Using HPCToolkit to Measure and Analyze the Performance of GPU-accelerated Applications

John Mellor-Crummey
Rice University

Tutorial
Mar-Apr 2021
NERSC and OLCF (Virtual)
Acknowledgments

• Current funding
  – DOE Exascale Computing Project (Subcontract 4000151982)
  – DOE Labs: ANL (Subcontract 9F-60073), Tri-labs (LLNL Subcontract B645220)
  – Industry: AMD, Total E&P Research & Technology

• Team
  – Rice University
    • HPCToolkit PI: Prof. John Mellor-Crummey
    • Research staff: Laksono Adhianto, Mark Krentel, Xiaozhu Meng, Scott Warren
    • Contractor: Marty Itzkowitz
    • Students: Jonathon Anderson, Aaron Cherian, Dejan Grubisic, Yumeng Liu, Keren Zhou
    • Recent summer interns: Vladimir Indjic, Tijana Jovanovic, Aleksa Simovic
  – University of Wisconsin – Madison
    • Dyninst PI: Prof. Barton Miller
HPCToolkit Team at the Tutorial

Laksono Adhianto
Mark Krentel
John Mellor-Crummey
Xiaozhu Meng

Aaron Cherian
Dejan Grubisic
Yumeng Liu
Keren Zhou
DOE’s Forthcoming Heterogeneous Exascale Platforms

- **Aurora compute nodes (ALCF)**
  - 2 Intel Xeon “Sapphire Rapids” processors
  - 6 Intel Xe “Ponte Vecchio” GPUs
  - 8 Slingshot endpoints
  - Unified memory architecture

- **Frontier compute nodes (OLCF)**
  - 1 AMD EPYC CPU
  - 4 purpose-built AMD Radeon Instinct GPUs
  - Multiple Slingshot endpoints
  - Unified memory architecture

- **El Capitan compute nodes (LLNL)**
  - Next-generation AMD EPYC “Genoa” CPU (5nm)
  - Next-generation AMD Radeon Instinct GPUs
DOE’s NVIDIA-based Heterogeneous Supercomputers

• Summit compute nodes (OLCF)
  • 2 IBM Power9 processors
  • 6 NVIDIA V100 GPUs
  • Dual-rail Mellanox EDR Infiniband Fat Tree

• Sierra compute nodes (LLNL)
  • 2 IBM Power9 processors
  • 4 NVIDIA V100 GPUs
  • Mellanox EDR Infiniband Fat Tree

• Perlmutter compute nodes (LBNL)
  • AMD Milan CPU
  • 4 NVIDIA A100 GPUs
  • Cray Slingshot Interconnect
Node-level Programming Models for Heterogeneous Supercomputers

- Native programming models from platform vendors
  - Intel DPC++
  - CUDA
  - HIP: AMD’s CUDA-like model

- Directive-based models
  - OpenACC: offload structured blocks and device functions, work sharing loops, data environment, data mappings
  - OpenMP

- C++ template-based models
  - RAJA: parallelism loops, iteration spaces, execution policies, traversal templates, lambda functions, n-dimensional array abstractions, and lambda functions
  - Kokkos
Global Programming Models

• Message passing
  • MPI

• Partitioned global address space programming models
  • languages
    • Coarray Fortran, Coarray C++, Chapel, UPC
  • libraries
    • UPC++, GASNet, OpenSHMEM, Global Arrays

• Object-based
  • Charm++

Sources: Frontier Spec Sheet
https://docs.nersc.gov/development/programming-models
Performance Analysis Challenges for GPU-accelerated Supercomputers

• Myriad performance concerns
  – Computation: need extreme-scale data parallelism to keep GPUs busy
  – Data movement costs within and between memory spaces
  – Internode communication
  – I/O

• Many ways to hurt performance
  – insufficient parallelism, load imbalance, serialization, replicated work, data copies, synchronization, lack of locality, …

• Hardware and execution model complexity
  – Multiple compute engines with vastly different characteristics, capabilities, and concerns
  – Multiple memory spaces with different performance characteristics
  – Asynchronous execution
Measurement Challenges for GPU-accelerated Supercomputers

• Extreme-scale parallelism
  – Serialization within tools will disrupt parallel performance

• Dependent on third-party measurement interfaces
  – Hardware
    – CPU hardware performance monitoring unit
    – GPU hardware counters and PC sampling
  – Software
    – Glibc LD_AUDIT for tracking dynamic loading of shared libraries
    – Linux perf_events for kernel measurement
    – GPU monitoring and instrumentation libraries from vendors

• Multiple measurement modalities and interfaces
  – Sampling on the CPU
  – Callbacks when GPU operations are launched and (sometimes) completed
  – GPU event stream, including PC sampling measurements

• Frequent GPU kernel launches require a low-overhead measurement substrate
Engineering Challenges for Performance Tools

- **Complex applications**
  - Compositions of programming models
  - > 100 dynamic libraries
  - Application binaries exceeding 5GB
  - HPC libraries that intercept system calls (mmap, munmap, open, close)
- **Quirky application characteristics**
  - NAMD: exit initiated by a non-initial thread
  - Kull: forking non-readable helper application
- **Dynamic library loading**
  - Implicit system locks on dynamic library state
  - RUNPATH: library-specific library load path
  - Early threads in library init constructors
  - Nested dynamic library loading
- **Provisioning thread local state**
  - Implicit lock when creating or destroying thread local storage
- **Process fork**
  - atfork handlers trigger thread destructors
- **Interactions with vendor tool substrates**
  - Libraries lack documentation of their actions, e.g. creating threads
  - Callbacks for submission and completion on unspecified (and sometimes different) threads
- **Interaction between tools and software stack**
  - Interaction of signals with everything
  - Managing monitoring when forking
- **Lack of vendor tooling and documentation**
  - Non-standard GPU binary formats that lack public documentation
Other GPU Performance Tools

• Features
  • Trace view
    • A series of events that happen over time on each process, thread, and GPU stream
  • Profile view
    • A correlation of performance metrics with program contexts

• Tools
  • GPU vendors
    • Nsight Systems, Nsight Compute, nvprof, ROCProfiler, Intel VTune
  • Third party
    • TAU, VampirTrace, ARM Map
Shortcomings of Other Tools for Complex GPU-accelerated Programs

• They lack a comprehensive profile view to analyze
  – CPU calling contexts (including inlined frames) where GPU operations are invoked
    • Understanding where, how and why GPU kernels arose from instantiation of nested templates
    • Understanding costs of GPU APIs (e.g., cudaMemcpy) invoked from many different contexts
  – Sophisticated GPU calling contexts
    • OpenMP Target, Kokkos, and RAJA generate GPU code with many small procedures
  – Loop-level performance information on CPUs and GPUs
• At best, existing tools only attribute runtime cost to a flat profile view of functions executed on GPUs
Outline

• Performance measurement and analysis challenges for GPU-accelerated supercomputers

• Introduction to HPCToolkit performance tools
  – Overview of HPCToolkit components and their workflow
  – HPCToolkit's graphical user interfaces
  – Analyzing the performance of GPU-accelerated supercomputers with HPCToolkit
    – Overview of HPCToolkit's GPU performance measurement capabilities
    – Collecting measurements
    – Analysis and attribution
    – Scalable analysis of performance data

• Status, ongoing work, final remarks
Rice University’s HPCToolkit Performance Tools

- Employs binary-level measurement and analysis
  - Observes executions of fully optimized, dynamically-linked parallel applications
  - Supports multi-lingual codes with external binary-only libraries

- Collects sampling-based measurements of CPU
  - Controllable overhead
  - Minimize systematic error and avoid blind spots
  - Enable data collection for large-scale parallelism

- Measures GPU performance using vendor APIs
  - Register callbacks to monitor launch/completion of GPU operations
  - Monitor asynchronous GPU operations using activity APIs from NVIDIA and AMD
  - Collect fine-grain measurements of GPU code using PC sampling (NVIDIA) and instrumentation (Intel GTPin)

