NESAP Project: XGC & WDMApp on Perlmutter

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EXASCALE COMPUTING PROJECT

XGC introduction

- Tokamak plasma physics code specializing in edge physics and realistic geometry
- Gyrokinetic (i.e. $6D \rightarrow 5D$ via analytic reduction using gyro-averaging)
- Particle-in-cell with an unstructured 2D grid and structured toroidal dimension
- Domain decomposition: toroidally sliced, then each MPI rank handles a subset of the grid



Tokamak cross-section



core

ECP and the Whole Device Model (WDMApp)

- The WDMApp is an Exascale Computing Project (ECP) application
- Couples XGC with a core code (GENE or GEM) for "whole device modeling"
- The vast majority (>90%) of time spent is spent in XGC, so its optimization is most critical



XGC engineering challenges

- A wide array of physics features and modes must be supported, e.g.:
 - Delta-f (perturbation from Maxwellian) and full-f
 - Electrostatic (magnetic field perturbations due to plasma ignored) and electromagnetic
 - Axisymmetric ("XGCa")
 - Impurities
 - Neutral particles with atomic cross-sections
 - Coupling (GENE, GEM, XGC, in-situ analysis)
- These different modes of operation can drastically alter landscape of performance bottlenecks
- Physics in constant state of development
 - Some changes are modular additional features
 - e.g. new sources
 - But others are (sometimes fundamental) structural modifications, e.g.:
 - Split-weight scheme
 - Stellarator
 - 6D

- Multirate timestepping
- Time telescoping
- Implicit timestepping



Target architectures

Machine	Cori KNL	Summit	Perlmutter	Frontier	Aurora
Testbed				Crusher	Florentia
Vendor	Intel	Nvidia	Nvidia	AMD	Intel
"Native" language		Cuda	Cuda	HIP	SYCL
GPU resources per rank		1 V100	1 A100	½ MI250X	
Host memory per rank	96 GB	85.3 GB	64 GB	64 GB	
Device memory per rank		16 GB	40 GB	64 GB	

- Some calculations are better off distributed among compute nodes on Cori (less memory per rank, slower computation), but shouldn't be distributed on Perlmutter (negligible computation time, more memory available)
- Some data is better off stored on device memory if there is a lot of available device memory, but
 must be moved between host and device if there is not



Exascale Preparation: Kokkos and C++

Kokkos: a portability abstraction layer that maps to OpenMP, Cuda, HIP, and SYCL



XGC Timeline

Pre 2019

Fortran code with 3 versions of dominant kernels:

• OpenACC collisions and Cuda Fortran electron push for GPUs

- Vectorized CPU version,
- Simple reference CPU version

2019 Fortran code using wrappers and macros to offload with Kokkos

- Tedious and inflexible
- Unclear for AMD/Intel GPUs

Present day C++ code with non-critical components left in Fortran



XGC engineering approaches

- Portability with Kokkos
- Major focus on encapsulation/modularity
- Templating
 - e.g., electron push and ion push are quite different (electrons subcycle and are drift kinetic, ions are gyrokinetic) but use the same code
 - Makes it much easier than before to experiment/swap out options
- Kernels
 - Most major code components can be run independently
 - They use the same code base not copies. This means:
 - They are never outdated
 - They don't require extra maintenance
 - Work on the kernels can immediately benefit the code
- Testing/CI
 - Unit tests, kernel regression tests, and run test on every pull request
 - Automated physics testing still in progress planned for bimonthly



Transition to C++

- Original attempt was to keep computation kernels in Fortran
 - Wrappers for Kokkos/Cabana functionality
 - Kernels launched with Kokkos::parallel_for() adapted to be compiled as both Fortran and Cuda Fortran



Continue with Fortran

- Feasible strategy for Cuda Fortran, but less clear for AMD/Intel GPUs
- Tedious interfaces, limited functionality
- OpenMP+ offloading instead of Kokkos?



