Hybrid Programming

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Gabriele Jost, Texas Advanced Computing Center

This short talk is a conglomeration of larger presentations given by the above authors at a variety of tutorials including SC08, SC09 (upcoming) ParCFD 2009, SciDAC 2009
We are grateful for the use of these slides at the NUG User Group Meeting
Computer Centers and Vendors are Responding with New Designs

- Virtually all upcoming systems have various forms of heterogeneous parallelism
  - NERSC6 with its multicore design TBA
  - Blue Waters with its Power7 hardware threaded design
    8 cores, 12 execution units/core, 4-way SMT/core
  - ASC Sequoia (follow-on to BlueGene design) with anticipated support for transactional memory
- Experts everywhere are preparing for this architecture revolution with new languages, extensions to old languages, tools (and angst)
- Our goal at NERSC is to make this as painless as possible for application scientists
- We invite you to comment on our plans
Blue Waters Project

Power7 Chip: Heart of Blue Waters

- **Base Technology**
  - 45 nm, 576 mm²
  - 1.2 B transistors
- **Chip**
  - 8 cores
  - 12 execution units/core
  - 4-way SMT/core
  - Caches
    - 32 KB I,D-cache, 256 KB L2/core
    - 32 MB L3 (private/shared)
  - Dual DDR3 memory controllers
    - 100 GB/s sustained memory bandwidth

Slide Courtesy Thom Dunning, NCSA

NERSC Users Group Meeting 2009
# Blue Waters Computing System

<table>
<thead>
<tr>
<th>System Attribute</th>
<th>Ranger</th>
<th>Blue Waters</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Vendor</strong></td>
<td>Sun</td>
<td>IBM</td>
</tr>
<tr>
<td><strong>Processor</strong></td>
<td>AMD Barcelona</td>
<td>IBM Power7</td>
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<tr>
<td>Peak Performance (PF)</td>
<td>0.579</td>
<td>&gt;20</td>
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<tr>
<td>Sustained Performance (PF)</td>
<td>&lt;0.05</td>
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<tr>
<td>Number of Cores/Chip</td>
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<td>Number of Processor Cores</td>
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<td>&gt;3</td>
</tr>
<tr>
<td>Amount of Memory (TB)</td>
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<td>&gt;6</td>
</tr>
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<td>Amount of Disk Storage (PB)</td>
<td>1.73 (s)</td>
<td>&gt;5</td>
</tr>
<tr>
<td>Amount of Archival Storage (PB)</td>
<td>2.5 (20)</td>
<td>&gt;200</td>
</tr>
<tr>
<td>External Bandwidth (Gbps)</td>
<td>10</td>
<td>&gt;10</td>
</tr>
</tbody>
</table>

Red numbers are ratios between Blue Waters and Ranger

- Blue Waters Project
- NERSC Users Group Meeting 2009
Blue Gene/P integrates a Double “Hummer” Floating Point Unit for added functionality

• Four PowerPC 450 (PPC450) cores, cache coherent
• Double "Hummer" floating point unit (FPU) per core
  - 64-bit (double precision)
  - Capable of SIMD floating-point multiply add (FMA) yielding 4 flops/cycle per core = 3.4 Gflop/s core
• L2 Cache, 2 KB, private per core, 128-byte lines
• L3 Cache, 8 MB, shared across all 4 cores, 128-byte lines
Next generation Sequoia’s programming model will likely be multilevel

Possibly ~1.5 Million cores and even more threads!

Note: Speculative Execution (SE) and Transactional Memory (TM)

Diagram courtesy Mark Seager, LLNL
Within the MPI-OpenMP hybrid model, there are variants depending on system and application.

Which programming model is fastest?

MPI everywhere?

Fully hybrid MPI & OpenMP?

In - between? (Mixed model)

Historically hybrid programming can be slower than pure MPI.
Programming models can be designed for hybrid systems

- Pure MPI (one MPI process on each CPU) “MPI-Everywhere”
- Hybrid MPI+OpenMP
  - shared memory OpenMP
  - distributed memory MPI
- Other: Virtual shared memory systems, PGAS, HPF, ...
- New Models combine MPI and UPC or CAF (see Lusk, et al. SC09, SIAM Feb. 2009.)
MPI and Threads

• MPI describes parallelism between *processes* (with separate address spaces)
• *Thread* parallelism provides a shared-memory model within a process, commonly Pthreads and OpenMP
• In the threads model of parallel programming, a single process can have multiple, concurrent execution paths
  - Pthreads (Posix Threads) is a standard library implementation that can be used for parallel programming
  - Pthreads generally provides more complicated and dynamic approaches
  - OpenMP is a set of compiler directives, callable runtime library routines, and environment variables that extend Fortran, C and C++
  - OpenMP provides convenient features for loop-level parallelism
  - OpenMP 3.0 adds task parallelism (released May 2008)
Hybrid Programming generally combines message passing with shared memory

- Other choices for a shared memory model include an implementations by Microsoft and others, as well as Pthreads
- In this talk, we concentrate on combining MPI with OpenMP
- OpenMP consists mostly of directives, where as MPI, related message passing libraries, and Pthreads methods consist of library routines
- Data movement in message passing libraries must be explicitly programmed, in contrast to OpenMP, where it happens automatically as data is read and written
- One goal of OpenMP is to make parallel programming easy
- It is also designed to be implemented incrementally
- We first explain some basic concepts of OpenMP, since we assume you are starting with an MPI program, or knowledge of MPI
Basic Concepts of OpenMP

- OpenMP is an explicit programming model, namely the programmer specifies the parallelism. The compiler and run time system translate this into the parallel execution model.
- The task of the programmer is to correctly identify the parallelism and the dependencies
- OpenMP can have both implicit and explicit synchronization points
- Although OpenMP can be used beyond loop parallelism, we recommend studying loop parallelism first as a way to understand certain concepts such as private and shared variables, false sharing, race conditions, ...
MPI Memory Model

- **Message Passing Interface**
- **Memory Model:**
  - MPI assumes a private address space
  - Private address space for each MPI Process
  - Data needs to be explicitly communicated
- **Applies to distributed and shared memory computer architectures**
OpenMP Memory Model

- OpenMP assumes a shared address space
- No communication is required between threads
- Thread Synchronization is required when accessing shared data
OpenMP Code General Structure

- Fork-Join Model:
  - Execution begins with a single “Master Thread”
  - A team of threads is created at each parallel region
  - Threads are joined at the end of parallel regions
  - Execution is continued after parallel region by the Master Thread until the beginning of the next parallel region
The ParLab at Berkeley sponsored a Parallel Computing Bootcamp

- Note: All Bootcamp taped lectures, slides can be downloaded
  - See http://parlab.eecs.berkeley.edu/bootcampagenda
  - Including:
    - OpenMP
    - PGAS Languages
    - OpenCL
    - And several other interesting lectures

- From this website, you can also download the following:
  - makefile that should work on all NERSC clusters if you uncomment appropriate lines,
  - job-franklin-serial, job-franklin-pthreads4, job-franklin-openmp4, job-franklin-mpi4,
  - job-bassi-serial, job-bassi-pthreads8, job-bassi-openmp8, job-bassi-mpi8
  - sample batch files to launch jobs on Franklin and Bassi. Use qsub to submit on Franklin and llsubmit to submit on Bassi.

- We are also preparing sample codes to be available from the NERSC Website
- We recommend if you don’t know OpenMP, you watch the ParLab BootCamp talk by Tim Mattson
Program to compute PI by quadrature, Tim starts with a simple serial program:

```c
static long num_steps = 100000;
double step;
void main()
{
    int i; double x, pi, sum = 0.0;

    step = 1.0/(double) num_steps;
    x = 0.5 * step;
    for (i=0;i<=num_steps;i++){
        x+=step;
        sum+=4.0/(1.0+x*x);
    }
    pi = step * sum;
}
```
Next he shows
Steps of Parallelization by OpenMP

• Identify concurrency in the loop, iterations may be executed concurrently:

```c
for (i=0;i<=num_steps;i++){
    x+=step;
    sum+=4.0/(1.0+x*x);
}
```

• Steps: isolate data that must be shared from data that will be local to a task
• Redefine x to remove loop carried dependence
• Look at how to rewrite the “reduction,” where results from each iteration are accumulated into a single global sum
• Trick to promote scalar “sum” to an array indexed by the number of threads to create thread local copies of shared data
Examines differences between explicitly specifying the OpenMP other methods

- Final loop with explicit safe update of shared data

```c
#include <omp.h>
static long num_steps = 100000;
#define NUM 4
double step;
void main()
{
    double pi, sum = 0.0;
    step = 1.0/(double) num_steps;
    #pragma omp parallel num_threads(NUM)
    int i, ID;    double x, psum=0.0;
    ID = omp_get_thread_num();
    for (i=ID;i<=num_steps;i+=nthreads){
        x=(i+0.5)*step;
        psum+=4.0/(1.0+x*x);
    }
    #pragma omp critical
    sum += psum
}
pi = step * sum;
```

- Along the way, example exposes concepts of private and shared data, false sharing, and other concepts. Refer to ParLab talk/slides.
Another version of the same PI program uses common OpenMP constructs

- Private clause for creating data local to a thread
- Reduction clause for managing data dependencies

```c
#include <omp.h>
static long num_steps = 100000; double step;
void main()
{
    int i; double x, pi, sum = 0.0;

    step = 1.0/(double) num_steps;
    #pragma omp parallel for private(i,x) reduction (+:sum)
    for (i=0;i<=num_steps;i++){
        x = (i+0.5)*step;
        sum = sum + 4.0/(1.0+x*x);
    }
    pi = step * sum;
}
```

- Most people would write the OpenMP in this fashion, but the example serves to illustrate some of the steps behind the directives and the thought process for shared/private variables
In order to do hybrid programming, models must be combined via Standards

- Hybrid programming (two programming models) requires that the standards make commitments to each other on semantics.
- OpenMP’s commitment: if a thread is blocked by an operating system call (e.g. file or network I/O), the other threads remain runnable.
  - This is a major commitment; it involves the thread scheduler in the OpenMP compiler’s runtime system and interaction with the OS.
  - What this means in the MPI context: An MPI call like MPI_Recv or MPI_Wait only blocks the calling thread.
- MPI’s commitments are more complex…
The MPI Standard Defines 4 Levels of Thread Safety that affect Hybrid

• Note that these are not specific to Hybrid OpenMP Models
• The are in the form of commitments that the multithreaded application makes to the MPI implementation
  – MPI_THREAD_SINGLE: only one thread in the application
  – MPI_THREAD_FUNNELED: only one thread makes MPI calls, the Master Thread in the OpenMP context (next slide)
  – MPI_THREAD_SERIALIZED: Multiple threads make MPI calls, but only one at a time (not concurrently)
  – MPI_THREAD_MULTIPLE: Any thread may make MPI calls at any time, no restrictions

• MPI-2 defines an alternative to MPI_Init
  – MPI_Init_thread(requested, provided)
    ▪ Allows applications to say what level it needs, and the MPI implementation to say what it provides
What This Means in the OpenMP Context

- **MPI_THREAD_SINGLE**
  - There is no OpenMP multithreading in the program.

- **MPI_THREAD_FUNNELED**
  - All of the MPI calls are made by the master thread i.e., all MPI calls are:
    - Outside OpenMP parallel regions, or
    - Inside OpenMP master regions, or
    - Guarded by call to MPI_Is_thread_main MPI call.
      - (same thread that called MPI_Init_thread)

- **MPI_THREAD_SERIALIZED**
  #pragma omp parallel
  ...
  #pragma omp atomic
  {
    ...MPI calls allowed here...
  }

- **MPI_THREAD_MULTIPLE**
  - Anything goes; any thread may make an MPI call at any time
Threads and MPI in MPI-2

• An implementation is not required to support levels higher than MPI_THREAD_SINGLE; that is, an implementation is not required to be thread safe in order to be standard-conforming
• A fully thread-compliant implementation will support MPI_THREAD_MULTIPLE
• A portable program that does not call MPI_Init_thread should assume that only MPI_THREAD_SINGLE is supported
For MPI_THREAD_MULTIPLE

• When multiple threads make MPI calls concurrently, the outcome will be as if the calls executed sequentially in some (any) order
• Blocking MPI calls will block only the calling thread and will not prevent other threads from running or executing MPI functions
• It is the user's responsibility to prevent races when threads in the same process post conflicting MPI calls
• User must ensure that collective operations on the same communicator, window, or file handle are correctly ordered among threads
The Current Situation

• All MPI implementations support MPI_THREAD_SINGLE (duh).
• They probably support MPI_THREAD_FUNNELED even if they don’t admit it.
  – Does require thread-safe malloc
  – Probably OK in OpenMP programs
• “Thread-safe” usually means MPI_THREAD_MULTIPLE.
• This is hard for MPI implementations that are sensitive to performance, like MPICH2.
  – Lock granularity issue
  – Working on lock-free MPICH2 implementation
• “Easy” OpenMP programs (loops parallelized with OpenMP, communication in between loops) only need FUNNELED.
  – So don’t need “thread-safe” MPI for many hybrid programs
  – But watch out for Amdahl’s Law!
How to determine thread support

MPI_Init_thread(&argc,&argv, MPI_THREAD_MULTIPLE,&provided);
printf("Supports level %d of %d %d %d %d\n", 
    provided,
    MPI_THREAD_SINGLE,
    MPI_THREAD_FUNNELED,
    MPI_THREAD_SERIALIZED,
    MPI_THREAD_MULTIPLE);

Example output:

>Supports level 1 of 0 1 2 3

Support may vary depending on chosen compiler and MPI library.
Thread Support Levels on Franklin-PGI

PGI compiler

- with libmpich.a:
  + MPICH_MAX_THREAD_SAFETY not set: Supports level 0 of 0 1 2 3
  + MPICH_MAX_THREAD_SAFETY='single': Supports level 0 of 0 1 2 3
  + MPICH_MAX_THREAD_SAFETY='funneled': Supports level 1 of 0 1 2 3
  + MPICH_MAX_THREAD_SAFETY='serialized': Supports level 2 of 0 1 2 3
  + MPICH_MAX_THREAD_SAFETY='multiple': This library does not support multiple.

- with libmpich_threadm.a:
  + MPICH_MAX_THREAD_SAFETY not set: Supports level 0 of 0 1 2 3
  + MPICH_MAX_THREAD_SAFETY='single': Supports level 0 of 0 1 2 3
  + MPICH_MAX_THREAD_SAFETY='funneled': Supports level 1 of 0 1 2 3
  + MPICH_MAX_THREAD_SAFETY='serialized': Supports level 2 of 0 1 2 3
  + MPICH_MAX_THREAD_SAFETY='multiple': Supports level 3 of 0 1 2 3
Thread Support Levels on Franklin-PathScale and gcc

PathScale and gcc compilers give same result

- with libmpich.a:
  + MPICH_MAX_THREAD_SAFETY not set: Supports level 0 of 0 1 2 3
  + MPICH_MAX_THREAD_SAFETY='single': Supports level 0 of 0 1 2 3
  + MPICH_MAX_THREAD_SAFETY='funneled': Supports level 1 of 0 1 2 3
  + MPICH_MAX_THREAD_SAFETY='serialized': Supports level 2 of 0 1 2 3
  + MPICH_MAX_THREAD_SAFETY='multiple': This library does not support multiple.

- with libmpich_threadm.a not available
Thread Support Levels on Franklin-Summary

- Without setting the env variable, we always get '0'.

- To increase the supported level,
  - We need to explicitly set the environment variable.

- The MPI_THREAD_MULTIPLE level is currently supported only for PGI.
  - To get this level, one needs to link against libmpich_threadm.a.

Thanks to Woo-Sun Yang, NERSC User Services, for testing this on Franklin
Argonne has developed tools to Visualize the Behavior of Hybrid Programs

- Jumpshot is a logfile-based parallel program visualizer of the “standard” type. Uses MPI profiling interface.
- Recently it has been augmented in two ways to improve scalability.
  - Summary states and messages are shown as well as individual states and messages.
    - Provides a high-level view of a long run.
    - SLOG2 logfile structure allows fast interactive access (jumping, scrolling, and zooming) for large logfiles.
Jumpshot and Multithreading

- Newest additions are for multithreaded and hybrid programs that use pthreads.
  - Separate timelines for each thread id
  - Support for grouping threads by communicator as well as by process
Using Jumpshot with Hybrid Programs

- SLOG2/Jumpshot needs two properties of the OpenMP implementation that are not guaranteed by the OpenMP standard
  - OpenMP threads must be pthreads
    - Otherwise, the locking in the logging library necessary to preserve exclusive access to the logging buffers would need to be modified.
  - These pthread ids must be reused (threads are “parked” when not in use)
    - Otherwise Jumpshot would need zillions of time lines.
- At NERSC, we are currently examining the use of Jumpshot and other tools for the analysis of hybrid programs
  - Part of the Cray Center of Excellence (COE) Program
Some Available Performance Tools

- **All/Most Major HPC platforms**
  - IPM Integrated Performance Manager, NERSC and others
  - Performance Visualization for Parallel Programs
    - [http://www-unix.mcs.anl.gov/perfvis](http://www-unix.mcs.anl.gov/perfvis) (jumpshot, etc)
  - TAU [http://www.cs.uoregon.edu/research/paracomp/tau/](http://www.cs.uoregon.edu/research/paracomp/tau/)
    - C++, Java, C, Fortran 90, HPF, and HPC++, and OpenMP
  - Vampir: [http://www.vampir-ng.com](http://www.vampir-ng.com) for parallel programs (Tracing supported through TAU, KOJAK, and Adaptor)
  - PAPI: Performance analysis using hardware counters
  - Paradyn - can operate on executable [http://www.cs.wisc.edu/~paradyn/](http://www.cs.wisc.edu/~paradyn/)
  - PARAVER [http://www.cepba.upc.es/paraver](http://www.cepba.upc.es/paraver)
    - MPI, OpenMP, Performance counters, system activity
  - GNU gprof

- **Also most vendors support their own tools (e.g., Cray Apprentice2)**
Visualization and Analysis of Parallel Programs

- Trace data based
- Global displays show all selected processes
  - Timeline: application execution over time
  - Counter Timeline: counter dev. over time
  - Summary Timeline: shows parallelism
  - Summary Chart: aggregated profiling
  - Activity Chart: presents per-process profiling
  - Call Tree: draws dynamic call tree
  - Message Statistics: for each process pair
  - I/O Statistics: MPI I/O operation statistics
- Process displays show a single process per window
  - Activity Chart
  - Timeline
  - Call Tree

Vampir Slides courtesy of Wolfgang E. Nagel, Holger Brunst TU Dresden.

www.vampir-ng.com
Vampir – Routine Profiles and Statistics

- **Setup Summary Chart**
  - Global Displays ⇒ Summary Chart
  - Context Menu ⇒ Select ⇒ All Symbols
  - Context Menu ⇒ Options ⇒ Per Process

- **Selected group:**
  All Master Threads
Vampir – Timeline Display

- Can display MPI collective and I/O operations
- To zoom, draw rectangle with the mouse
- Also used to select sub-intervals for statistics
Vampir – Timeline Display – Info Dialogs

Vampir 4.0 - Timeline Display

Vampir 4.0 - Identified Message
- Origin: Process 5
- Destination: Process 1
- Tag: 3
- Communicator: 0
- Interval: 11.275123 s - 11.275166 s
- Duration: 42.4 us
- Length: 640 bytes
- Data rate: 14.355 Mbytes/s

Vampir 4.0 - Source View Process 9
- Location: Process 9
- Operation: ssor (327)
- Activity: Setup (6)
- Interval: 11.271290 s - 11.282990 s
- Duration: 11.7000 ms
- Source: buts.f: Line 1 Col 1

subroutine buts( ldmx, ldmv, ldhw,
    nx, ny, nz, k,
    omega,
    v, tv,
    d, udx, udy, udz,
    ist, iend, jst, jend,
    n20, n21, ipt, jpt )

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Cray Apprentice

- Call Graph Profile
- Function Overview
- Communication & I/O Activity View
- Load balance views
- Source code mapping
- Time Line Views
- Pair-wise Communication View

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TAU Performance System Architecture

http://www.cs.uoregon.edu/research/tau/home.php

Instrumentation

- source code
- object code
- library wrapper
- binary code
- virtual machine

MEASUREMENT API

Measurement

Event creation and management

- event identifier
- entry/exit events
- atomic events
- event mapping
- event control

Profiling

- statistics
- atomic profiles
- entry/exit profiles
- I/O profiles
- profile sampling

Tracing

- trace buffering
- record creation
- trace I/O
- timestamp generation
- trace filtering
- trace merging

Performance data sources

- timing
- hardware counters
- system counters
- kernel

OS and runtime system modules

- threading
- interrupts
- runtime system
- I/O

From Sameer Shende U. Oregon
IPM Performance Tool

Integrated Performance Monitoring

- portable, lightweight
- scalable profiling
- fast hash method
- profiles MPI topology
- profiles code regions
- open source
- easy to use

But, your code’s “hot” spots may vary depending on architecture

Developed by David Skinner, LBNL
Extremely difficult to use tools on very large numbers of processors: research area

- TotalView scalability
  - BlueGene/L port included significant scaling requirements
  - Collaborative scalability project targeting traditional OSs
  - Scalable subset debugging on BG/L
- Scalable, lightweight tools
  - “Focused tools”: fewer features, but extreme scalability
  - Stack Trace Analysis Tool (STAT)
  - Scalable infrastructure: LaunchMON, MRNet
- Automatic error detection
  - Memory correctness tools
  - Umpire
  - Threading tools

Adapted from Scott Futral, Dong Ahn, and Greg Lee, LLNL
Advice for Debugging and Tuning MPI-OpenMP Hybrid Codes

- Debug and Tune MPI code and OpenMP code separately.
- Decide which loop to parallelize. Better to parallelize outer loop. Decide whether Loop permutation or loop exchange is needed.
- Choose between loop-based or SPMD.
- Use different OpenMP task scheduling options.
- Experiment with different combinations of MPI tasks and number of threads per MPI task.
- