Today’s Pipeline

Morning Session Overview

• Introduction to Parallel Programming Concepts - 09:00 am PDT
• Understanding Supercomputer Architecture
• Basic Parallelism & MPI
• BREAK - 10:30 a.m. - 10:45 a.m. PDT
• MPI Collectives
• Q&A
• LUNCH - 12:00 p.m. - 01:00 p.m. PDT

Please refer to Event Web Page for Specific Times
Today’s Pipeline
Afternoon Session Preview (after Lunch)

• Introduction to OpenMP: 01:00 p.m. PDT
• Understanding OpenMP + Hybrid OpenMP Concepts
• BREAK : 02:45 p.m. - 03:00 p.m. PDT
• Interactive Exercises & Hands-On Practice
• ADJOURN: 04:00 p.m. PDT

Please refer to Event Web Page for More Detailed Session Times
Some Logistics

● In-person attendees please also join Zoom for full participation
● Please change your name in Zoom session
  ○ to: first_name last_name
  ○ Click “Participants”, then “More” next to your name to rename
● Click the CC button to toggle captions and View Full Transcript
● Session is being recorded
● Users are muted upon joining Zoom
  ○ Feel free to unmute and ask questions or ask in GDoc below
● GDoc is used for Q&A (instead of Zoom chat)
  ○ https://tinyurl.com/4fvkzeud
● Please answer a short survey afterward
  ○ https://tinyurl.com/562bvv62
Some Logistics

● Slides and videos will be available on NERSC Training Event page and LBNL Computing Sciences Summer Program page

● You’re encouraged to register for OpenMP Monthly Training Series, May-Oct 2024
  ○ Session 3 of 7 on July 8. Can catch up Session 1 and 2 via videos and exercises

● Introduction to CUDA Programming Training (coming soon)
Hands-on Exercises on Perlmutter

ssh <user>@perlmutter.nersc.gov, land on login node:

- % cd $SCRATCH
- % git clone https://github.com/NERSC/crash-course-supercomputing.git
  ◦ Downloads all exercises (and answers!)

References
  ◦ Running Jobs: https://docs.nersc.gov/jobs/
  ◦ Interactive Jobs: https://docs.nersc.gov/jobs/examples/#interactive
Using Perlmutter Compute Node Reservations

- Existing NERSC users (at time of registration) have been added to “ntrain3” project
- Apply for a training account if no NERSC account at time of registration or if MFA for login is not setup yet
  - [https://iris.nersc.gov/train](https://iris.nersc.gov/train), and use the 4-letter code bk8X
  - Training accounts valid until July 10
- Perlmutter node reservations: 10:30 am - 4:30 pm PDT today
  - `--reservation=crash_course -A ntrain3 -C cpu` for sbatch or salloc sessions
  - No need to use `--reservation` or `-A` when outside of the reservation hours
NERSC Code of Conduct

As NERSC collaborators, we are all bound by the Code of Conduct:

- Team Science
- Service
- Trust
- Innovation
- Respect

We agree to **work together professionally and productively** towards our shared goals while respecting each other’s differences and ideas.

We should all feel free to speak up to maintain this environment and remember there are resources available to **report violations** to foster an inclusive, collaborative environment. Email [nersc-training@lbl.gov](mailto:nersc-training@lbl.gov) for any concerns.

[https://www.nersc.gov/nersc-code-of-conduct](https://www.nersc.gov/nersc-code-of-conduct) or search “NERSC Code of Conduct”
Introduction to Parallel Programming Concepts
I. PARALLELISM

“Parallel Worlds” by alobshbennett from http://www.flickr.com/photos/alobshbennett/3209564747/sizes/l/in/photostream/
I. Parallelism

- Concepts of Parallelization
- Serial vs. Parallel
- Parallelization strategies
What is Parallelism?

● Generally Speaking:
  ○ Parallelism lets us work smarter, not harder, by simultaneously tackling multiple tasks.
  ○ How?
    ■ the concept of dividing a task or problem into smaller subtasks that can be executed simultaneously.
  ○ Benefit?
    ■ Work can get done more efficiently, thus quicker!
Parallelization Concepts

This concept applies to both everyday activities like preparing dinner:

- Imagine preparing a lasagna dinner with multiple tasks involved.
- Some tasks, such as making the sauce, assembling the lasagna, and baking it, can be performed independently and concurrently.
- These tasks do not depend on each other's completion, allowing for parallel execution.
Serial vs. Parallel

- **Serial**: tasks must be performed in sequence
- **Parallel**: tasks can be performed independently in any order

Serial vs. Parallel

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Serial vs. Parallel

- **Serial**: tasks must be performed in sequence
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"Unlocking the Power of Parallel Computing in Julia Programming" by Ombar Karacharekar
Serial vs. Parallel: Example