Transition to C++

- Better usage of Kokkos/Cabana
- Earlier compiler support on ECP target architectures
- Lots of additional work to convert code
- Refactoring needed for offloading, might as well convert at the same time

"Like replacing every part of an airplane while in flight"



New plane (C++ code from scratch)

- No time spent on Fortran interfacing
- Faster development since correctness not critical to current production

- Alternative in retrospect:
 - Write C++ version separately, from scratch?

Mid-air replacement

- Single code base
 - Maintenance and improvements benefit current production code
- Code kept up to date as new physics capabilities integrated
 - Already: EM physics, multispecies physics
- Code continually tested in production conditions

Particle memory management: Reside on CPU or GPU?

- Summit and Perlmutter have different optimal memory management for particles
 - Depends on available memory per GPU and per MPI rank, and communication rate



Summit performance

- Electrostatic simulation
- Steady improvement over time as more kernels moved from CPU (left) to GPU (right)



11 Exascale Computing Project

Summit performance

- Faster computation -> worse relative weak scaling
- Deviation from weak scaling due to:
 - Particle shift
 - Electric field interplanar gather (MPI_Allgather)



Perlmutter vs Summit

- Note: *Electromagnetic* simulation
 - Electron push kernel is less important since it is subcycled fewer times
 - Additional grid operations (due to extra fields)
- ~2.1X faster than Summit (same # GPUs)





Perlmutter full-machine weak scaling

- GPU-aware MPI may improve this
- Simulation size too small Perlmutter can fit more per node
 - Particle operations well-suited for GPU
 - Will improve weak scaling by increasing computation vs MPI communication



Perlmutter vs Cori KNL

- How best to compare two very different machines? (Different memory layout, FLOPS, GPUs, etc.)
- One option: Run the same simulation "packed" into as few nodes as possible

	64 Cori KNL nodes	16 Perlmutter nodes	Difference
Memory (host + device)	6.14 TB	6.66 TB	8%
Theoretical peak FLOPS (DP)	192 TFLOPS	660 TFLOPs	3.4X
Time per step	369.2 s	41.5 s	8.9X faster

- For this electrostatic simulation, we are utilizing Perlmutter resources are 2.6X better than on Cori KNL
- Varies depending on simulation type: electromagnetic simulations are not so GPUoptimized yet



ECP testbed performance

- Comparing V100 vs GCD (i.e. ½ MI250X), EM simulation is ~2.54X faster on Crusher (Frontier testbed) than Summit
- Performance on Aurora testbed machine also looking promising (not public yet)
- Our portability strategy seems to be working!





New Physics on Perlmutter

- In many tokamaks, exhaust from plasma is directed along the separatrix toward divertor plates
- The divertor must be prepared to handle the heat of this exhaust a wider impact area is better, so divertor heat load width λ_q is an important parameter to study



- Using electrostatic simulations, XGC has matched observed λ_q for other tokamaks, but its predictions for ITER suggest it will be in a new regime with a higher-than-expected λ_q (good news)
- Our fully electromagnetic simulations on **Perlmutter** suggest that EM effects will increase λ_q even further



New Physics on Perlmutter



Poincare puncture-density plot of magnetic field in electromagnetic turbulence • Homoclinic tangles have been observed in the simulation, resulting in a more diffuse stream of plasma from the X-point to the divertor than previously thought

(These have been observed before but only under special circumstances like ELMS)

• Interventions may be possible to strengthen these tangles and further increase divertor heat load width

XGC simulation by S. Ku (PPPL) on Summit; Visualization by D. Pugmire (ORNL)

New Physics on Perlmutter





19 Exascale Computing Project

DIII-D simulation by S. Ku, PPPL; Visualization by D. Pugmire, ORNL]

Conclusion

- XGC is running on Perlmutter and generally performing well
 - Still plenty of work to be done to optimize XGC (especially EM mode): offloading kernels to GPU via Kokkos, improving MPI communication and load balancing, and keeping up with new physics additions
- Perlmutter is already enabling XGC simulations that are providing insight on electromagnetic fusion plasma behavior and making predictions for ITER

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