2];  
72  
73     // Density profile to inject  
74     t_density density;  
75  
76     // Initial momentum of particles  
77     t_part_data ufl[3];  
78     t_part_data uth[3];  
79  
80     // Simulation box info  
81     int nx[2];  
82     t_part_data dx[2];  
83     t_part_data box[2];  
84  
85     // Time step  
86     float dt;  
87  
88     // Iteration number  
89     int iter;  
90  
91     // Moving window  
92     int moving_window;  
93     int n_move;  
94  
95 } t_species;
```

```
1 /*  
2  * current.h  
3  * zpic  
4  *  
5  * Created by Ricardo Fonseca on 12/8/10.  
6  * Copyright 2010 Centro de Física dos Plasmas. All rights reserved.  
7  *  
8  */  
9  
10 #ifndef __CURRENT__  
11 #define __CURRENT__  
12  
13 #include "zpic.h"  
14  
15 enum smooth_type { NONE, BINOMIAL, COMPENSATED };  
16  
17 typedef struct {  
18     enum smooth_type xtype, ytype;  
19     int xlevel, ylevel;  
20 } t_smooth;  
21  
22 typedef struct {  
23  
24     t_vfld *J;  
25  
26     t_vfld *J_buf;  
27  
28     // Grid parameters  
29     int nx[2];  
30     int nrow;  
31     int gc[2][2];  
32  
33     // Box size  
34     t_fld box[2];  
35  
36     // Cell size  
37     t_fld dx[2];  
38  
39     // Current smoothing  
40     t_smooth smooth;  
41  
42     // Time step  
43     float dt;  
44  
45     // Iteration number  
46     int iter;  
47  
48     // Moving window  
49     int moving_window;  
50  
51 } t_current;
```

EM2D #1 (cont'd)

- Let's take a look at how we have implemented the gather-scatter in ZPIC.
- First, we have defined a new struct ***t_all_data*** to hold all the “packed” data.
- It provides access to all the plain arrays that hold the consecutive data to be processed in the hotpost loop.

t_fld *Jx_buf
t_fld *Jy_buf
t_fld *Jz_buf
t_fld *Jx
t_fld *Jy
t_fld *Jz

...

- With *t_fld* being a float data type.

typedef float t_fld;

```
1  #ifndef __ONEMALLOC__
2  #define __ONEMALLOC__
3
4  #include "current.h"
5  #include "emf.h"
6  #include <stdint.h>
7
8  typedef struct {
9      int size;
10     int offset;
11
12     t_fld *Ex_buf;
13     t_fld *Ey_buf;
14     t_fld *Ez_buf;
15     t_fld *Bx_buf;
16     t_fld *By_buf;
17     t_fld *Bz_buf;
18
19     t_fld *Ex;
20     t_fld *Ey;
21     t_fld *Ez;
22     t_fld *Bx;
23     t_fld *By;
24     t_fld *Bz;
25 } t_emf_data;
26
27 typedef struct {
28     int size;
29     int offset;
30
31     t_fld *Jx_buf;
32     t_fld *Jy_buf;
33     t_fld *Jz_buf;
34
35     t_fld *Jx;
36     t_fld *Jy;
37     t_fld *Jz;
38 } t_current_data;
39
40 typedef struct {
41     t_current_data current_data;
42     t_emf_data emf_data;
43 } t_all_data;
44
45 void init_all_data(t_all_data *data, t_current *current, t_emf *emf);
46 void delete_all_data(t_all_data *data);
47
48 void copy_in_all_data(t_all_data *data, t_current *current, t_emf *emf);
49 void copy_out_all_data(t_all_data *data, t_current *current, t_emf *emf);
50
51 #endif // __ONEMALLOC__
```

EM2D #1 (outlining, gather-scatter) (cont'd)

Allocate (malloc) memory

```
5 void init_all_data(t_all_data *data, t_current *current, t_emf *emf) {
6
7     // t_current buffers
8     data->current_data.size = current->size;
9     data->current_data.offset = current->offset;
10
11     data->current_data.Jx_buf = malloc(current->size * sizeof(t_fld));
12     data->current_data.Jy_buf = malloc(current->size * sizeof(t_fld));
13     data->current_data.Jz_buf = malloc(current->size * sizeof(t_fld));
14
15     assert(data->current_data.Jx_buf);
16     assert(data->current_data.Jy_buf);
17     assert(data->current_data.Jz_buf);
18
19     // Move pointers to [0][0]
20     data->current_data.Jx = data->current_data.Jx_buf + data->current_data.offset;
21     data->current_data.Jy = data->current_data.Jy_buf + data->current_data.offset;
22     data->current_data.Jz = data->current_data.Jz_buf + data->current_data.offset;
23
24     // t_emf buffers
25     data->emf_data.size = emf->size;
26     data->emf_data.offset = emf->offset;
27
28     data->emf_data.Ex_buf = malloc(emf->size * sizeof(t_fld));
29     data->emf_data.Ey_buf = malloc(emf->size * sizeof(t_fld));
30     data->emf_data.Ez_buf = malloc(emf->size * sizeof(t_fld));
31     data->emf_data.Bx_buf = malloc(emf->size * sizeof(t_fld));
32     data->emf_data.By_buf = malloc(emf->size * sizeof(t_fld));
33     data->emf_data.Bz_buf = malloc(emf->size * sizeof(t_fld));
34
35     assert(data->emf_data.Ex_buf);
36     assert(data->emf_data.Ey_buf);
37     assert(data->emf_data.Ez_buf);
38     assert(data->emf_data.Bx_buf);
39     assert(data->emf_data.By_buf);
40     assert(data->emf_data.Bz_buf);
41
42     // Move pointers to [0][0]
43     data->emf_data.Ex = data->emf_data.Ex_buf + data->emf_data.offset;
44     data->emf_data.Ey = data->emf_data.Ey_buf + data->emf_data.offset;
45     data->emf_data.Ez = data->emf_data.Ez_buf + data->emf_data.offset;
46
47     data->emf_data.Bx = data->emf_data.Bx_buf + data->emf_data.offset;
48     data->emf_data.By = data->emf_data.By_buf + data->emf_data.offset;
49     data->emf_data.Bz = data->emf_data.Bz_buf + data->emf_data.offset;
50 }
```

Copy data to/from 1D arrays

```
76 void copy_in_all_data(t_all_data *data, t_current *current, t_emf *emf) {
77
78     for (int i = 0; i < data->emf_data.size; ++i) {
79         data->emf_data.Ex_buf[i] = emf->E_buf[i].x;
80         data->emf_data.Ey_buf[i] = emf->E_buf[i].y;
81         data->emf_data.Ez_buf[i] = emf->E_buf[i].z;
82
83         data->emf_data.Bx_buf[i] = emf->B_buf[i].x;
84         data->emf_data.By_buf[i] = emf->B_buf[i].y;
85         data->emf_data.Bz_buf[i] = emf->B_buf[i].z;
86     }
87
88     for (int i = 0; i < data->current_data.size; ++i) {
89         data->current_data.Jx_buf[i] = current->J_buf[i].x;
90         data->current_data.Jy_buf[i] = current->J_buf[i].y;
91         data->current_data.Jz_buf[i] = current->J_buf[i].z;
92     }
93 }
94
95 void copy_out_all_data(t_all_data *data, t_current *current, t_emf *emf) {
96
97     for (int i = 0; i < data->emf_data.size; ++i) {
98         emf->E_buf[i].x = data->emf_data.Ex_buf[i];
99         emf->E_buf[i].y = data->emf_data.Ey_buf[i];
100        emf->E_buf[i].z = data->emf_data.Ez_buf[i];
101
102        emf->B_buf[i].x = data->emf_data.Bx_buf[i];
103        emf->B_buf[i].y = data->emf_data.By_buf[i];
104        emf->B_buf[i].z = data->emf_data.Bz_buf[i];
105    }
106
107    for (int i = 0; i < data->current_data.size; ++i) {
108        current->J_buf[i].x = data->current_data.Jx_buf[i];
109        current->J_buf[i].y = data->current_data.Jy_buf[i];
110        current->J_buf[i].z = data->current_data.Jz_buf[i];
111    }
112 }
```

Deallocate (free) memory

```
52 void delete_all_data(t_all_data *data) {
53     free(data->current_data.Jx_buf);
54     free(data->current_data.Jy_buf);
55     free(data->current_data.Jz_buf);
56
57     data->current_data.Jx_buf = NULL;
58     data->current_data.Jy_buf = NULL;
59     data->current_data.Jz_buf = NULL;
60
61     free(data->emf_data.Ex_buf);
62     free(data->emf_data.Ey_buf);
63     free(data->emf_data.Ez_buf);
64     free(data->emf_data.Bx_buf);
65     free(data->emf_data.By_buf);
66     free(data->emf_data.Bz_buf);
67
68     data->emf_data.Ex_buf = NULL;
69     data->emf_data.Ey_buf = NULL;
70     data->emf_data.Ez_buf = NULL;
71     data->emf_data.Bx_buf = NULL;
72     data->emf_data.By_buf = NULL;
73     data->emf_data.Bz_buf = NULL;
74 }
```


EM2D #1 (outlining, gather-scatter) (cont'd)

- The ZPIC code also adapts the size of the data structures to the number of particles interacting at each simulation step. This leads to additional computations to keep data consistent in ZPIC.

```
783 void pack_spec(const int size, const t_part *part, int **ix, int **iy,
784               t_part_data **x, t_part_data **y, t_part_data **ux,
785               t_part_data **uy, t_part_data **uz) {
786
787     *ix = malloc(size * sizeof(int));
788     *iy = malloc(size * sizeof(int));
789
790     *x = malloc(size * sizeof(t_part_data));
791     *y = malloc(size * sizeof(t_part_data));
792     *ux = malloc(size * sizeof(t_part_data));
793     *uy = malloc(size * sizeof(t_part_data));
794     *uz = malloc(size * sizeof(t_part_data));
795
796     assert(*ix);
797     assert(*iy);
798     assert(*x);
799     assert(*y);
800     assert(*ux);
801     assert(*uy);
802     assert(*uz);
803
804     for (int i = 0; i < size; ++i) {
805         (*ix)[i] = part[i].ix;
806         (*iy)[i] = part[i].iy;
807
808         (*x)[i] = part[i].x;
809         (*y)[i] = part[i].y;
810         (*ux)[i] = part[i].ux;
811         (*uy)[i] = part[i].uy;
812         (*uz)[i] = part[i].uz;
813     }
814 }
```

```
816 void unpack_spec(const int size, t_part *part, int **ix, int **iy,
817                 t_part_data **x, t_part_data **y, t_part_data **ux,
818                 t_part_data **uy, t_part_data **uz) {
819
820     for (int i = 0; i < size; ++i) {
821         part[i].ix = (*ix)[i];
822         part[i].iy = (*iy)[i];
823
824         part[i].x = (*x)[i];
825         part[i].y = (*y)[i];
826         part[i].ux = (*ux)[i];
827         part[i].uy = (*uy)[i];
828         part[i].uz = (*uz)[i];
829     }
830
831     free(*ix);
832     free(*iy);
833     free(*x);
834     free(*y);
835     free(*ux);
836     free(*uy);
837     free(*uz);
838
839     *ix = *iy = NULL;
840     *x = *y = *ux = *uy = *uz = NULL;
841 }
```

EM2D #1 (cont'd)

- How do we glue all these pieces of code?
- The original function *spec_advance()* has the same interface with the rest of the code.
- Reallocation of memory is needed before running the hotspot loop.
- Also needed to gather the relevant data into consecutive arrays.
- Next step is to compute the hotspot loop by invoking the outlined function.
- Once the output of the simulation step is ready, it is scattered to the corresponding memory locations.
- And finally the memory re-allocation is done after running the hotspot loop.

```
844 void spec_advance(t_species *spec, t_emf *emf, t_current *current,  
845                  t_all_data *data) {  
846     int i;  
847     t_part_data qnx, qny, qvz;  
848  
849     uint64_t t0;  
850     t0 = timer_ticks();  
851  
852     const t_part_data tem = 0.5 * spec->dt / spec->m_q;  
853     const t_part_data dt_dx = spec->dt / spec->dx[0];  
854     const t_part_data dt_dy = spec->dt / spec->dx[1];  
855  
856     // Auxiliary values for current deposition  
857     qnx = spec->q * spec->dx[0] / spec->dt;  
858     qny = spec->q * spec->dx[1] / spec->dt;  
859  
860     const int nx0 = spec->nx[0];  
861     const int nx1 = spec->nx[1];  
862  
863     ///////////  
864     // Pack spec->part //  
865     ///////////  
866     int *spec_ix, *spec_iy;  
867     t_part_data *spec_x, *spec_y, *spec_ux, *spec_uy, *spec_uz;  
868  
869     pack_spec(spec->np_max, spec->part, &spec_ix, &spec_iy, &spec_x, &spec_y,  
870              &spec_ux, &spec_uy, &spec_uz);  
871  
872     copy_in_all_data(data, current, emf);  
873  
874     spec_advance_outlining( // spec data  
875                            spec->part, spec->np, spec->q, qnx, qny, tem, dt_dx, dt_dy, spec_ix,  
876                            spec_iy, spec_x, spec_y, spec_ux, spec_uy, spec_uz,  
877                            // emf data  
878                            emf->nrow, data->emf_data.Ex, data->emf_data.Ey, data->emf_data.Ez,  
879                            data->emf_data.Bx, data->emf_data.By, data->emf_data.Bz,  
880                            // current data  
881                            current, data->current_data.Jx, data->current_data.Jy,  
882                            data->current_data.Jz);  
883  
884     copy_out_all_data(data, current, emf);  
885  
886     ///////////  
887     // Unpack spec //  
888     ///////////  
889     unpack_spec(spec->np_max, spec->part, &spec_ix, &spec_iy, &spec_x, &spec_y,  
890                &spec_ux, &spec_uy, &spec_uz);  
891  
892     // Advance internal iteration number  
893     spec->iter += 1;  
894     _spec_npush += spec->np;
```

EM2D #1 (outlining, gather-scatter) (cont'd)

- Let's see changes in Codee Screening Report by narrowing it down to the outlined function.
- Reported 0 checks, so nothing helps to exploit parallelism (Vector, Multi and Offload).

```
$ cd em2d-1-outlining/

$ pwreport --screening --include-tags all particles.c:spec_advance_outlining --brief -- -Ofast -lm
Compiler flags: -Ofast -lm

[C] target compiler: <none> (Compiler Agnostic Mode)

SCREENING REPORT

Target                Lines of code Optimizable lines Analysis time # checks Effort Cost Profiling
-----
particles.c:spec_advance_outlining 837          0          128 ms          0          0 h          0€ n/a
-----
Total                837          0          128 ms          0          0 h          0€ n/a

CHECKS PER STAGE OF THE PERFORMANCE OPTIMIZATION ROADMAP
Target                Scalar Control Memory Vector Multi Offload
-----
particles.c:spec_advance_outlining 0          0          0          0          0          0
-----
Total                0          0          0          0          0          0

TOTAL NUMBER OF LOOPS FOR CODEE AUTO AND GUIDED MODES
----- # checks -----
Codee mode # Loops Scalar Control Memory Vector Multi Offload
-----
Auto      0          0          0          0          0          0
Guided    0          0          0          0          0          0

1 file successfully analyzed and 0 failures in 129 ms
```

EM2D #1 (outlining, gather-scatter data) (cont'd)

- Let's investigate the remaining challenges in the outlined function through `pwreport --non-analyzable`.
- Codee output message “*Unsupported interprocedural dependency analysis for a function*” pinpoints the call to the function “`dep_current_zamp()`” as the next issue to overcome.

```
$ pwreport --non-analyzable particles.c:spec_advance_outlining
[C] target compiler: <none> (Compiler Agnostic Mode)

Count Type
-----
1 Unsupported interprocedural dependency analysis for a function

Count : Number of occurrences of the unsupported feature
Type : Type of unsupported feature

1 file successfully analyzed and 0 failures in 96 ms
```

Parallel ZPIC/em2d: from serial to CPU & GPU...



EM2D #1 (outlining, gather-scatter data)



EM2D #0 (serial version)

EM2D #7a (Basic GPU+OpenACC Atomic)

EM2D #6a (Basic GPU+OpenMP Atomic)

EM2D #5a (Basic CPU+OpenMP Atomic)

EM2D #4 (loop fission)

EM2D #3 (change Array of Structs by separate arrays)

EM2D #2 (inlining deb_current_zamb)

EM2D #2 (Inlining deb_current_zamb)

- In computing, **inline expansion**, or **inlining**, is a manual or compiler optimization that **replaces a function call site with the body of the called function**.
- Benefits for the programmer:
 - Eliminates overhead from calls to functions/procedures.
 - Enable code transformations that otherwise would not be applicable.
- In ZPIC we use inlining to enable the detection of the pattern “sparse reduction” by Codee (it is work-in-progress to do detection across procedure calls).

The code has a function that is called in other code sections:

```
void foo(int *x, int i) {  
    x[i] = 0;  
}
```

Before inlining (e.g., assume *foo* is called within a loop):

```
for(int i=0; i<n; ++i) {  
    foo(x, i);  
}
```

After inlining:

```
for(int i=0; i<n; ++i) {  
    x[i] = 0;  
}
```

EM2D #2 (inlining deb_current_zamb)

Before inlining

```
// Store new momenta
spec_ux[i] = ux;
spec_uy[i] = uy;
spec_uz[i] = uz;

// push particle
rg = 1.0f / sqrtf(1.0f + ux * ux + uy * uy + uz * uz);

dx = dt_dx * rg * ux;
dy = dt_dy * rg * uy;

x1 = spec_x[i] + dx;
y1 = spec_y[i] + dy;

di = ltrim(x1);
dj = ltrim(y1);

x1 -= di;
y1 -= dj;

qvz = spec_q * uz * rg;

dep_current_zamb(spec_ix[i], spec_iy[i], di, dj, spec_x[i], spec_y[i], dx,
dy, qnx, qny, qvz, current_nrow, current_Jx, current_Jy,
current_Jz);

// Store results
spec_x[i] = x1;
spec_y[i] = y1;
spec_ix[i] += di;
spec_iy[i] += dj;
}
// clang-format off

void pack_spec(const int size, const t_part *part, int **ix, int **iy,
t_part_data **x, t_part_data **y, t_part_data **ux,
t_part_data **uy, t_part_data **uz) {

*ix = malloc(size * sizeof(int));
*iy = malloc(size * sizeof(int));

*x = malloc(size * sizeof(t_part_data));
*y = malloc(size * sizeof(t_part_data));
*ux = malloc(size * sizeof(t_part_data));
*uy = malloc(size * sizeof(t_part_data));
*uz = malloc(size * sizeof(t_part_data));
}
```

After inlining

```
// dep_current_zamb(spec_ix[i], spec_iy[i], di, dj, spec_x[i], spec_y[i],
// dx, dy, qnx, qny, qvz, current_nrow, current_Jx,
// current_Jy, current_Jz);

////////////////////////////////////
// dep_current_zamb inlined START //
////////////////////////////////////

const float ix = spec_ix[i];
const float iy = spec_iy[i];
const float x0 = spec_x[i];

...

wp1[0] = 0.5f * (S0y[0] + S1y[0]);
wp1[1] = 0.5f * (S0y[1] + S1y[1]);

wp2[0] = 0.5f * (S0x[0] + S1x[0]);
wp2[1] = 0.5f * (S0x[1] + S1x[1]);

current_Jx[vp[k].ix + nrow * vp[k].iy] += w1 * wp1[0];
current_Jx[vp[k].ix + nrow * (vp[k].iy + 1)] += w1 * wp1[1];

current_Jy[vp[k].ix + nrow * vp[k].iy] += w2 * wp2[0];
current_Jy[vp[k].ix + 1 + nrow * vp[k].iy] += w2 * wp2[1];

current_Jz[vp[k].ix + nrow * vp[k].iy] +=
vp[k].qvz * (S0x[0] * S0y[0] + S1x[0] * S1y[0] +
(S0x[0] * S1y[0] - S1x[0] * S0y[0]) / 2.0f);
current_Jz[vp[k].ix + 1 + nrow * vp[k].iy] +=
vp[k].qvz * (S0x[1] * S0y[0] + S1x[1] * S1y[0] +
(S0x[1] * S1y[0] - S1x[1] * S0y[0]) / 2.0f);
current_Jz[vp[k].ix + nrow * (vp[k].iy + 1)] +=
vp[k].qvz * (S0x[0] * S0y[1] + S1x[0] * S1y[1] +
(S0x[0] * S1y[1] - S1x[0] * S0y[1]) / 2.0f);
current_Jz[vp[k].ix + 1 + nrow * (vp[k].iy + 1)] +=
vp[k].qvz * (S0x[1] * S0y[1] + S1x[1] * S1y[1] +
(S0x[1] * S1y[1] - S1x[1] * S0y[1]) / 2.0f);
}

////////////////////////////////////
// dep_current_zamb inlined END //
////////////////////////////////////
```

The inlining exposes the computation of J_x , J_y and J_z in the target hotspot loop. As a result, the sparse reduction pattern in the code.

EM2D #2 (inlining deb_current_zamb) (cont'd)

- After applying inlining, Codee reports a total of 135 checks in the hotspot function.
- It also reports 2 loops in the function, but 0 opportunities related to parallelism (Multi, Offload).

```
$ cd em2d-2-inlining/
$ pwreport --screening --include-tags all particles.c:spec_advance_outlining --brief -- -Ofast -lm
Compiler flags: -Ofast -lm
[C] target compiler: <none> (Compiler Agnostic Mode)

SCREENING REPORT

Target                Lines of code Optimizable lines Analysis time # checks Effort Cost    Profiling
-----
particles.c:spec_advance_outlining 936      172      183 ms      135      513 h  16787€  n/a
-----
Total                936      172      183 ms      135      513 h  16787€  n/a

CHECKS PER STAGE OF THE PERFORMANCE OPTIMIZATION ROADMAP
Target                Scalar Control Memory Vector Multi Offload
-----
particles.c:spec_advance_outlining 11       1       121      2       0       0
-----
Total                11       1       121      2       0       0

TOTAL NUMBER OF LOOPS FOR CODEE AUTO AND GUIDED MODES
----- # checks -----
Codee mode # Loops Scalar Control Memory Vector Multi Offload
-----
Auto      0      0      0      0      0      0      0
Guided    2      5      1     121      2      0      0

1 file successfully analyzed and 0 failures in 183 ms
```


EM2D #2 (inlining deb_current_zamb) (cont'd)

- Let's see **the detailed list of checkers reported by Codee**, and we can identify the next recommendations:
 - Avoid the usage of Array of Structs (AoS) [PWR016]
 - Avoid the usage of non-consecutive and indirect memory accesses [PWR010, PWR035, PWR036]
- These **recommendations are reported for the loops at lines 690 and 891.**

```
$ pwreport --checks --include-tags all particles.c:spec_advance_outlining --brief -- -Ofast -lm
Compiler flags: -Ofast -lm

[C] target compiler: <none> (Compiler Agnostic Mode)

CHECKS REPORT

particles.c:823:22 [PWR048]: Replace multiplication/addition combo with an explicit call to fused multiply-add
...
particles.c:795:5 [PWR016]: using separated plain arrays instead of Array-of-Structs (AoS) 'vp' is recommended to maximize data locality
...
particles.c:687:15 [PWR002]: 'qyz' not declared in the innermost scope possible
particles.c:690:3 [PWR010]: 'vp' multi-dimensional array not accessed in row-major order
particles.c:690:3 [PWR021]: extract temporary computations to a vectorizable loop
particles.c:690:3 [PWR035]: avoid non-consecutive array access for variable 'vp' to improve performance
particles.c:690:3 [PWR036]: avoid indirect array access for variables 'current_Jz', 'current_Jy' and 'current_Jx' to improve performance
particles.c:804:17 [PWR045]: replace division with a multiplication with a reciprocal
particles.c:896:23 [PWR016]: using separated plain arrays instead of Array-of-Structs (AoS) 'vp' is recommended to maximize data locality
...
particles.c:891:5 [PWR010]: 'vp' multi-dimensional array not accessed in row-major order
particles.c:891:5 [PWR021]: extract temporary computations to a vectorizable loop
particles.c:891:5 [PWR035]: avoid non-consecutive array access for variable 'vp' to improve performance
particles.c:891:5 [PWR036]: avoid indirect array access for variables 'current_Jz', 'current_Jy' and 'current_Jx' to improve performance
particles.c:925:24 [PWR045]: replace division with a multiplication with a reciprocal
...

1 file successfully analyzed and 0 failures in 209 ms
```

Parallel ZPIC/em2d: from serial to CPU & GPU...



EM2D #7a (Basic GPU+OpenACC Atomic)

EM2D #6a (Basic GPU+OpenMP Atomic)

EM2D #5a (Basic CPU+OpenMP Atomic)

EM2D #4 (loop fission)

EM2D #3 (change Array of Structs by separate arrays)

EM2D #2 (inlining deb_current_zamb)

EM2D #1 (outlining, gather-scatter data)

EM2D #0 (serial version)

EM2D #3 (change Array of Structs by separate arrays)

- In computing, **Array of Structures (AoS)**, **Structure of Arrays (SoA)** and **Array of Structures of Arrays (AoSoA)** refer to contrasting ways to arrange a sequence of records in memory, with regard to interleaving, and are of interest in SIMD programming, for example.
- In ZPIC we use it to enable the detection of the pattern “sparse reduction”, which cannot be detected because the loop body contains uses of AoS (that we must first replace by separate arrays).

Code example

The following example shows a loop processing the x and y coordinates for an array of points:

```
1 | typedef struct {  
2 |     int x;  
3 |     int y;  
4 |     int z;  
5 | } point;  
6 |  
7 | void foo() {  
8 |     point points[1000];  
9 |     for (int i = 0; i < 1000; i++) {  
10 |         points[i].x = 1;  
11 |         points[i].y = 1;  
12 |     }  
13 | }
```

This could seem like an example where using an Array-of-Structs is justifiable. However, since the z coordinate is never accessed along the other two, there may be cache misses that could be avoided by creating one array for each coordinate:

```
1 | void foo() {  
2 |     int points_x[1000];  
3 |     int points_y[1000];  
4 |     int points_z[1000];  
5 |     for (int i = 0; i < 1000; i++) {  
6 |         points_x[i] = 1;  
7 |         points_y[i] = 1;  
8 |     }  
9 | }
```

[Source: PWR016: Use separate arrays instead of an Array-of-Structs (<https://www.codeee.com/knowledge/pwr016/>)]

EM2D #3 (change Array of Structs by separate arrays)

Before AoS into separate arrays

```
for (k = 0; k < vnp; k++) {  
    float S0x[2], S1x[2], S0y[2], S1y[2];  
    float w1, w2;  
    float wp1[2], wp2[2];
```

```
    S0x[0] = 1.0f - vp[k].x0;  
    S0x[1] = vp[k].x0;
```

```
    S1x[0] = 1.0f - vp[k].x1;  
    S1x[1] = vp[k].x1;
```

```
    S0y[0] = 1.0f - vp[k].y0;  
    S0y[1] = vp[k].y0;
```

```
    S1y[0] = 1.0f - vp[k].y1;  
    S1y[1] = vp[k].y1;
```

```
    w1 = qnx * vp[k].dx;  
    w2 = qny * vp[k].dy;
```

```
    wp1[0] = 0.5f * (S0y[0] + S1y[0]);  
    wp1[1] = 0.5f * (S0y[1] + S1y[1]);
```

```
    wp2[0] = 0.5f * (S0x[0] + S1x[0]);  
    wp2[1] = 0.5f * (S0x[1] + S1x[1]);
```

```
    current_Jx[vp[k].ix + nrow * vp[k].iy] += w1 * wp1[0];  
    current_Jx[vp[k].ix + nrow * (vp[k].iy + 1)] += w1 * wp1[1];
```

```
    current_Jy[vp[k].ix + nrow * vp[k].iy] += w2 * wp2[0];  
    current_Jy[vp[k].ix + 1 + nrow * vp[k].iy] += w2 * wp2[1];
```

```
    current_Jz[vp[k].ix + nrow * vp[k].iy] +=  
        vp[k].qvz * (S0x[0] * S0y[0] + S1x[0] * S1y[0] +  
                    (S0x[0] * S1y[0] - S1x[0] * S0y[0]) / 2.0f);
```

```
    current_Jz[vp[k].ix + 1 + nrow * vp[k].iy] +=  
        vp[k].qvz * (S0x[1] * S0y[0] + S1x[1] * S1y[0] +  
                    (S0x[1] * S1y[0] - S1x[1] * S0y[0]) / 2.0f);
```

```
    current_Jz[vp[k].ix + nrow * (vp[k].iy + 1)] +=  
        vp[k].qvz * (S0x[0] * S0y[1] + S1x[0] * S1y[1] +  
                    (S0x[0] * S1y[1] - S1x[0] * S0y[1]) / 2.0f);
```

```
    current_Jz[vp[k].ix + 1 + nrow * (vp[k].iy + 1)] +=  
        vp[k].qvz * (S0x[1] * S0y[1] + S1x[1] * S1y[1] +  
                    (S0x[1] * S1y[1] - S1x[1] * S0y[1]) / 2.0f);
```

```
}
```

After AoS into separate arrays

```
float S0x[2], S1x[2], S0y[2], S1y[2];  
float w1, w2;  
float wp1[2], wp2[2];
```

```
S0x[0] = 1.0f - vp_x0[k];  
S0x[1] = vp_x0[k];
```

```
S1x[0] = 1.0f - vp_x1[k];  
S1x[1] = vp_x1[k];
```

```
S0y[0] = 1.0f - vp_y0[k];  
S0y[1] = vp_y0[k];
```

```
S1y[0] = 1.0f - vp_y1[k];  
S1y[1] = vp_y1[k];
```

```
w1 = qnx * vp_dx[k];  
w2 = qny * vp_dy[k];
```

```
wp1[0] = 0.5f * (S0y[0] + S1y[0]);  
wp1[1] = 0.5f * (S0y[1] + S1y[1]);
```

```
wp2[0] = 0.5f * (S0x[0] + S1x[0]);  
wp2[1] = 0.5f * (S0x[1] + S1x[1]);
```

```
current_Jx[vp_ix[k] + nrow * vp_iy[k]] += w1 * wp1[0];  
current_Jx[vp_ix[k] + nrow * (vp_iy[k] + 1)] += w1 * wp1[1];
```

```
current_Jy[vp_ix[k] + nrow * vp_iy[k]] += w2 * wp2[0];  
current_Jy[vp_ix[k] + 1 + nrow * vp_iy[k]] += w2 * wp2[1];
```

```
current_Jz[vp_ix[k] + nrow * vp_iy[k]] +=  
    vp_qvz[k] * (S0x[0] * S0y[0] + S1x[0] * S1y[0] +  
                (S0x[0] * S1y[0] - S1x[0] * S0y[0]) / 2.0f);
```

```
current_Jz[vp_ix[k] + 1 + nrow * vp_iy[k]] +=  
    vp_qvz[k] * (S0x[1] * S0y[0] + S1x[1] * S1y[0] +  
                (S0x[1] * S1y[0] - S1x[1] * S0y[0]) / 2.0f);
```

```
current_Jz[vp_ix[k] + nrow * (vp_iy[k] + 1)] +=  
    vp_qvz[k] * (S0x[0] * S0y[1] + S1x[0] * S1y[1] +  
                (S0x[0] * S1y[1] - S1x[0] * S0y[1]) / 2.0f);
```

```
current_Jz[vp_ix[k] + 1 + nrow * (vp_iy[k] + 1)] +=  
    vp_qvz[k] * (S0x[1] * S0y[1] + S1x[1] * S1y[1] +  
                (S0x[1] * S1y[1] - S1x[1] * S0y[1]) / 2.0f);
```

```
}
```

```
////////////////////////////////////  
// den current zamb inlined FMD //
```

Applying convert AoS into separate arrays enables to detect the sparse reduction pattern associated with Jx, Jy and Jz in the target hotspot loop.

Example: Replace 'vp[k].x0' by 'vp_x0[k]'.

EM2D #3 (change Array of Structs by separate arrays) (cont'd)

- Now that the AOS issues have been overcome, Codee still reports the non-consecutive memory access issues [PWR036] in both loops at lines 690 and 887.

```
$ cd em2d-3-aos/

$ pwreport --checks particles.c:spec_advance_outlining --brief -- -Ofast -lm
[C] target compiler: <none> (Compiler Agnostic Mode)

CHECKS REPORT

particles.c:819:22 [PWR048]: Replace multiplication/addition combo with an explicit call to fused multiply-add
particles.c:856:22 [PWR048]: Replace multiplication/addition combo with an explicit call to fused multiply-add
particles.c:920:24 [PWR048]: Replace multiplication/addition combo with an explicit call to fused multiply-add
particles.c:923:24 [PWR048]: Replace multiplication/addition combo with an explicit call to fused multiply-add
particles.c:926:24 [PWR048]: Replace multiplication/addition combo with an explicit call to fused multiply-add
particles.c:929:24 [PWR048]: Replace multiplication/addition combo with an explicit call to fused multiply-add
particles.c:690:3 [PWR021]: extract temporary computations to a vectorizable loop
particles.c:690:3 [PWR036]: avoid indirect array access for variables 'current_Jz', 'current_Jy' and 'current_Jx' to improve performance
particles.c:800:17 [PWR045]: replace division with a multiplication with a reciprocal
particles.c:887:5 [PWR021]: extract temporary computations to a vectorizable loop
particles.c:887:5 [PWR036]: avoid indirect array access for variables 'current_Jz', 'current_Jy' and 'current_Jx' to improve performance
particles.c:921:24 [PWR045]: replace division with a multiplication with a reciprocal
particles.c:924:24 [PWR045]: replace division with a multiplication with a reciprocal
particles.c:927:24 [PWR045]: replace division with a multiplication with a reciprocal
particles.c:930:24 [PWR045]: replace division with a multiplication with a reciprocal

1 file successfully analyzed and 0 failures in 184 ms
```

Parallel ZPIC/em2d: from serial to CPU & GPU...



EM2D #7a (Basic GPU+OpenACC Atomic)

EM2D #6a (Basic GPU+OpenMP Atomic)

EM2D #5a (Basic CPU+OpenMP Atomic)

EM2D #4 (loop fission)



EM2D #3 (change Array of Structs by separate arrays)



EM2D #2 (inlining deb_current_zamb)



EM2D #1 (outlining, gather-scatter data)



EM2D #0 (serial version)

EM2D #4 (loop fission)

- In computer science, **loop fission** (or loop distribution) is a compiler optimization in which **a loop is broken into multiple loops over the same index range with each taking only a part of the original loop's body.**
- Benefits:
 - Break down a large loop body into smaller ones to achieve better utilization of locality of reference.
 - In multi-core processors that can split a task into multiple tasks for each processor.
- In ZPIC we use it to enable the detection of the pattern “sparse reduction”, by separating the part of the loop body that cannot be matched to a pattern by Codee tools.

Before loop fission the code has a loop that computes several output variables:

```
for(int i=0; i<n; ++i) {  
    x[i] = 0;  
    y[i] = y[i-1] + 1;  
}
```

After loop fission: the code contains several loops dedicated to the computation of different outputs:

```
for(int i=0; i<n; ++i) {  
    x[i] = 0;  
}  
for(int i=0; i<n; ++i) {  
    y[i] = y[i-1] + 1;  
}
```

EM2D #4 (loop fission) (cont'd)

- Let's use *pwloops* to figure out which variables lead to *n/a*, to split the loop body accordingly.
- So we need to split the loop body so that the computation of following variables is in a separate loop:

spec_ux

spec_uy

spec_uz

spec_x

spec_y

spec_ix

spec_iy

```
$ cd em2d-3-aos/

$ pwloops --datascoping particles.c:690 --single-loop --brief -- -Ofast -lm
Compiler flags: -Ofast -lm

[C] target compiler: <none> (Compiler Agnostic Mode)

Loop      Variable      Kind      Read/Write Temporary Compute Pattern Memory Pattern OpenMP (multi)      OpenACC (offload)
-----
particles.c
  ~ spec_advance_outlining:690:3
    |->      Bpx          scalar  rw          x
    |->      Bpy          scalar  rw          x
    |->      Bpz          scalar  rw          x
    |->      Bx           pointer ro          shared(Bx)      copyin(Bx)
    |->      By           pointer ro          shared(By)      copyin(By)
    |->      Bz           pointer ro          shared(Bz)      copyin(Bz)
    ...
    |->      qnx          scalar  ro          shared(qnx)      copyin(qnx)
    |->      qny          scalar  ro          shared(qny)      copyin(qny)
    |->      qvz          scalar  rw          x          private(qvz)
    |->      ng           scalar  rw          x
    |->      spec_ix[]     pointer n/a      n/a      n/a      linear      n/a
    |->      spec_iy[]     pointer n/a      n/a      n/a      linear      n/a
    |->      spec_np       scalar  ro          shared(spec_np)  copyin(spec_np)
    |->      spec_q       scalar  ro          shared(spec_q)  copyin(spec_q)
    |->      spec_ux[]     pointer n/a      n/a      n/a      linear      n/a
    |->      spec_uy[]     pointer n/a      n/a      n/a      linear      n/a
    |->      spec_uz[]     pointer n/a      n/a      n/a      linear      n/a
    |->      spec_x[]      pointer n/a      n/a      n/a      linear      n/a
    |->      spec_y[]      pointer n/a      n/a      n/a      linear      n/a
    ...

1 file successfully analyzed and 0 failures in 1309 ms
```


EM2D #4 (loop fission) (cont'd)

Before loop fission

```
ux = utx + uty * Bpz - utz * Bpy;
uy = uty + utz * Bpx - utx * Bpz;
uz = utz + utx * Bpy - uty * Bpx;

// Perform second half of the rotation

Bpx *= otsq;
Bpy *= otsq;
Bpz *= otsq;

utx += uy * Bpz - uz * Bpy;
uty += uz * Bpx - ux * Bpz;
utz += ux * Bpy - uy * Bpx;

// Perform second half of electric field acceleration
ux = utx + Epx;
uy = uty + Epy;
uz = utz + Epz;

// Store new momenta
spec_ux[i] = ux;
spec_uy[i] = uy;
spec_uz[i] = uz;

// push particle
rg = 1.0f / sqrtf(1.0f + ux * ux + uy * uy + uz * uz);

dx = dt_dx * rg * ux;
dy = dt_dy * rg * uy;

x1 = spec_x[i] + dx;
y1 = spec_y[i] + dy;

di = ltrim(x1);
dj = ltrim(y1);

x1 -= di;
y1 -= dj;

qvz = spec_q * uz * rg;

// dep_current_zamb(spec_ix[i], spec_iy[i], di, dj, spec_x[i], spec_y[i],
//                  dx, dy, qnx, qny, qvz, current_nrow, current_jx,
//                  current_jy, current_jz);
```

After loop fission

```
ux = utx + uty * Bpz - utz * Bpy;
uy = uty + utz * Bpx - utx * Bpz;
uz = utz + utx * Bpy - uty * Bpx;

// Perform second half of the rotation

Bpx *= otsq;
Bpy *= otsq;
Bpz *= otsq;

utx += uy * Bpz - uz * Bpy;
uty += uz * Bpx - ux * Bpz;
utz += ux * Bpy - uy * Bpx;

// Perform second half of electric field acceleration
ux = utx + Epx;
uy = uty + Epy;
uz = utz + Epz;

// Store new momenta
spec_ux[i] = ux;
spec_uy[i] = uy;
spec_uz[i] = uz;
}

for (int i = 0; i < spec_np; i++) {
    // Load particle momenta
    t_part_data ux = spec_ux[i];
    t_part_data uy = spec_uy[i];
    t_part_data uz = spec_uz[i];

    // push particle
    t_part_data rg = 1.0f / sqrtf(1.0f + ux * ux + uy * uy + uz * uz);

    dx = dt_dx * rg * ux;
    dy = dt_dy * rg * uy;

    x1 = spec_x[i] + dx;
    y1 = spec_y[i] + dy;

    di = ltrim(x1);
    dj = ltrim(y1);

    x1 -= di;
    y1 -= dj;
```

Applying loop fission requires to duplicate the loop header.

In this code it also requires to duplicate some computation in the two loops resulting from the fission.

EM2D #4 (loop fission) (cont'd)

- Now we have three loops, two outermost loops (lines 694 and 755) due to loop fission.
- And the second loop is analyzable (*spec_advance_outlining:755*), showing a parallelization opportunity with a sparse reduction pattern.

```
$ cd em2d-4-loopfission/  
$ pwreport --checks --include-tags all particles.c:spec_advance_outlining --brief -- -Ofast -lm  
...
```

Parallel ZPIC/em2d: from serial to CPU & GPU...



EM2D #7a (Basic GPU+OpenACC Atomic)

EM2D #6a (Basic GPU+OpenMP Atomic)

EM2D #5a (Basic CPU+OpenMP Atomic)

EM2D #4 (loop fission)

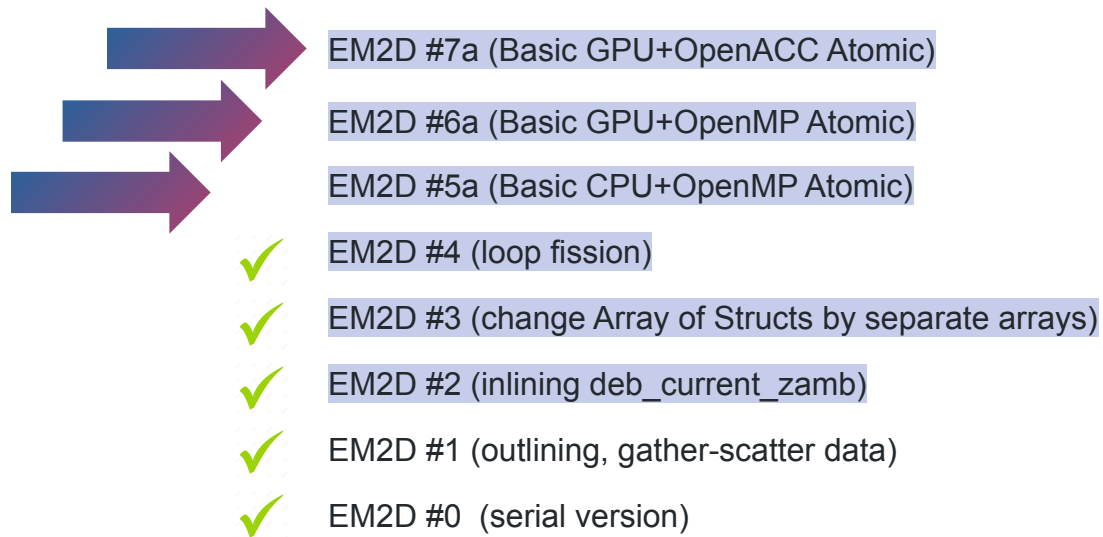
EM2D #3 (change Array of Structs by separate arrays)

EM2D #2 (inlining deb_current_zamb)

EM2D #1 (outlining, gather-scatter data)

EM2D #0 (serial version)

Parallel ZPIC/em2d: from serial to CPU & GPU...



EM2D #5a

(Basic CPU+OpenMP Atomic)

- Now that the sparse reduction loop is a parallelization opportunity reported by Codee, we can take advantage of the corresponding parallelization strategies using OpenMP on CPU:
 - Parallel loop w/ atomic
 - Parallel loop w/ explicit privatization
- **Let's generate the "atomic" version as it is the easiest to code and maintain.**
- Running this version built with **clang-11** on a Cori GPU node with 8 threads @NERSC takes **9.19 seconds (speedup 1.22x)**

```
755 #pragma omp parallel default(none) \
756     shared(current_nrow, current_Jx, current_Jy, current_Jz, dt_dx, dt_dy, \
757         qnx, qny, spec_ix, spec_iy, spec_np, spec_q, spec_ux, spec_uy, \
758         spec_uz, spec_x, spec_y) private(di, dj, dx, dy, qvz, x1, y1)
759 {
760     #pragma omp for private(di, dj, dx, dy, qvz, x1, y1) schedule(auto)
761     for (int i = 0; i < spec_np; i++) {
762         // Load particle momenta
763         t_part_data ux = spec_ux[i];
764         t_part_data uy = spec_uy[i];
765         t_part_data uz = spec_uz[i];
766
767         // push particle
768         t_part_data rg = 1.0f / sqrtf(1.0f + ux * ux + uy * uy + uz * uz);
769
770         ...
771
772         #pragma omp atomic update
773         current_Jz[vp_ix[k] + 1 + nrow * (vp_iy[k] + 1)] +=
774             vp_qvz[k] * (S0x[1] * S0y[1] + S1x[1] * S1y[1] +
775                 (S0x[1] * S1y[1] - S1x[1] * S0y[1]) / 2.0f);
776     }
777
778     ///////////////////////////////////////////////////
779     // dep_current_zamb inlined END //
780     ///////////////////////////////////////////////////
781
782     // Store results
783     spec_x[i] = x1;
784     spec_y[i] = y1;
785     spec_ix[i] += di;
786     spec_iy[i] += dj;
787 }
788 // end parallel
```

EM2D #6a

(Basic GPU+OpenMP Atomic)

- The advantage of the “atomic” strategy is that it is also available for OpenMP on GPU.
- Let’s generate the “atomic” version as it is the easiest to code and maintain.
 - Note that to implement the data transfers you will need an additional parameter *current_size* for *spec_advance_outlining()*, as needed to transfer arrays *current_Jx*, *current_Jy* and *current_Jz*.
- Running this version built with *clang-11* on a Cori GPU @NERSC takes 9,87 seconds (speedup 1,13x)
- Running this version built with *cray* on a Cori GPU @NERSC takes 8,27 seconds (speedup 1,35x)

```
755     int Jsize = current_size;
756     #pragma omp target teams distribute parallel for
757         shared(dt_dx, dt_dy, qnx, qny, spec_np, spec_q, spec_ux,
758             spec_uy, spec_uz)
759         map(to: dt_dx, dt_dy, qnx, qny, spec_np, spec_q,
760             spec_ux[0:spec_np], spec_uy[0:spec_np], spec_uz[0:spec_np])
761         private(di, dj, dx, dy, qvz, x1, y1)
762         map(tofrom: current_Jx[0:Jsize], current_Jy[0:Jsize],
763             current_Jz[0:Jsize], spec_ix[0:spec_np],
764                 spec_iy[0:spec_np], spec_x[0:spec_np], spec_y[0:spec_np])
765         schedule(auto)
766     for (int i = 0; i < spec_np; i++) {
767         // Load particle momenta
768         t_part_data ux = spec_ux[i];
769         t_part_data uy = spec_uy[i];
770         t_part_data uz = spec_uz[i];
771
772         // push particle
773         t_part_data rg = 1.0f / sqrtf(1.0f + ux * ux + uy * uy + uz * uz);
774
775         ...
776
777     #pragma omp atomic update
778         current_Jz[vp_ix[k] + 1 + nrow * (vp_iy[k] + 1)] +=
779             vp_qvz[k] * (S0x[1] * S0y[1] + S1x[1] * S1y[1] +
780                 (S0x[1] * S1y[1] - S1x[1] * S0y[1]) / 2.0f);
781     }
782
783     // dep_current_zamb inlined END //
784
785     // Store results
786     spec_x[i] = x1;
787     spec_y[i] = y1;
788     spec_ix[i] += di;
789     spec_iy[i] += dj;
790 }
```

EM2D #7a

(Basic GPU+OpenACC Atomic)

- And the “atomic” strategy is also available for OpenACC on GPU.
- Let’s generate the “atomic” version as it is the easiest to code and maintain.
 - Note that to implement the data transfers you will need an additional parameter *current_size* for *spec_advance_outlining()*, as needed to transfer arrays *current_Jx*, *current_Jy* and *current_Jz*.
- Running this version built with `nvc` on a Cori GPU @NERSC takes 7,49 seconds (speedup 1,49x)

```
755     int Jsize = current_size;
756     #pragma acc data copyin(dt_dx, dt_dy, qnx, qny, spec_np, spec_q,
757                             spec_ux [0:spec_np], spec_uy [0:spec_np],
758                             spec_uz [0:spec_np])
759     copy(current_Jx [0:Jsize], current_Jy [0:Jsize], current_Jz [0:Jsize],
760          spec_ix [0:spec_np], spec_iy [0:spec_np], spec_x [0:spec_np],
761          spec_y [0:spec_np])
762     {
763     #pragma acc parallel
764     {
765     #pragma acc loop
766     for (int i = 0; i < spec_np; i++) {
767         // Load particle momenta
768         t_part_data ux = spec_ux[i];
769         t_part_data uy = spec_uy[i];
770         t_part_data uz = spec_uz[i];
771
772         ...
773
774     #pragma acc atomic update
775         current_Jz[vp_ix[k] + 1 + nrow * (vp_iy[k] + 1)] +=
776             vp_qvz[k] * (S0x[1] * S0y[1] + S1x[1] * S1y[1] +
777                         (S0x[1] * S1y[1] - S1x[1] * S0y[1]) / 2.0f);
778     }
779
780     ///////////////////////////////////////////////////
781     // dep_current_zamb inlined END //
782     ///////////////////////////////////////////////////
783
784     // Store results
785     spec_x[i] = x1;
786     spec_y[i] = y1;
787     spec_ix[i] += di;
788     spec_iy[i] += dj;
789     }
790 } // end parallel
791 } // end data
```

Benchmarking on Perlmutter using Nvidia & GNU toolchains

| Version | #threads | Nvidia @ GPU node NVC 22.7 Time (sec) [Speedup] | GNU @ GPU node GCC 12.1 Time (sec) [Speedup] |
|---|------------|---|---|
| EM2D #0 (serial version) | n/a | 9.95 s | 11.44 s |
| EM2D #1 (outlining, gather-scatter data) | n/a | 10.95 s [0,91x] | 11.72 s [0,98x] |
| EM2D #2 (inlining deb_current_zamb) | n/a | 10.67 s [0,93x] | 11.46 s [0,99x] |
| EM2D #3 (refactor AoS) | n/a | 10.23 s [0,97x] | 11.32 s [1,01x] |
| EM2D #4 (apply loop fission) | n/a | 6.47 s [1,54x] | 9.41 s [1,21x] |
| EM2D #5a (basic CPU OpenMP Atomic) | 32 threads | 5.48 s [1,82x] | n/a (gcc 7.5 yields 6.33 seconds, 1.82x speedup) |
| EM2D #6a (basic GPU OpenMP Atomic) | n/a | n/a (nvc requires schedule(static) and Codee generates schedule(auto)) | n/a |
| EM2D #7a (basic GPU OpenACC Atomic) | n/a | n/a (nvc 22.7 combined with Codee 2023.1 raises a runtime error under investigation) | 9.26s [1,23x] |

OpenMP multithreading
yields speedup 1.82x

OpenACC offload yields
speedup 1.23x, a starting
point for further optimization

Parallel ZPIC/em2d: from serial to CPU & GPU...



EM2D #7a (Basic GPU+OpenACC Atomic)



EM2D #6a (Basic GPU+OpenMP Atomic)



EM2D #5a (Basic CPU+OpenMP Atomic)



EM2D #4 (loop fission)



EM2D #3 (change Array of Structs by separate arrays)



EM2D #2 (inlining deb_current_zamb)



EM2D #1 (outlining, gather-scatter data)



EM2D #0 (serial version)

Further optimization of ZPIC is possible!

- Now we have a baseline implementation of ZPIC/em2d, using OpenMP/OpenACC on CPU/GPU.
- Optimizations for CPU+OpenMP:
 - You can try the performance of several parallelization strategies, like explicit privatization.
 - We suggest that first you parallelize the first loop that arises after loop fission, which is a FORALL pattern that can be parallelized in a straightforward manner.
 - Next, we suggest that you use one unique parallel region for the two loops: it covers both the FORALL loop and the SPARSE REDUCTION loop.
 - And third, if you want to go a step beyond, move the parallel region outside the simulation loop.
- Optimizations for GPU+OpenMP/OpenACC:
 - We suggest that first you parallelize the first loop that arises after loop fission, which is a FORALL patterns that can be parallelized in a straightforward manner.
 - Next, we suggest that you use one unique data movement region for the two loops: it covers both the FORALL loop and the SPARSE REDUCTION loop.
 - And third, if you want to go a step beyond, move the data movement region outside the simulation loop.
- Note the similarities between the optimized version: for CPU you reason about minimizing parallel regions, and for GPUs you reason about minimizing data movement.
- Code the corresponding version and benchmark the performance improvements on the computer.

Final considerations about optimization of Sparse Reductions!

```
// Convergence loop of the simulation
for(iter=0, err = tol;
    err >= tol && iter < iter_max;
    iter++){

    // Forall "B"
    for (j=0; j<n; j++ ) {
        B[j] = j;
    }

    // Sparse reduction "A"
    for (j=0; j<n; j++ ) {
        A[C[j]] += B[j];
    }
}
```

| | ATMUX (n = 17000) | LULESHmk (n = 30000) | ZPIC (128x128 cells, 8 particles per cell) |
|---|----------------------|-------------------------|--|
| No. repetitions (final value of "iter") | 10 | 223.680.000 | 65.000.000 |
| No. loop iterations of sparse reduction (value of "n") | 17.000 | 30.000 | 3 |
| Execution time of one loop iteration | LOW | HIGH | TINY |

- **ATMUX: it is challenging due to large memory requirements for sparse matrices...**

- Note that the cost of each sparse reduction is directly related to the memory consumption of the sparse matrix, which leads to high parallelization overheads due to data movement on the GPU.

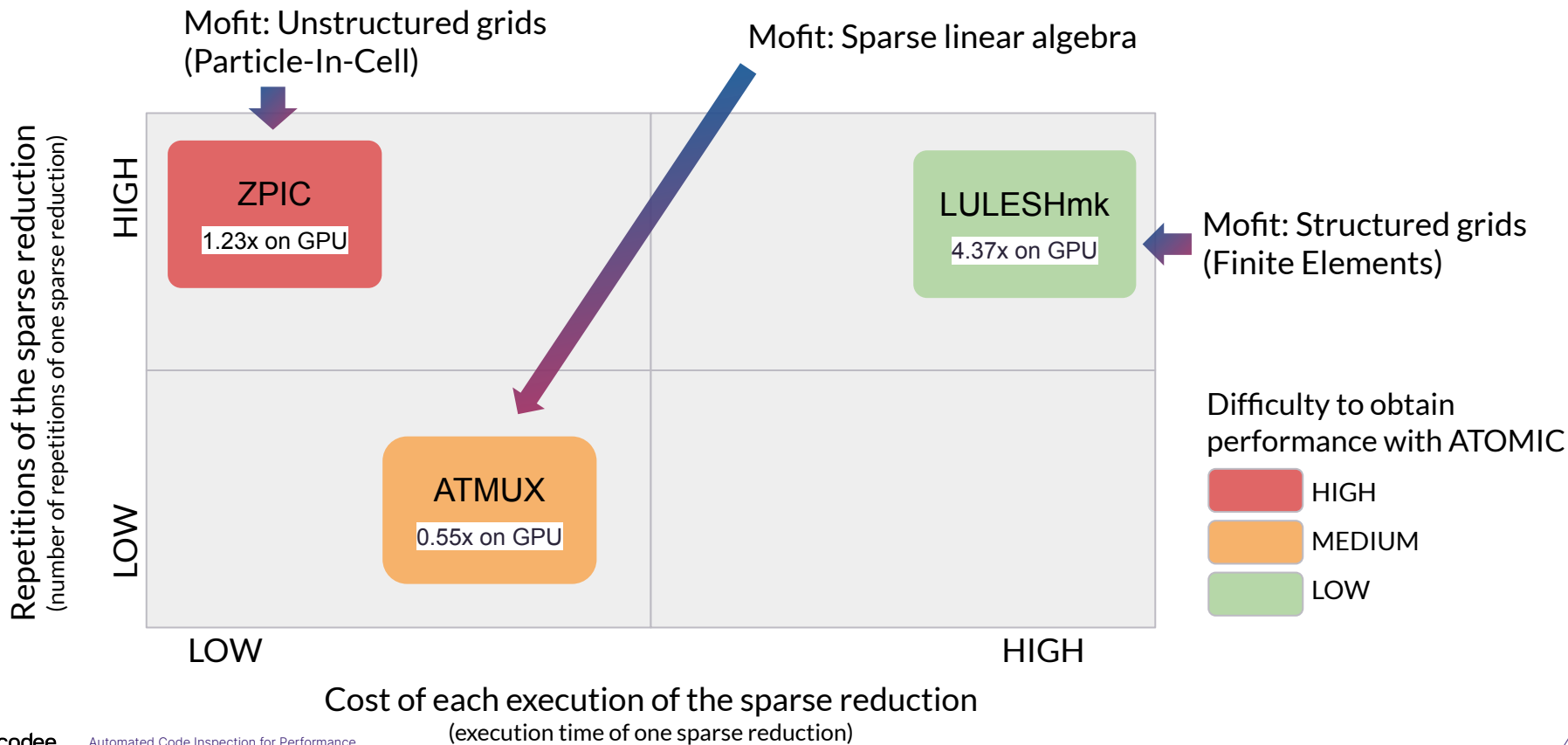
- **LULESHmk: it is challenging to find parallelization opportunities in the source code...**

- In this case the sparse reduction is time-consuming and so the parallelization overhead has less impact on performance.
- So it is easier to obtain performance for LULESHmk than for ZPIC.

- **ZPIC: it is challenging to obtain performance on both CPU and GPU because...**

- The parallelization overhead of the sparse reduction is very high compared to the execution time of one run of the sparse reduction.
- So parallelization overhead must be amortized across all of the repetitions (e.g. move data movement and thread creation out of the loop).
- This also make it key to parallelize other code sections that interact with the sparse reduction (e.g. parallelize the forall pattern).

The Performance Quadrant of Sparse Reductions





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