- Preparing Lasagna Dinner
Serial vs. Parallel: Example

- Preparing Lasagna Dinner

  **SERIAL TASKS**
  - Making the sauce
  - Assembling the lasagna
  - Baking the lasagna
  - Washing lettuce
  - Cutting vegetables
  - Assembling the salad
Serial vs. Parallel: Example

- Preparing Lasagna Dinner

**SERIAL TASKS**
- Making the sauce
- Assembling the lasagna
- Baking the lasagna
- Washing lettuce
- Cutting vegetables
- Assembling the salad

**PARALLEL TASKS**
- Making the lasagna
- Making the salad
- Setting the table
Serial vs. Parallel: Graph

Make Sauce -> Cook Noodles
  Grate Cheese -> Assemble -> Bake -> Lasagna
  Wash lettuce -> Cut lettuce
  Wash veg -> Cut veg -> Assemble
  Salad

Prep butter -> Cut bread -> Spread -> Bake -> Garlic Bread

Serve Dinner

4:15 4:30 5:00 5:30 6:00
Serial vs. Parallel: Graph

Synchronization Points

Make Sauce
Cook Noodles
Grate Cheese
Assemble
Bake
Lasagna
Wash lettuce
Cut lettuce
Assemble
Set Table
Serve Dinner

Wash veg
Cut veg

Prep butter
Cut bread
Spread
Bake
Garlic Bread
Serial vs. Parallel: Graph
Serial vs. Parallel: Example

- Could have several chefs, each performing one parallel task
- This is concept behind parallel computing
Discussion: Jigsaw Puzzle*

- Suppose we want to do a large, $N$-piece jigsaw puzzle (e.g., $N = 10,000$ pieces)
- Time for one person to complete puzzle: $T$ hours
- How can we decrease walltime to completion?
Discussion: Jigsaw Puzzle

- Impact of having multiple people at the table
  - Walltime to completion
  - Communication
  - Resource contention

- Let number of people = $p$
  - Think about what happens when $p = 1, 2, 4, \ldots 5000$
Discussion: Jigsaw Puzzle

Alternate setup: $p$ people, each at separate table with $N/p$ pieces each

- What is the impact on
  - Walltime to completion
  - Communication
  - Resource contention?
Discussion: Jigsaw Puzzle

Alternate setup: divide puzzle by features, each person works on one, e.g., mountain, sky, stream, tree, meadow, etc.

- What is the impact on
  - Walltime to completion
  - Communication
  - Resource contention?
Parallel Algorithm Design: PCAM

- **Partition**
  - Decompose problem into fine-grained tasks to maximize potential parallelism

- **Communication**
  - Determine communication pattern among tasks

- **Agglomeration**
  - Combine into coarser-grained tasks, if necessary, to reduce communication requirements or other costs

- **Mapping**
  - Assign tasks to processors, subject to tradeoff between communication cost and concurrency

(from Heath: *Parallel Numerical Algorithms*)
II. ARCHITECTURE

II. Supercomputer Architecture

- What is a supercomputer?
- Conceptual overview of architecture

Cray 1 (1976)

IBM Blue Gene (2005)

Cray XT5 (2009)

HPE-Cray Shasta Architecture (2021)

Future HPC Architecture (2029-???)
What Is a Supercomputer?

“The biggest, fastest computer right this minute.” – Henry Neeman

Tips on Identifying a Supercomputer

● Generally, at least 100 times more powerful than PC
● This field of study known as supercomputing, high-performance computing (HPC), or scientific computing
● Scientists utilize supercomputers to solve complex problems.
   • Really hard problems need really LARGE (super)computers
Supercomputing Architectures

- **Cluster Architecture**
  - Connects multiple standalone computers to work together as a single system. Provides a cost-effective solution for scalable computing power.

- **Symmetric Multiprocessing (SMP)**
  - Involves multiple processors sharing a single memory space. Suitable for tasks requiring frequent communication between processors.

- **Massively Parallel Processing (MPP)**
  - Consists of many processors with their own memory. Effective for tasks that can be divided into independent subtasks.
SMP Architecture

● SMP stands for Symmetric Multiprocessing architecture
  ○ commonly used in supercomputers, servers, and high-performance computing environments.
  ○ all processors have equal access to memory and input/output devices.
    ■ Massive memory, shared by multiple processors
SMP Architecture

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    - Massive memory, shared by multiple processors
- Any processor can work on any task, no matter its location in memory
  - Ideal for parallelization of sums, loops, etc.
SMP Architecture

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  - all processors have equal access to memory and input/output devices.
    - Massive memory, shared by multiple processors
- Any processor can work on any task, no matter its location in memory
  - Ideal for parallelization of sums, loops, etc.
- SMP systems and architectures allow for better load balancing and resource utilization across multiple processors.
Cluster Architecture

- CPUs on racks, do computations (fast)
- Communicate through networked connections (slow)
- Want to write programs that divide computations evenly but minimize communication
State-of-the-Art Architectures

- Today: hybrid architectures very common
  - Multiple \{16, 24, 32, 64, 68, 128\}-core nodes, connected to other nodes by (slow) interconnect
  - Cores in node share memory (like small SMP machines)
  - Machine appears to follow cluster architecture (with multi-core nodes rather than single processors)
  - To take advantage of all parallelism, use MPI (cluster) and OpenMP (SMP) hybrid programming
NERSC Systems Ecosystem

HPE Slingshot 11 interconnect
- 4 NICs/GPU node,
- 1 NIC/CPU node

1,792 GPU-accelerated nodes
- 4 NVIDIA A100 GPUs + 1 AMD “Milan” CPU
- 448 TB (CPU) + 320 TB (GPU) memory

3,072 CPU-only nodes
- 2 AMD “Milan” CPUs
- 1,536 TB CPU memory

35 PB All-Flash Scratch

>5 TB/s

50 GB/s

1.6 TB/s

5 GB/s

100 GB/s

2 x 400 Gb/s

2 x 100 Gb/s

Off-Platform Storage
- HPSS Tape Archive ~300 PB
- Common File System 130 PB
- /home 450 TB

DTNs, Gateways

Edge services

Ethernet
- Science Friendly
- Security
- Production Monitoring
- Power Efficiency
- LAN

Experimental Facility

ASCR Facility

Home Institution

Cloud

Edge

#8, 93.8PF Peak

HPE Slingshot 11 interconnect

1,792 GPU-accelerated nodes

3,072 CPU-only nodes

ESnet

Spin

NERSC

BERKELEY LAB

Office of Science

U.S. DEPARTMENT OF ENERGY

Bringing Science Solutions to the World
Perlmutter: Optimized for Science

- First phase arrived 2021; second phase in 2022; final acceptance in 2023
- GPU-accelerated and CPU-only nodes
- HPE Cray Slingshot high-performance network
- 35 PB all-flash scratch file system

**GPU-Accelerated Nodes**
- 1,536 GPU-accelerated nodes
- 1 AMD “Milan” CPU + 4 NVIDIA A100 GPUs per node
- 256 GB CPU memory and 40 GB GPU high BW memory

**CPU-Only Nodes**
- 3,072 CPU only nodes
- 2 AMD “Milan” CPUs per node
- 512 GB memory per node
HPC Systems: Perlmutter

**GPU nodes:**
- Immense compute power from GPUs
- Large jobs using many GPUs encouraged
- Great for codes that can exploit GPU compute power

**CPU nodes:**
- Powerful CPUs (but only 10% of GPU compute power)
- Equivalent in compute power to all of Cori (former system)
- More like a traditional cluster
- Great for throughput jobs
File Systems

- Global File Systems:
  - Home
  - Community (CFS)
- Local File Systems:
  - Scratch
- Long-term Storage System:
  - HPSS
NERSC Architectures Through the Years

- **Seaborg (2003-2006):** An IBM SP system with 6,656 Power3 processors, each with 375 MHz. It used shared memory and IBM's high-performance switch (HPS) interconnect. The system delivered 10 teraflops.

- **Jacquard (2004-2007):** A Linux cluster with 712 nodes, each containing dual Intel Xeon processors (3.06 GHz). It had 4 GB of memory per node and used Myrinet interconnects, providing 9.2 teraflops.

- **Bassi (2005-2009):** An IBM Power5+ system with 888 processors (1.9 GHz). It had 8 GB of memory per processor and used IBM's Federation switch interconnect, achieving 3.6 teraflops.
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NERSC Architectures Through the Years

- **Franklin (2008-2012):** A Cray XT4 system with 38,288 AMD Opteron cores (2.3 GHz). It used DDR2 memory and Cray's SeaStar2+ interconnect, delivering 352 teraflops.

- **Hopper (2010-2015):** A Cray XE6 system with 153,216 AMD Magny-Cours cores (2.1 GHz). It had 2 GB of memory per core and used Cray's Gemini interconnect, providing 1.28 petaflops.
NERSC Architectures Through the Years

- **Edison (2013-2019):** A Cray XC30 system with 133,824 Intel Ivy Bridge cores (2.4 GHz). It used DDR3 memory and Cray's Aries interconnect, providing 2.57 petaflops.

- **Cori (2016-2023):** A Cray XC40 system with 622,336 cores, including Intel Haswell and Knights Landing processors. It features DDR4 memory and Cray's Aries interconnect, delivering 30 petaflops.
State-of-the-Art Architectures

● Hybrid CPU/GPGPU architectures also very common
  ○ Nodes consist of one (or more) multicore CPU + one (or more) GPU
  ○ Heavy computations offloaded to GPGPUs
  ○ Separate memory for CPU and GPU
  ○ Complicated programming paradigm, outside the scope of today’s training
    ■ Often use CUDA to directly program GPU offload portions of code
    ■ Alternatives: standards-based directives, OpenACC or OpenMP offloading; programming environments such as Kokkos or Raja
Introduction to Message Passing Interface (MPI)
III. BASIC MPI

“MPI Adventure” by Stefan Jürgensen, from http://www.flickr.com/photos/94039982@N00/6177616380/sizes/l/in/photostream/
III. Basic MPI

- Introduction to MPI
- Parallel programming concepts
- The Six Necessary MPI Commands
- Example program
Introduction to Message Passing Interface (MPI)

- The Message Passing Interface (MPI) is a standardized and portable message-passing system designed to function on a wide variety of parallel computing architectures.
  - Standards have evolved over the years
  - Accommodate advances in hardware and programming practices.
- Industry standard for parallel programming
  - 200+ page document
Introduction to MPI

- MPI implemented by many vendors; open source implementations available too
  - Cray, IBM, HPE vendor implementations
  - MPICH, OpenMPI (open source)
- MPI function library is used in writing C, C++, or Fortran programs in HPC
Introduction to MPI

- **MPI-1 (1994 finalized and released)**
  - Provided basic point-to-point and collective communication functionalities.
- **MPI-2 (1996 release)**
  - Introduced several significant extensions, including dynamic process management, parallel I/O, and one-sided communications.
- **MPI-3 (2012 release)**
  - Further enhanced the capabilities of MPI with non-blocking collective operations, improved one-sided communications, and better support for shared memory programming. Added support for the Fortran 2008 standard.
- **MPI-4.0 (June 2021 release)**
  - Includes several enhancements and new features
MPI 4.0 Standard

● Partitioned Communications
  ○ Introduces a new communication mechanism designed for GPUs & other devices where data can be partitioned into parts that can be processed independently.

● Persistent Collectives
  ○ Extends the existing persistent communication interface to include collective operations, providing optimizations for frequently repeated operations.

● Fault Tolerance
  ○ Adds new mechanisms to handle failures in hardware and processes more effectively.

● Enhancements for Hybrid Programming
  ○ Improvements in the handling of shared memory, which is crucial for systems combining multiple levels of parallelism.
Parallelization Concepts

- Two primary programming paradigms:
  - **SPMD** (single program, multiple data)
  - **MPMD** (multiple programs, multiple data)
- MPI can be used for either paradigm
SPMD vs. MPMD

- SPMD: Write single program that will perform same operation on multiple sets of data
  - Multiple chefs baking many lasagnas
  - Rendering different frames of movie
- MPMD: Write different programs to perform different operations on multiple sets of data
  - Multiple chefs preparing four-course dinner
  - Rendering different parts of movie frame
- Can also write hybrid program in which some processes perform same task
The Six Necessary MPI Commands

```c
int MPI_Init(int *argc, char **argv)
int MPI_Finalize(void)
int MPI_Comm_size(MPI_Comm comm, int *size)
int MPI_Comm_rank(MPI_Comm comm, int *rank)
int MPI_Send(void *buf, int count, MPI_Datatype datatype, int dest, int tag, MPI_Comm comm)
int MPI_Recv(void *buf, int count, MPI_Datatype datatype, int source, int tag, MPI_Comm comm, MPI_Status *status)
```
Initiation and Termination

- **MPI_Init(int *argc, char **argv)** initiates MPI
  - Place in body of code after variable declarations and before any MPI commands
  - Initializes the MPI execution environment. Must be called before any other MPI function.

- **MPI_Finalize(void)** shuts down MPI
  - Place near end of code, after last MPI command
  - Terminates the MPI execution environment. No MPI function can be called after this except *MPI_Init* and *MPI_Finalize*. 
Message Passing Interface

Message passing interface (MPI)

MP_{COMM\_WORLD}

Process ID (rank):

0
1
2
3
4
5

CLUSTER

node 1
CPU 0
CPU 1

node 2
CPU 0

node 3
CPU 0
CPU 1

node 4
CPU 0
Environmental Inquiry

● **MPI_Comm_size(MPI_Comm comm, int *size)**
  ○ Determines the size of the group associated with a communicator
  ○ Allows flexibility in number of processes used in program

● **MPI_Comm_rank(MPI_Comm comm, int *rank)**
  ○ Find out identifier of current process
  ○ Determines the rank of the calling process in the communicator.
  ○ $0 \leq \text{rank} \leq \text{size}-1$
Message Passing: Send

- **MPI_Send**: Sends a message from this MPI process to another.
  - `MPI_Send(const void *buf, int count, MPI_Datatype datatype, int dest, int tag, MPI_Comm comm)`
    - Performs a send from this MPI process to another.
    - Sends a message of length `count` items and datatype `datatype` contained in `buf` with tag `tag` to process number `dest` in communicator `comm`.
    - With MPI 4.0, the `buf` parameter is now marked as `const` to indicate that the buffer should not be modified during the send operation.
    - E.g., `MPI_Send(&x, 1, MPI_DOUBLE, manager, me, MPI_COMM_WORLD)`. 

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Message Passing: Receive

- `MPI_Recv(void *buf, int count, MPI_Datatype datatype, int source, int tag, MPI_Comm comm, MPI_Status *status)`
  - Performs a blocking receive of data from another process.
  - Receive message of length `count` items and datatype `datatype` with tag `tag` in buffer `buf` from process number `source` in communicator `comm`, and record status `status`
  - E.g. `MPI_Recv(&x, 1, MPI_DOUBLE, source, source, MPI_COMM_WORLD, &status)`
Message Passing

- **WARNING!** Standard receive function is blocking
- **MPIRecv** returns only after receive buffer contains requested message
- **MPI_Send** *may or may not block* until message received (usually blocks)
  - Depends on implementation standard as the blocking behavior of **MPI_Send** depends on the size of the message and the underlying system's buffering capabilities.
  - **MPI_Send** will block until it can safely copy the message to the system's buffer, which might not necessarily mean the message has been received by the destination process.
  - For small messages, it may return quickly if the system can buffer them, but for larger messages, it may block until the receiving process calls **MPIRecv**.
- Must watch out for deadlock
Warning: DEADLOCKS

Must Watch Out for DEADLOCKS

- Deadlocks can occur in MPI programs if send and receive operations are not properly ordered
  - more generally, if processes are waiting on each other indefinitely.
- To avoid deadlocks, ensure that the send/receive operations are properly matched
  - And consider using non-blocking communication functions (MPI_Isend, MPI_Irecv) or changing the program's structure to avoid circular dependencies.
Deadlocking Example (Always)

```c
#include <mpi.h>
#include <stdio.h>

int main(int argc, char **argv) {
    int me, np, q, sendto;
    MPI_Status status;
    MPI_Init(&argc, &argv);
    MPI_Comm_size(MPI_COMM_WORLD, &np);
    MPI_Comm_rank(MPI_COMM_WORLD, &me);
    if (np%2==1) return 0;
    if (me%2==1) {sendto = me-1; }
    else {sendto = me+1; }
    MPI_Recv(&q, 1, MPI_INT, sendto, sendto, MPI_COMM_WORLD, &status);
    MPI_Send(&me, 1, MPI_INT, sendto, me, MPI_COMM_WORLD);
    printf("Sent %d to proc %d, received %d from proc %d\n", me, sendto, q, sendto);
    MPI_Finalize();
    return 0;
}
```
#include <mpi.h>
#include <stdio.h>

int main(int argc, char **argv) {
    int me, np, q, sendto;
    MPI_Status status;
    MPI_Init(&argc, &argv);
    MPI_Comm_size(MPI_COMM_WORLD, &np);
    MPI_Comm_rank(MPI_COMM_WORLD, &me);
    if (np%2==1) return 0;
    if (me%2==1) {sendto = me-1;}
    else {sendto = me+1;}
    MPI_Send(&me, 1, MPI_INT, sendto, me, MPI_COMM_WORLD);
    MPI_Recv(&q, 1, MPI_INT, sendto, sendto, MPI_COMM_WORLD, &status);
    printf("Sent %d to proc %d, received %d from proc %d\n", me, sendto, q, sendto);
    MPI_Finalize();
    return 0;
}
#include <mpi.h>
#include <stdio.h>

int main(int argc, char **argv) {
    int me, np, q, sendto;
    MPI_Status status;
    MPI_Init(&argc, &argv);
    MPI_Comm_size(MPI_COMM_WORLD, &np);
    MPI_Comm_rank(MPI_COMM_WORLD, &me);
    if (np%2==1) return 0;
    if (me%2==1) {sendto = me-1;}
    else {sendto = me+1;}
    if (me%2 == 0) {
        MPI_Send(&me, 1, MPI_INT, sendto, me, MPI_COMM_WORLD);
        MPI_Recv(&q, 1, MPI_INT, sendto, sendto, MPI_COMM_WORLD, &status);
    } else {
        MPI_Recv(&q, 1, MPI_INT, sendto, sendto, MPI_COMM_WORLD, &status);
        MPI_Send(&me, 1, MPI_INT, sendto, me, MPI_COMM_WORLD);
    }
    printf("Sent %d to proc %d, received %d from proc %d\n", me, sendto, q, sendto);
    MPI_Finalize();
    return 0;
}
Explanation: Always Deadlocking Example

- Logically incorrect
- Deadlock caused by blocking `MPI_Recvs`
- All processes wait for corresponding `MPI_Sends` to begin, which never happens
Explanation: Sometimes Deadlocking Example

- Logically correct
- Deadlock could be caused by MPI_Send competing for buffer space
- Unsafe because depends on system resources

Solutions:
- Reorder sends and receives, like safe example, having evens send first and odds send second
- Use non-blocking sends and receives or other advanced functions from MPI library (see MPI standard for details)
INTERLUDE 1: COMPUTING PI IN PARALLEL

“Pi of Pi” by spellbee2, from http://www.flickr.com/photos/49825386@N08/7253578340/
sizes/l/in/photostream/
Interlude 1: Computing $\pi$ in Parallel

- Project Description
- Serial Code
- Parallelization Strategies
- Your Assignment
Project Description

- We want to compute $\pi$
- One method: method of darts*
- Ratio of area of square to area of inscribed circle proportional to $\pi$

* This is a TERRIBLE way to compute pi! Don’t do this in real life!!!! (See Appendix 1 for better ways)

Method of Darts

- Imagine dartboard with circle of radius $R$ inscribed in square
- Area of circle $= \pi R^2$
- Area of square $= (2R)^2 = 4R^2$
- Area of circle $\frac{\pi R^2}{4R^2} = \frac{\pi}{4}$

"Dartboard" by AndyRobertsPhotos, from http://www.flickr.com/photos/aroberts/2907670014/sizes/o/in/photostream/
Method of Darts

● Ratio of areas proportional to $\pi$

● How to find areas?
  ○ Suppose we threw darts (completely randomly) at dartboard
  ○ Count # darts landing in circle & total # darts landing in square
  ○ Ratio of these numbers gives approximation to ratio of areas
  ○ Quality of approximation increases with # darts thrown
Method of Darts

\[ \pi = 4 \times \frac{\text{# darts inside circle}}{\text{# darts thrown}} \]

Method of Darts cake in celebration of Pi Day 2009, Rebecca Hartman-Baker
Method of Darts

● Okay, Rebecca and Charles, but how in the world do we simulate this experiment on a computer?
● Decide on length $R$
● Generate pairs of random numbers $(x, y)$ s.t.

$$-R \leq (x, y) \leq R$$

● If $(x, y)$ within circle (i.e., if $(x^2+y^2) \leq R^2$) add one to tally for inside circle
● Lastly, find ratio
Serial Code (darts.c)

```c
#include "lcgenerator.h"
static long num_trials = 1000000;

int main() {
    long Ncirc = 0;
    double pi, x, y;
    double r = 1.0; /* radius of circle */
    double r2 = r*r;

    for (long i = 0; i < num_trials; i++) {
        x = r*lcgrandom();
        y = r*lcgrandom();
        if ((x*x + y*y) <= r2)
            Ncirc++;
    }

    pi = 4.0 * ((double)Ncirc)/((double)num_trials);
    printf("\n For %ld trials, pi = %f\n", num_trials, pi);

    return 0;
}
```
// Random number generator -- and not a very good one, either!

static long MULTIPLIER = 1366;
static long ADDEND = 150889;
static long PMOD = 714025;
long random_last = 0;

// This is not a thread-safe random number generator

double lcgrandom() {
    long random_next;
    random_next = (MULTIPLIER * random_last + ADDEND) % PMOD;
    random_last = random_next;

    return ((double)random_next/(double)PMOD);
}
Serial Code (darts.f90) (1)

! First, the pseudorandom number generator

real function lcgrandom()
    integer*8, parameter :: MULTIPLIER = 1366
    integer*8, parameter :: ADDEND = 150889
    integer*8, parameter :: PMOD = 714025
    integer*8, save :: random_last = 0

    integer*8 :: random_next = 0
    random_next = mod((MULTIPLIER * random_last + ADDEND), PMOD)
    random_last = random_next
    lcgrandom = (1.0*random_next)/PMOD
    return
end
! Now, we compute pi

program darts
    implicit none
    integer*8 :: num_trials = 1000000, i = 0, Ncirc = 0
    real :: pi = 0.0, x = 0.0, y = 0.0, r = 1.0
    real :: r2 = 0.0
    real :: lcgrandom
    r2 = r*r

    do i = 1, num_trials
        x = r*lcgrandom()
        y = r*lcgrandom()
        if ((x*x + y*y) .le. r2) then
            Ncirc = Ncirc+1
        end if
    end do

    pi = 4.0*((1.0*Ncirc)/(1.0*num_trials))
    print*, ' For ', num_trials, ' trials, pi = ', pi
end
Parallelization Strategies

- What tasks independent of each other?
- What tasks must be performed sequentially?
- Using PCAM parallel algorithm design strategy
Partition

“Decompose problem into fine-grained tasks to maximize potential parallelism”

- Finest grained task: throw of one dart
- Each throw independent of all others
- If we had huge computer, could assign one throw to each processor
Communication

“Determine communication pattern among tasks”

- Each processor throws dart(s) then sends results back to manager process
Agglomeration

“Combine into coarser-grained tasks, if necessary, to reduce communication requirements or other costs”

- To get good value of $\pi$, must use millions of darts
- We don’t have millions of processors available
- Furthermore, communication between manager and millions of worker processors would be very expensive
- Solution: divide up number of dart throws evenly between processors, so each processor does a share of work
Mapping

“Assign tasks to processors, subject to tradeoff between communication cost and concurrency”

- Assign role of “manager” to processor 0
- Processor 0 will receive tallies from all the other processors, and will compute final value of $\pi$
- Every processor, including manager, will perform equal share of dart throws
Your Assignment

- Clone the whole assignment (including answers!) to Perlmutter from the repository with: `git clone https://github.com/NERSC/crash-course-supercomputing.git`
- Copy `darts.c/lcgenerator.h` or `darts.f90` (your choice) from `crash-course-supercomputing/darts-suite/{c,fortran}`
- Parallelize the code using the 6 basic MPI commands
- Rename your new MPI code `darts-mpi.c` or `darts-mpi.f90`
Introduction to MPI Collectives
IV. MPI COLLECTIVES

MPI Collectives

- Communication involving group of processes
- Collective operations
  - Broadcast
  - Gather
  - Scatter
  - Reduce
  - All-
  - Barrier
Broadcast

- Perhaps one message needs to be sent from manager to all worker processes
- Could send individual messages
- Instead, use broadcast – more efficient, faster
- `int MPI_Bcast(void* buffer, int count, MPI_Datatype datatype, int root, MPI_Comm comm)`
Gather

- All processes need to send same (similar) message to manager
- Could implement with each process calling `MPI_Send(…)` and manager looping through `MPI_Recv(…)`
- Instead, use gather operation – more efficient, faster
- Messages concatenated in rank order
- `int MPI_Gather(void* sendbuf, int sendcount, MPI_Datatype sendtype, void* recvbuf, int recvcount, MPI_Datatype recvtype, int root, MPI_Comm comm)`
- Note: `recvcount` = # items received from each process, not total
Gather

- Maybe some processes need to send longer messages than others
- Allow varying data count from each process with MPI_Gatherv(...)
- `int MPI_Gatherv(void* sendbuf, int sendcount, MPI_Datatype sendtype, void* recvbuf, int *recvcounts, int *displs, MPI_Datatype recvtype, int root, MPI_Comm comm)`
- `recvcounts` is array; entry `i` in `displs` array specifies displacement relative to `recvbuf[0]` at which to place data from corresponding process number
Scatter

- Inverse of gather: split message into $NP$ equal pieces, with $i$th segment sent to $i$th process in group
- `int MPI_Scatter(void* sendbuf, int sendcount, MPI Datatype sendtype, void* recvbuf, int recvcount, MPI Datatype recvtype, int root, MPI Comm comm)`
- Send messages of varying sizes across processes in group: `MPI_Scatterv(...)`
- `int MPI_Scatterv(void* sendbuf, int *sendcounts, int *displs, MPI_datatype sendtype, void* recvbuf, int recvcount, MPI Datatype recvtype, int root, MPI Comm comm)`
Reduce

- Perhaps we need to do sum of many subsums owned by all processors
- Perhaps we need to find maximum value of variable across all processors
- Perform global reduce operation across all group members
- `int MPI_Reduce(void* sendbuf, void* recvbuf, int count, MPI_Datatype datatype, MPI_Op op, int root, MPI_Comm comm)`
Reduce: Predefined Operations

