NVIDIA HPC STANDARD LANGUAGE PARALLELISM, C++

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4/7/22
PROGRAMMING THE NVIDIA PLATFORM

CPU, GPU, and Network

ACCELERATED STANDARD LANGUAGES
ISO C++, ISO Fortran

std::transform(par, x, x+n, y, y,
    [=](float x, float y) { return y + a*x; })

do concurrent (i = 1:n)
    y(i) = y(i) + a*x(i)
endo

import cunumeric as np

def saxpy(a, x, y):
    y[:] += a*x

INCREMENTAL PORTABLE OPTIMIZATION
OpenACC, OpenMP

#pragma acc data copy(x,y) {
...}
std::transform(par, x, x+n, y, y,
    [=](float x, float y) {
        return y + a*x;
    });
...

#pragma omp target data map(x,y) {
...}
std::transform(par, x, x+n, y, y,
    [=](float x, float y) {
        return y + a*x;
    });
...

PLATFORM SPECIALIZATION
CUDA

__global__
void saxpy(int n, float a,
    float *x, float *y) {
    int i = blockIdx.x*blockDim.x + threadIdx.x;
    if (i < n) y[i] += a*x[i];
}

int main(void) {
...}

cudaMemcpy(d_x, x, ...);
cudaMemcpy(d_y, y, ...);
saxpy<<<(N+255)/256,256>>>(...);
cudaMemcpy(y, d_y, ...);

ACCELERATION LIBRARIES
Core Math Communication Data Analytics AI Quantum
ACCELERATED STANDARD LANGUAGES

Parallel performance for wherever your code runs

ISO C++

```cpp
std::transform(par, x, x+n, y, y,[=](float x, float y){
    return y + a*x;
});
```

ISO Fortran

```fortran
do concurrent (i = 1:n)
    y(i) = y(i) + a*x(i)
enddo
```

Python

```python
import cunumeric as np
...
def saxpy(a, x, y):
    y[:] += a*x
```

<table>
<thead>
<tr>
<th>CPU</th>
<th>GPU</th>
</tr>
</thead>
<tbody>
<tr>
<td>nvc++ -stdpar=multicore</td>
<td>nvc++ -stdpar=gpu</td>
</tr>
<tr>
<td>nvfortran -stdpar=multicore</td>
<td>nvfortran -stdpar=gpu</td>
</tr>
<tr>
<td>legate -cpus 16 saxpy.py</td>
<td>legate -gpus 1 saxpy.py</td>
</tr>
</tbody>
</table>
FUTURE OF CONCURRENCY AND PARALLELISM IN HPC: STANDARD LANGUAGES

How did we get here?

ON-GOING LONG-TERM INVESTMENT

ISO committee participation from industry, academia and government labs.

Fruit born in 2020 was planted over the previous decade.

Focus on enhancing concurrency and parallelism for all.

Open collaboration between partners and competitors.

Past investments in directives enabled rapid progress.

MAJOR FEATURES

Memory Model Enhancements

C++14 Atomics Extensions

C++17 Parallel Algorithms

C++20 Concurrency Library

C++23 Multi-Dim. Array Abstractions

C++23 Extended Floating Point Types

C++23 Range Based Parallel Algorithms

C++2X Executors

C++2X Linear Algebra

Fortran 202X DO CONCURRENT Reduction
PARALLEL PROGRAMMING WITH ISO C++
HPC PROGRAMMING IN ISO C++

C++ Parallel Algorithms

- Introduced in C++17
- Parallel and vector concurrency via execution policies
  - `std::execution::par, std::execution::par_unseq, std::execution::seq`
- Several new algorithms in C++17 including
  - `std::for_each_n(POLICY, first, size, func)`
- Insert `std::execution::par` as first parameter when calling algorithms
- NVC++ (since 20.7): automatic CPU or GPU acceleration of C++17 parallel algorithms
  - Leverages CUDA Unified Memory

```cpp
std::sort(std::execution::par, c.begin(), c.end());
std::unique(std::execution::par, c.begin(), c.end());
```
HPC PROGRAMMING IN ISO C++

ISO is the place for portable concurrency and parallelism

**C++17 & C++20**
- Parallel Algorithms
  - In NVC++
  - Parallel and vector concurrency
- Forward Progress Guarantees
  - Extend the C++ execution model for accelerators
- Memory Model Clarifications
  - Extend the C++ memory model for accelerators
- Ranges
  - Simplifies iterating over a range of values
- Scalable Synchronization Library
  - Express thread synchronization that is portable and scalable across CPUs and accelerators
  - In libc++:
    - `std::atomic<T>`
    - `std::barrier`
    - `std::counting_semaphore`
    - `std::atomic<T>::wait/notify_*`
    - `std::atomic_ref<T>`

**C++23**
- `std::mdspan/mdarray`
  - HPC-oriented multi-dimensional array abstractions.
- Range-Based Parallel Algorithms
  - Improved multi-dimensional loops
- Extended Floating Point Types
  - First-class support for formats new and old: `std::float16_t/float64_t`

**Preview support coming to NVC++**

**And Beyond**
- Executors / Senders-Recievers
  - Simplify launching and managing parallel work across CPUs and accelerators
- Linear Algebra
  - C++ standard algorithms API to linear algebra
  - Maps to vendor optimized BLAS libraries

**Ranges**
- Simplifies iterating over a range of values

**Scalable Synchronization Library**
- Express thread synchronization that is portable and scalable across CPUs and accelerators
  - In libc++: `std::atomic<T>`
  - `std::barrier`
  - `std::counting_semaphore`
  - `std::atomic<T>::wait/notify_*`
  - `std::atomic_ref<T>`
C++17 PARALLEL ALGORITHMS

Lulesh Hydrodynamics Mini-app

- ~9000 lines of C++
- Parallel versions in MPI, OpenMP, OpenACC, CUDA, RAJA, Kokkos, ISO C++...
- Designed to stress compiler vectorization, parallel overheads, on-node parallelism

codesign.llnl.gov/lulesh
static inline void CalcHydroConstraintForElems(Domain &domain, Index_t length, Index_t *regElemlist, Real_t dvovmax, Real_t &dthydro) {
    #if _OPENMP
    const Index_t threads = omp_get_max_threads();
    Index_t hydro_elem_per_thread[threads];
    Index_t dthydro_per_thread[threads];
    #else
    Index_t threads = 1;
    Index_t hydro_elem_per_thread[1];
    Index_t dthydro_per_thread[1];
    #endif
    #pragma omp parallel firstprivate(length, dvovmax)
    {
        Real_t dthydro_tmp = dthydro;
        Index_t hydro_elem = -1;
        #if _OPENMP
        Index_t thread_num = omp_get_thread_num();
        #else
        Index_t thread_num = 0;
        #endif
        #pragma omp for
        for (Index_t i = 0; i < length; ++i) {
            Index_t indx = regElemlist[i];
            if (domain.vdov(indx) != Real_t(0.0)) {
                Real_t dtdev = dvovmax / (fabs(domain.vdov(indx)) + Real_t(1.e-20));
                if (dthydro_tmp > dtdev) {
                    dthydro_tmp = dtdev;
                    hydro_elem = indx;
                }
            }
        }
        dthydro_per_thread[thread_num] = dthydro_tmp;
        hydro_elem_per_thread[thread_num] = hydro_elem;
    } for (Index_t i = 1; i < threads; ++i) {
        if (dthydro_per_thread[i] < dthydro_per_thread[0]) {
            dthydro_per_thread[0] = dthydro_per_thread[i];
            hydro_elem_per_thread[0] = hydro_elem_per_thread[i];
        }
    } if (hydro_elem_per_thread[0] != -1) {
        dthydro = dthydro_per_thread[0];
    } return;
}
C++ STANDARD PARALLELISM

Lulesh Performance

- OpenMP on 64c EPYC 7742
- Standard C++ on 64c EPYC 7742
- Standard C++ on A100

Same ISO C++ Code
M-AIA

Multi-physics simulation framework developed at the Institute of Aerodynamics, RWTH Aachen University

- Hierarchical grids, complex moving geometries
- Adaptive meshing, load balancing
- Numerical methods: FV, DG, LBM, FEM, Level-Set, ...
- Physics: aeroacoustics, combustion, biomedical, ...
- Developed by ~20 PhDs (Mech. Eng.), ~500k LOC++
- **Programming model**: MPI + ISO C++ parallelism