- Associates metrics with both static and dynamic context
  - Loop nests, procedures, inlined code, calling contexts on both CPU and GPU

- Enables one to specify and compute derived CPU and GPU performance metrics of your choosing
  - Diagnosis often requires more than one species of metric

- Supports top-down performance analysis
  - Identify costs of interest and drill down to causes: up and down call chains, over time
HPCToolkit High-level Workflow

- **source code** → **optimized binary**
  - Compile & link

- **profile execution** [hpcrun]
  - Call path profiles
  - Call path traces

- **binary analysis** [hpcstruct]
  - Program structure

- **interpret profile correlate w/ source** [hpcprof/hpcprof-mpi]
  - Presentation [hpcviewer]

- **database**
Measure execution unobtrusively with **hpcrun**

- Launch optimized dynamically-linked application binaries
- Collect call path profiles of events of interest
- Where necessary, intercept interfaces for control and measurement
Call Path Profiling

- Measure and attribute costs in context
  - Sample timer or hardware counter overflows
  - Gather CPU calling context using stack unwinding

Overhead proportional to sampling frequency, not call frequency
HPCToolkit High-level Workflow

Analyze binary with **hpcstruct**: recover program structure
- Analyze machine code, line map, debugging information
- Extract loop nests & identify inlined procedures
- Map transformed loops and procedures to source

- **profile execution** [hpcrun]
- **call path profiles**
- **call path traces**
- **binary analysis** [hpcstruct]
- **program structure**
- **interpret profile** correlate w/ source [hpcprof/hpcprof-mpi]
- **presentation** [hpcviewer]
Dyninst: A Toolkit for Binary Analysis and Instrumentation

Architectures
- X86_64
- Power/BE
- Power/LE
- ARM
- AMD Vega
- CUDA
- Intel GPU

Lead Institution: University of Wisconsin – Madison
HPCToolkit High-level Workflow

- Combine multiple profiles
  - Multiple threads; multiple processes; multiple executions
- Correlate metrics to static & dynamic program structure
HPCToolkit High-level Workflow

Presentation
- Explore performance data from multiple perspectives
  - Rank order by metrics to focus on what’s important
    e.g., cycles, instructions, GPU instructions, GPU stalls
  - Compute derived metrics to help gain insight, e.g. scalability losses
- Explore evolution of behavior over time
Code-centric Analysis with hpcviewer

- function calls in full context
- inlined procedures
- inlined templates
- outlined OpenMP loops
- sequential loops

**source pane**

**view control**

**metric display**

**navigation pane**

**metric pane**
Understanding Temporal Behavior

- Profiling compresses out the temporal dimension
  - Temporal patterns, e.g. serial sections and dynamic load imbalance are invisible in profiles

- What can we do? Trace call path samples
  - N times per second, take a call path sample of each thread
  - Organize the samples for each thread along a time line
  - View how the execution evolves left to right
  - What do we view? assign each procedure a color; view a depth slice of an execution
Time-centric Analysis of Call Path Traces

Detail of a trace of Flash3 - block structured AMR code written in Fortran

- 256 ranks

Depth, trace, and call path views
Outline

- Performance measurement and analysis challenges for GPU-accelerated supercomputers
- Introduction to HPCToolkit performance tools
  - Overview of HPCToolkit components and their workflow
  - HPCToolkit's graphical user interfaces
  - Analyzing the performance of GPU-accelerated supercomputers with HPCToolkit
    - Overview of HPCToolkit's GPU performance measurement capabilities
    - Collecting measurements
    - Analysis and attribution
    - Scalable analysis of performance data
- Status, ongoing work, final remarks
HPCToolkit for GPU-accelerated Computations

- CUPTI
- Sanitizer
- ROCTracer
- Level Zero
- OpenCL
- NVIDIA
- AMD
- Intel
- OpenMP