<table>
<thead>
<tr>
<th>MPI_Op</th>
<th>Meaning</th>
<th>Allowed Types</th>
</tr>
</thead>
<tbody>
<tr>
<td>MPI_MAX</td>
<td>Maximum</td>
<td>Integer, floating point</td>
</tr>
<tr>
<td>MPI_MIN</td>
<td>Minimum</td>
<td>Integer, floating point</td>
</tr>
<tr>
<td>MPI_SUM</td>
<td>Sum</td>
<td>Integer, floating point, complex</td>
</tr>
<tr>
<td>MPI_PROD</td>
<td>Product</td>
<td>Integer, floating point, complex</td>
</tr>
<tr>
<td>MPI_LAND</td>
<td>Logical and</td>
<td>Integer, logical</td>
</tr>
<tr>
<td>MPI_BAND</td>
<td>Bitwise and</td>
<td>Integer, logical</td>
</tr>
<tr>
<td>MPI_LOR</td>
<td>Logical or</td>
<td>Integer, logical</td>
</tr>
<tr>
<td>MPI_BOR</td>
<td>Bitwise or</td>
<td>Integer, logical</td>
</tr>
<tr>
<td>MPI_LXOR</td>
<td>Logical xor</td>
<td>Integer, logical</td>
</tr>
<tr>
<td>MPI_BXOR</td>
<td>Bitwise xor</td>
<td>Integer, logical</td>
</tr>
<tr>
<td>MPI_MAXLOC</td>
<td>Maximum value &amp; location</td>
<td>*</td>
</tr>
<tr>
<td>MPI_MINLOC</td>
<td>Minimum value &amp; location</td>
<td>*</td>
</tr>
</tbody>
</table>
Reduce: Operations

- **MPI_MAXLOC and MPI_MINLOC**
  - Returns \{max, min\} and rank of first process with that value
  - Use with special MPI pair datatype arguments:
    - `MPI_FLOAT_INT` (float and int)
    - `MPI_DOUBLE_INT` (double and int)
    - `MPI_LONG_INT` (long and int)
    - `MPI_2INT` (pair of int)
  - See MPI standard for more details

- **User-defined operations**
  - Use `MPI_Op_create(…)` to create new operations
  - See MPI standard for more details
All-Operations

● Sometimes, may want to have result of gather, scatter, or reduce on all processes

● Gather operations
  ○ int MPI_Allgather(void* sendbuf, int sendcount, MPI_Datatype sendtype, void* recvbuf, int recvcount, MPI_Datatype recvtype, MPI_Comm comm)
  ○ int MPI_Allgatherv(void* sendbuf, int sendcount, MPI_Datatype sendtype, void* recvbuf, int *recvcounts, int *displs, MPI_Datatype recvtype, MPI_Comm comm)
All-to-All Scatter/Gather

- Extension of Allgather in which each process sends distinct data to each receiver
- Block $j$ from process $i$ is received by process $j$ into $i$th block of $\text{recvbuf}$
- `int MPI_Alltoall(void* sendbuf, int sendcount, MPI_Datatype sendtype, void* recvbuf, int recvcount, MPI_Datatype recvtype, MPI_Comm comm)`
- Corresponding `MPI_Alltoallv` function also available
All-Reduce

- Same as `MPI_Reduce` except result appears on all processes
- `int MPI_Allreduce(void* sendbuf, void* recvbuf, int count, MPI_Datatype datatype, MPI_Op op, MPI_Comm comm)`
Barrier

- In algorithm, may need to synchronize processes
- Barrier blocks until all group members have called it
- \texttt{int MPI\_Barrier(MPI\_Comm \ comm)}
Bibliography/Resources: MPI/MPI Collectives


- MPICH Documentation http://www.mpich.org/documentation/guides/
Bibliography/Resources: MPI/MPI Collectives

- Message Passing Interface (MPI) Tutorial [https://hpc-tutorials.llnl.gov/mpi/](https://hpc-tutorials.llnl.gov/mpi/)
- MPI Standard at MPI Forum: [https://www.mpi-forum.org/docs/](https://www.mpi-forum.org/docs/)
  - MPI 3.1: [https://www.mpi-forum.org/docs/mpi-3.1/mpi31-report.pdf](https://www.mpi-forum.org/docs/mpi-3.1/mpi31-report.pdf)
  - MPI 4.0: [https://www.mpi-forum.org/docs/mpi-4.0/mpi40-report.pdf](https://www.mpi-forum.org/docs/mpi-4.0/mpi40-report.pdf)
INTERLUDE 2: COMPUTING PI WITH MPI COLLECTIVES

“Pi-Shaped Power Lines at Fermilab” by Michael Kappel from http://www.flickr.com/photos/m-i-k-e/4781834200/sizes/l/in/photostream/
Interlude 2: Computing $\pi$ with MPI Collectives

- In previous Interlude, you used the 6 basic MPI routines to develop a parallel program using the Method of Darts to compute $\pi$
- The communications in previous program could be made more efficient by using collectives
- Your assignment: update your MPI code to use collective communications
- Rename it `darts-collective.c` or `darts-collective.f90`