![Decaying isotropic turbulence](image)

<table>
<thead>
<tr>
<th>Relative Speed-Up</th>
<th>0</th>
<th>1</th>
<th>1.025</th>
<th>8.74</th>
</tr>
</thead>
<tbody>
<tr>
<td>OpenMP @2x EPYC 7742</td>
<td>1</td>
<td></td>
<td></td>
<td>1.025</td>
</tr>
<tr>
<td>ISO C++ @2x EPYC 7742</td>
<td></td>
<td>1</td>
<td></td>
<td>8.74</td>
</tr>
<tr>
<td>ISO C++ @4x A100-40</td>
<td>1</td>
<td>8.74</td>
<td></td>
<td>1.025</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Number of GPUs: P [GPUs]</th>
<th>0</th>
<th>20</th>
<th>40</th>
<th>60</th>
<th>80</th>
<th>100</th>
<th>120</th>
</tr>
</thead>
<tbody>
<tr>
<td>Speedup SU(P) = ( \frac{T_{P_0}}{T_P} )</td>
<td>2</td>
<td>4</td>
<td>6</td>
<td>8</td>
<td>10</td>
<td>12</td>
<td>14</td>
</tr>
<tr>
<td>Strong efficiency SE(P, ( P_0 )) = ( \frac{T_{P_0}}{T_{P_0}^*} )</td>
<td>0.0</td>
<td>0.2</td>
<td>0.4</td>
<td>0.6</td>
<td>0.8</td>
<td>1.0</td>
<td>1.0</td>
</tr>
</tbody>
</table>
M-AIA REFACTORIZING

```cpp
#pragma omp parallel // OpenMP parallel region
{
    #pragma omp for // OpenMP for loop
    for (MInt i = 0; i < noCells; i++) { // Loop over all cells
        if (timeStep % ipow2[maxLevel_ - level[i] * distLevel]] == 0) { // Multi-grid loop
            const MInt distStartId = i * nDist; // More offsets for 1D accesses // Local offsets
            const MInt distStartId = i * distNeighbors;
            const MFloat* const distributionsStart = &distributions[distStartId];
            for (MInt j = 0; j < nDist - 1; j += 2) { // Unrolled loop distributions (factor 2)
                if (neighborId[I + distNeighbors * j] > -1) { // First unrolled iteration
                    const MInt n1StartId = neighborId[distStartId + j] * nDist;
                    oldDistributions[n1StartId + j] = distributionsStart[j]; // 1D access AoS format
                }
                if (neighborId[I + distNeighbors + j + 1] > -1) { // Second unrolled iteration
                    const MInt n2StartId = neighborId[distStartId + j] * nDist;
                    oldDistributions[n2StartId + j + 1] = distributionsStart[j + 1];
                }
            }
            oldDistributions[distStartId + lastId] = distributionsStart[lastId]; // Zero-th distribution
        }
    }
}
```

Single ISO C++ code that runs in parallel on CPU and GPU.
STLBM
Many-core Lattice Boltzmann with C++ Parallel Algorithms

- Framework for parallel lattice-Boltzmann simulations on multiple platforms, including many-core CPUs and GPUs

- Implemented with C++17 standard (Parallel Algorithms) to achieve parallel efficiency

- No language extensions, external libraries, vendor-specific code annotations, or pre-compilation steps

"We have with delight discovered the NVIDIA "stdpar" implementation of C++ Parallel Algorithms. ... We believe that the result produces state-of-the-art performance, is highly didactical, and introduces a paradigm shift in cross-platform CPU/GPU programming in the community."

-- Professor Jonas Latt, University of Geneva

https://gitlab.com/unigehpfs/stlbm
C++ PARALLEL ALGORITHM REFACCTORING

Simple loops may be replaced with a for_each_n or transform algorithm.

```cpp
#pragma omp parallel for firstprivate(qlc_monoq, \nqqc_monoq, monoq_limiter_mult, \nmonoq_max_slope, ptiny)
for ( Index_t i = 0 ; i < domain.regElemSize(r); ++i ) {
    ...
}
```

```cpp
std::for_each_n(
    std::execution::par, counting_iterator(0), \ndomain.regElemSize(r), \n[=, &domain](Index_t i) {
    ...
})
```

```cpp
std::transform(
    std::execution::par, counting_iterator(0), \ndomain.regElemSize(r), \n[=, &domain](Index_t i) {
    ...
})
```
C++ PARALLEL ALGORITHM REFACTORING

When possible, use the algorithm that fits your use case. E.g. a transform_reduce enables parallel execution with a reduction.

```cpp
#pragma acc parallel loop default(present) deviceptr(d_normals)
for (unsigned i = 0; i < N_PATHS; i++) {
    float s_curr = S0;
    for (unsigned n = 0; n < N_STEPS; n++) {
        s_curr +=
            tmp1 * s_curr + sigma * s_curr * tmp3 *
            d_normals[i + n * N_PATHS];
        running_average += (s_curr - running_average) / (n + 1.0);
        if (running_average <= B) {
            break;
        }
    }
    payoff = (running_average > K ?
        running_average - K : 0.f);
    d_s[i] = tmp2 * payoff;
}

#pragma acc parallel loop default(present) reduction(+: sum)
for (unsigned i = 0; i < N_PATHS; ++i) {
    sum += (double)d_s[i];
}
```

```cpp
sum = std::transform_reduce(
    std::execution::par, counting_iterator(0),
    counting_iterator(N_PATHS),
    0.0, std::plus<>(), [=](int i) {
        double running_average = 0.0;
        float s_curr = S0;
        for (unsigned n = 0; n < N_STEPS; n++) {
            s_curr +=
                tmp1 * s_curr + sigma * s_curr * tmp3 *
                d_normals[i + n * N_PATHS];
            running_average += (s_curr - running_average) / (n + 1.0);
            if (running_average <= B) {
                break;
            }
        }
        payoff = (running_average > K ?
            running_average - K : 0.f);
        return (tmp2 * payoff);
    });
```
USING THE RIGHT ALGORITHM

Speedup - Higher is Better

- Xeon Gold 6148 (40 cores)
- OpenACC
- CUDA
- C++ (T+R)
- C++ (TR)
USING C++ RANGES

Simplify iterating over a range of values

- Ranges provides a standardized way to specify the range of values over which to iterate.
- The iota view is a simple way to declare the iteration space of the loop you have converted into a parallel algorithm.
- To use iota you must have GCC10 or newer installed and use specify `-std=c++20` in your `nvc++` options.

```cpp
auto v = std::ranges::views::iota(0, N*M);
std::for_each(
    std::execution::par_unseq,
    begin(v), end(v),
    [...] (auto idx) { ... });
```

*Prior to nvc++ 22.2 or if GCC10 is not available, the Thrust counting_iterator should be used in place of iota.*
USING C++ RANGES
Simplify iterating over a range of values

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    begin(v), end(v),
    [...] (auto idx) { ... });
```

- C++23 is expected to add the cartesian_product view, which expands ranges to support multi-dimension ranges.

```cpp
auto v = std::ranges::views::cartesian_product(
    stdv::iota(0, N),
    stdv::iota(0, M));
std::for_each(std::execution::par_unseq,
    begin(v), end(v),
    [=] (auto idx) {
        auto [i,j] = idx;
        ... 
    });
```

*Prior to nvc++ 22.2 or if GCC10 is not available, the Thrust counting_iterator should be used in place of iota.*
WHAT’S COMING IN C++: MDSPAN

C++23 brings mdspan, a standardized way to access multi-dimensional data, which composes well with ranges.

std::span A{input, N * M};
std::span B{output, M * N};

auto v = std::ranges::views::cartesian_product(
    std::ranges::views::iota(0, N),
    std::ranges::views::iota(0, M));

std::for_each(std::execution::par_unseq,
    begin(v), end(v),
    [=] (auto idx) {
        auto [i, j] = idx;
        B[i + j * N] = A[i * M + j];
    });

std::mdspan A{input, N, M};
std::mdspan B{output, M, N};

auto v = std::ranges::views::cartesian_product(
    std::ranges::views::iota(0, N),
    std::ranges::views::iota(0, M));

std::for_each(ex::par_unseq,
    begin(v), end(v),
    [=] (auto idx) {
        auto [i, j] = idx;
        B[i, j] = A[i, j];
    });
LIBCU++: A GPU-ENABLED STL

<table>
<thead>
<tr>
<th>Host Compiler’s Standard Library</th>
</tr>
</thead>
<tbody>
<tr>
<td>#include &lt;…&gt;</td>
</tr>
<tr>
<td>std::</td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td>#include &lt;cuda/std/…&gt;</td>
</tr>
<tr>
<td>cuda::std::</td>
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<tr>
<td></td>
</tr>
<tr>
<td>#include &lt;cuda/…&gt;</td>
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<tr>
<td>cuda::</td>
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</table>

libcu++ does not interfere with or replace your host Standard Library.
<table>
<thead>
<tr>
<th>Version</th>
<th>CUDA Version</th>
<th>Features</th>
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<tbody>
<tr>
<td>1.0.0</td>
<td>10.2</td>
<td>atomic&lt;T&gt; (SM60+) Type Traits</td>
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<tr>
<td>1.1.0</td>
<td>11.0</td>
<td>atomic&lt;T&gt;::wait/notify (SM70+) barrier (SM70+) latch (SM70+)</td>
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<td></td>
<td>*_semaphore (SM70+) cudaMemcpy_async (SM70+) chrono:: Clocks &amp; Durations</td>
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<td></td>
<td>ratio&lt;Num, Denom&gt;</td>
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<tr>
<td>1.2.0</td>
<td>11.1</td>
<td>cuda::pipeline (SM80+)</td>
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<tr>
<td>1.3.0</td>
<td>11.2</td>
<td>tuple&lt;T0, T1, ...&gt;</td>
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<td>1.4.1</td>
<td>11.3</td>
<td>complex byte chronon:: Dates &amp; Calendars</td>
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<td>2.0.0</td>
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<td>atomic_ref&lt;T&gt; (SM60+) Memory Resources &amp; Allocators cuda::stream_view</td>
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<td>Future</td>
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<td>Executors Range Factories &amp; Adaptors Parallel Range Algorithms</td>
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<td>Parallel Linear Algebra Algorithms mdspan&lt;T, ...&gt;</td>
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</tbody>
</table>
C++ PARALLEL ALGORITHMS HINTS

No **__device__** keyword needed for functions called in parallel algorithm, including lambdas. Use heap memory, not stack.

- `std::array<int, 1024> a = ...;` //uses stack memory, will not work in device code.
- `std::vector<int> v = ...;` //uses heap memory, OK

For lambdas, capture by value, not reference; especially scalars.

Use Random Access Iterators.

- `std::ranges::views::iota` - When possible
- `thrust::counting_iterator` - When iota is not an option

No exceptions in GPU code.
STANDARD PARALLELISM RESOURCES

NVIDIA Developer Blogs
• Developing Accelerated Code with Standard Language Parallelism
• Accelerating Standard C++ with GPUs
• Accelerating Fortran DO CONCURRENT
• Bringing Tensor Cores to Standard Fortran
• Accelerating Python on GPUs with NVC++ and Cython

Open-source codes
• LULESH - https://github.com/LLNL/LULESH
• STLBM - https://gitlab.com/unigehpfs/stlbm
• MiniWeather - https://github.com/mrnorman/miniWeather/
• POT3D - https://github.com/predsci/POT3D

C++ algorithms and execution policy reference
• https://en.cppreference.com/w/cpp/algorithm

NVIDIA HPC Compilers Forum
• https://forums.developer.nvidia.com/c/accelerated-computing/hpc-compilers

Legate and cuNumeric Resources
• https://github.com/nv-legate
Relevant GTC Spring 2022 Sessions

For more information on these topics

• No More Porting: Coding for GPUs with Standard C++, Fortran, and Python [S41496]
• A Deep Dive into the Latest HPC Software [S41494]
• C++ Standard Parallelism [S41960]
• Future of Standard and CUDA C++ [S41961]
• Shifting through the Gears of GPU Programming: Understanding Performance and Portability Trade-offs [S41620]
• From Directives to DO CONCURRENT: A Case Study in Standard Parallelism [S41318]