HPCToolkit GPU Core
Highlights of HPCToolkit’s Support for GPU-accelerated Codes

• It unwinds the CPU call stack to identify the CPU calling context for each GPU API invocation
• It employs novel data structures for fast and non-blocking inter-thread communication
• It employs binary analysis of GPU code to attribute fine-grain performance measurements to functions, inlined functions and templates, loops, and statements
  • NVIDIA, Intel, and AMD GPU binaries
• It uses a novel technique to reconstruct an approximate GPU calling context tree for computations from instruction-level measurements
• On NVIDIA GPUs: derives a rich set of metrics from PC samples from a single execution
• It performs scalable analysis of sparse representations of performance measurements and produces sparse representations tailored for graphical user interfaces
HPCToolkit’s Sparse Representation of Measurements at Run-time

Information for kernel execution on NVIDIA GPUs
HPCToolkit’s Code-Centric Profiles of GPU-accelerated Code

<table>
<thead>
<tr>
<th>CPU Calling Context</th>
<th>GPU API Node</th>
<th>GPU Calling Context</th>
</tr>
</thead>
<tbody>
<tr>
<td>1325: ParallelFor&lt;__nv_dl_wrapper_t&lt;__nv_dl_tag&lt;void (PeleC*)&gt;(double, char, int, int)&gt;</td>
<td>__nv_dl_wrapper_device_stub_launch_global&lt;__nv_dl_wrapper_t&lt;__nv_dl_tag&lt;void (*)()&gt;&gt;</td>
<td>__nv_dl_wrapper_device_stub_ZNSamrex13lauch_globalZNS_11Parallel</td>
</tr>
<tr>
<td>11: __nv_dl_wrapper_device_stub_launch_global&lt;__nv_dl_wrapper_t&lt;__nv_dl_tag&lt;void (*)()&gt;&gt;</td>
<td>__nv_dl_wrapper_device_stub_ZNSamrex13lauch_globalZNS_11Parallel</td>
<td>__nv_dl_wrapper_device_stub_ZNSamrex13lauch_globalZNS_11Parallel</td>
</tr>
</tbody>
</table>

### Fine-grained Metrics

<table>
<thead>
<tr>
<th>GPU</th>
<th>GINS:Sum (I)</th>
<th>GINS:Sum (E)</th>
</tr>
</thead>
<tbody>
<tr>
<td>3.30e+09</td>
<td>1.0%</td>
<td>1.0%</td>
</tr>
<tr>
<td>3.30e+09</td>
<td>1.0%</td>
<td>1.0%</td>
</tr>
<tr>
<td>3.30e+09</td>
<td>1.0%</td>
<td>1.0%</td>
</tr>
<tr>
<td>3.30e+09</td>
<td>1.0%</td>
<td>1.0%</td>
</tr>
<tr>
<td>3.00e+09</td>
<td>1.0%</td>
<td>2.57e+08</td>
</tr>
<tr>
<td>3.00e+09</td>
<td>1.0%</td>
<td>2.56e+08</td>
</tr>
<tr>
<td>3.00e+09</td>
<td>1.0%</td>
<td>2.53e+08</td>
</tr>
<tr>
<td>2.88e+09</td>
<td>0.9%</td>
<td>5.28e+07</td>
</tr>
<tr>
<td>4.57e+08</td>
<td>0.1%</td>
<td>4.56e+08</td>
</tr>
<tr>
<td>2.13e+07</td>
<td>0.0%</td>
<td>2.13e+07</td>
</tr>
</tbody>
</table>

### Coarse-grained Metrics

<table>
<thead>
<tr>
<th>GPU</th>
<th>GKER (sec):Sum (I)</th>
<th>GKER (sec):Sum (E)</th>
</tr>
</thead>
<tbody>
<tr>
<td>2.99e-01</td>
<td>16.5%</td>
<td>2.99e-01</td>
</tr>
<tr>
<td>2.99e-01</td>
<td>16.5%</td>
<td>2.99e-01</td>
</tr>
<tr>
<td>2.99e-01</td>
<td>16.5%</td>
<td>2.99e-01</td>
</tr>
<tr>
<td>2.99e-01</td>
<td>16.5%</td>
<td>2.99e-01</td>
</tr>
<tr>
<td>2.99e-01</td>
<td>16.5%</td>
<td>2.99e-01</td>
</tr>
</tbody>
</table>

### Derived Metrics

<table>
<thead>
<tr>
<th>GPU UTIL</th>
</tr>
</thead>
<tbody>
<tr>
<td>2.49%</td>
</tr>
<tr>
<td>2.49%</td>
</tr>
<tr>
<td>2.49%</td>
</tr>
<tr>
<td>2.49%</td>
</tr>
<tr>
<td>2.49%</td>
</tr>
</tbody>
</table>

---

*ECP - Extreme Computing Project*
GPU Performance Measurement

• Three categories of threads
  – Application Threads (N per process)
    • Launch kernels, move data, and synchronize GPU calls
  – Monitor Thread (1 per process)
    • Monitor GPU events and collect GPU measurements
  – Tracing Threads (1 for every K GPU streams)

• Interactions
  – Create correlation: An application thread \( T \) creates a correlation record when it launches a kernel and tags the kernel with a correlation ID \( C \), notifying the monitor thread that \( C \) belongs to \( T \)
  – Attribute measurements: The monitor thread collects measurements associated with \( C \) and communicates measurement records back to thread \( T \)
  – Record traces: The monitor thread sends activity traces to tracing threads to record in a separate trace file per GPU stream (NVIDIA, AMD) or device queue (Intel, AMD)
HPCToolkit’s Runtime Monitoring Infrastructure for OpenCL
Approximation of GPU Calling Contexts to Understand Performance

- GPU code from C++ template-based programming models is complex
- NVIDIA GPUs collect flat PC samples
- Flat profiles for instantiations of complex C++ templates are inscrutable

HPCToolkit reconstructs approximate GPU calling contexts

- Reconstruct call graph from machine code
- Infer calls at call sites
  - PC samples of call instructions indicate calls
  - Use call counts to apportion costs to call sites
- PC samples in a routine
Approximation of GPU Calling Contexts to Understand Performance

- GPU code from C++ template-based programming models is complex.
- NVIDIA GPUs collect flat PC samples.
- Flat profiles for instantiations of complex C++ templates are inscrutable.
- HPCToolkit reconstructs approximate GPU calling contexts.
  - PC samples of call instructions indicate calls.
  - Use counts to split costs.
  - PC samples in a routine infer caller or distribute costs equally to potential callers.

Flat profile of functions called by a GPU kernel.
Approximation of GPU Calling Contexts to Understand Performance

- GPU code from C++ template-based programming models is complex
- NVIDIA GPUs collect flat PC samples
- Flat profiles for instantiations of complex C++ templates are inscrutable

- HPCToolkit reconstructs approximate GPU calling contexts
  - Reconstruct call graph from machine code
  - Infer calls at call sites
    - PC samples of call instructions indicate calls
    - Use call counts to apportion costs to call sites
    - PC samples in a routine
Approximate Performance Attribution to GPU Calling Contexts

- GPU code from C++ template-based programming models is complex.
- NVIDIA GPUs collect flat PC samples.
- Flat profiles for instantiations of complex C++ templates are inscrutable.
- HPCToolkit reconstructs approximate GPU calling contexts - PC samples of call instructions indicate calls.
- Use counts to split costs - PC samples in a routine.
- Infer caller or distribute costs equally to potential callers.
Reconstruction of GPU Calling Context Trees

• Problem
  – Vendor GPU monitoring APIs don’t collect call paths inside GPU kernels

• Challenges
  – GPU functions may be invoked from different call sites
  – Need to decide how to attribute costs to each call site

• Solution
  – Reconstruct GPU calling context tree from flat instruction samples and static GPU call graph
Approximate Performance Attribution to GPU Calling Contexts

1. Construct a GPU static call graph based on functions and call instructions. Initialize call edge counts using counts or samples of call instructions.

2. For call graphs based on samples: if a function has samples and no incoming call edge has a non-zero weight, assign each of its incoming call edges a weight of 1; repeat for call edges of callers until at least one incoming call edge has samples.

3. Identify strongly connected components (SCCs) using Tarjan's algorithm. Rewire call graph, removing SCC internal structure and linking external calls to SCC.

4. Build CCT by splitting call graph. Like gprof, assume that every call to a function has equal cost. Apportion costs of each function among its call sites according to ratios of calls from each call site.
1. Construct a GPU static call graph based on functions and call instructions. Initialize call edge counts using counts or samples of call instructions.

2. For call graphs based on samples: if a function has samples and no incoming call edge has a non-zero weight, assign each of its incoming call edges a weight of 1; repeat for call edges of callers until at least one incoming call edge has samples.

3. Identify strongly connected components (SCCs) using Tarjan's algorithm. Rewire call graph, removing SCC internal structure and linking external calls to SCC.

4. Build CCT by splitting call graph. Like gprof, assume that every call to a function has equal cost. Apportion costs of each function among its call sites according to ratios of calls from each call site.
1. Construct a GPU static call graph based on functions and call instructions. Initialize call edge counts using counts or samples of call instructions.

2. For call graphs based on samples: if a function has samples and no incoming call edge has a non-zero weight, assign each of its incoming call edges a weight of 1; repeat for call edges of callers until at least one incoming call edge has samples.

3. Identify strongly connected components (SCCs) using Tarjan's algorithm. Rewire call graph, removing SCC internal structure and linking external calls to SCC.

4. Build CCT by splitting call graph. Like gprof, assume that every call to a function has equal cost. Apportion costs of each function among its call sites according to ratios of calls from each call site.
Approximate Performance Attribution to GPU Calling Contexts

1. Construct a GPU static call graph based on functions and call instructions. Initialize call edge counts using counts or samples of call instructions.

2. For call graphs based on samples: if a function has samples and no incoming call edge has a non-zero weight, assign each of its incoming call edges a weight of 1; repeat for call edges of callers until at least one incoming call edge has samples.

3. Identify strongly connected components (SCCs) using Tarjan's algorithm. Rewire call graph, removing SCC internal structure and linking external calls to SCC.

4. Build CCT by splitting call graph. Like gprof, assume that every call to a function has equal cost. Apportion costs of each function among its call sites according to ratios of calls from each call site.
Support for OpenMP TARGET

- HPCToolkit implementation of OMPT OpenMP API
  - host monitoring
    - leverages callbacks for regions, threads, tasks
  - GPU monitoring
    - leverages callbacks for device initialization, kernel launch, data operations
    - reconstruction of user-level calling contexts
- Leverages implementation of OMPT in LLVM OpenMP and libomptarget

ECP QMCPACK Project: miniqmc using OpenMP TARGET (Power9 + NVIDIA V100)

Reconstruct full calling contexts that include
- Outlined procedures for OpenMP parallel regions
- Offloaded OpenMP TARGET computation and synchronization

---

*ECP QMCPACK Project: miniqmc using OpenMP TARGET (Power9 + NVIDIA V100)*
Support for RAJA and Kokkos C++ Template-based Models

- RAJA and Kokkos provide portability layers atop C++ template-based programming abstractions
- HPCToolkit employs binary analysis to recover information about procedures, inlined functions and templates, and loops
  - Enables both developers and users to understand complex template instantiation present with these models

ECP EXAALT Project: LAMMPS using Kokkos over CUDA (Power9 + NVIDIA V100)

Reconstruct full calling contexts that include
- Inlined Kokkos templates
- Offloaded Kokkos CUDA computation
Deriving GPU Metrics

• **Problem**
  - GPU PC sampling cannot be used in the same pass with metric collection
  - Nsight-compute runs nine passes to collect multiple metrics for kernels

• **Our approach**
  - Measure a single pass of an execution and collect PC samples
  - Derive multiple metrics using PC samples and other activity records
    - e.g., GPU SM utilization, GPU occupancy, …
Nyx with CUDA: Trace of Multi-rank Multi-GPU Executions
Nyx with CUDA: Trace of Multi-rank Multi-GPU Executions
Scalable Analysis of Performance Data

• **When to reduce profile data?**
  - After termination: Linux perf, NVIDIA nvvp, and Paraver record detailed traces
  - At termination
    - Scalasca, Tau, Vampir use MPI to unify profile data into CUBE format
    - HPCToolkit saves separate profiles and traces per thread

• **Scalable analysis of performance data using out-of-core algorithms**
  - Inspect profiles and balance across ranks by aggregate size
  - Unify call stacks from all threads
  - Overlay static information on calling context trees: procedures, inline functions, loops, stmts
  - Generate computed statistics: aggregate and per profile
  - Write out two sparse outputs
    - profile-major-sparse database
    - calling-context-major-sparse database
  - Implementation: MPI + OpenMP
Is Using Sparse Formats Important?

• Assess the space savings of sparse profiles
  • AMD2006 CPU
    • 1 metric
    • 9 metrics, including some rare metrics
  • Nyx GPU
  • LAMMPS GPU

• Findings
  • as much as 21x space reduction for measurements
  • as much 337x reduction for output data

<table>
<thead>
<tr>
<th>Dataset</th>
<th>Size (MiB)</th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>Dense</td>
<td>Sparse</td>
<td>Ratio</td>
</tr>
<tr>
<td>AMG2006 (1) M</td>
<td>659.0</td>
<td>911.0</td>
<td>0.723x</td>
<td></td>
</tr>
<tr>
<td>D</td>
<td>7370.0</td>
<td>836.0</td>
<td>8.819x</td>
<td></td>
</tr>
<tr>
<td>AMG2006 (9) M</td>
<td>21.7</td>
<td>11.1</td>
<td>1.956x</td>
<td></td>
</tr>
<tr>
<td>D</td>
<td>2290.0</td>
<td>33.5</td>
<td>68.34x</td>
<td></td>
</tr>
<tr>
<td>Nyx M</td>
<td>5890.0</td>
<td>278.0</td>
<td>21.14x</td>
<td></td>
</tr>
<tr>
<td>D</td>
<td>130 GiB</td>
<td>601.0</td>
<td>221.5x</td>
<td></td>
</tr>
<tr>
<td>LAMMPS M</td>
<td>85.5</td>
<td>5.23</td>
<td>16.35x</td>
<td></td>
</tr>
<tr>
<td>D</td>
<td>8250.0</td>
<td>24.5</td>
<td>336.9x</td>
<td></td>
</tr>
</tbody>
</table>
Scalable Analysis of Performance Data: 64K profiles of AMG2006

**Input**
- 5GB profiles
- 225GB traces

**Analysis**
- 8 KNL nodes
- 1 rank / node
- 128T / rank

**Execution time**
- 184s
Outline

• Performance measurement and analysis challenges for GPU-accelerated supercomputers

• Introduction to HPCToolkit performance tools
  – Overview of HPCToolkit components and their workflow
  – HPCToolkit's graphical user interfaces
  – **Analyzing the performance of GPU-accelerated supercomputers with HPCToolkit**
    – Overview of HPCToolkit's GPU performance measurement capabilities
    – Collecting measurements
    – Analysis and attribution
    – Scalable analysis of performance data

• Status, ongoing work, final remarks
### Status for Various GPUs

<table>
<thead>
<tr>
<th>Vendor</th>
<th>Coarse-grain measurement</th>
<th>Fine-grain measurement</th>
<th>Tracing</th>
<th>Binary analysis: loops, inlined code</th>
</tr>
</thead>
<tbody>
<tr>
<td>NVIDIA</td>
<td>CUPTI</td>
<td>PC sampling</td>
<td>CUPTI</td>
<td>nvdisasm + Dyninst</td>
</tr>
<tr>
<td>Intel</td>
<td>OpenCL and Level 0</td>
<td>GTPin instrumentation</td>
<td>OpenCL callbacks</td>
<td>IGA + Dyninst</td>
</tr>
<tr>
<td>AMD</td>
<td>Roctracer</td>
<td>emerging Dyninst</td>
<td>Roctracer</td>
<td>emerging Dyninst decoder</td>
</tr>
</tbody>
</table>
# Detailed Performance Analysis Requires Support at Many Levels

<table>
<thead>
<tr>
<th>Hardware and Software Stack Components</th>
<th>Partners</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Hardware must include support for fine-grain measurement and attribution</strong></td>
<td>GPU vendors</td>
</tr>
<tr>
<td>• performance counters are not enough; NVIDIA's PC sampling approximates our needs</td>
<td></td>
</tr>
<tr>
<td><strong>System software must provide appropriate interfaces for introspection and analysis</strong></td>
<td>Red Hat</td>
</tr>
<tr>
<td>• e.g. Linux perf_events supports sample-based performance monitoring even in the kernel</td>
<td></td>
</tr>
<tr>
<td>• e.g. dynamic loader (ld.so) provides LD_AUDIT interface for monitoring and control of dynamic library operations</td>
<td></td>
</tr>
<tr>
<td>• elfutils must support NVIDIA's extended line maps in CUDA 11.2+ GPU binaries</td>
<td></td>
</tr>
<tr>
<td><strong>GPU vendor software stacks (kernel driver, runtime, tools API)</strong></td>
<td>GPU vendors</td>
</tr>
<tr>
<td><strong>Compiler must compute high-quality DWARF information</strong></td>
<td>Vendors and LLVM community</td>
</tr>
<tr>
<td>• associate each machine instruction with full call chains involving inlined templates and functions</td>
<td></td>
</tr>
<tr>
<td><strong>Runtime must maintain information needed to map computations to a source-level view</strong></td>
<td>OpenMP Language Committee and LLVM Community</td>
</tr>
<tr>
<td>• OpenMP's OMPT helps bridge the vast gap between the implementation and user-level view</td>
<td></td>
</tr>
<tr>
<td><strong>Performance tools must gather measurements using multiple modalities and map them to source</strong></td>
<td>Wisconsin's Dyninst Project</td>
</tr>
<tr>
<td>• precise attribution when possible</td>
<td></td>
</tr>
<tr>
<td>• reconstruct approximate attribution when precise attribution is unavailable</td>
<td></td>
</tr>
<tr>
<td>• GPU calling context</td>
<td></td>
</tr>
<tr>
<td>• loops in CPU and GPU code</td>
<td></td>
</tr>
<tr>
<td>• attribute inefficiencies from where they are observed back to their causes</td>
<td></td>
</tr>
</tbody>
</table>
Ongoing Work

• **Interface**
  - Emerging GPU Performance Advisor tool for NVIDIA GPUs
    - attributes instruction stalls with backward slicing, analyzes code, offers advice about most promising improvements
  - Integrated user interface that supports both profiles and traces
    - Automated serialization analysis of CPU and GPU traces

• **Internals**
  - Collecting GPU hardware counters, which will support Roofline analysis
  - Updating measurement and analysis support for NVIDIA GPUs (emerging CUPTI, more info about inlining)
  - Extending HPCToolkit to support analysis of machine learning frameworks: Pytorch, Tensorflow
  - Improving scalability of measurement and analysis
  - Developing instrumentation to assess performance on Intel GPUs
  - Refining implementation of monitoring for Intel’s Level 0
  - Improving binary analysis of AMD GPU binaries
Final Remarks

• **Nice to work with national labs and have early involvement in big procurements**
  - Amplifies our ability to affect vendor hardware and software in the near term

• **Software development challenges are myriad**
  - Developing tools for three GPU software stacks at the same time is ridiculous
  - Building capabilities ahead of current vendor hardware and software
  - AMD and Intel software is a work in progress
    - instability and API-breaking changes are common
  - Relying on vendor closed-source components is a challenge
    - standards specify only an API, but internals matter for tools that see all
    - undocumented behaviors about things that matter
    - missing capabilities, e.g. need excellent DWARF mappings for optimized GPU code
    - NVIDIA serializes kernels to facilitate measurement with PC sampling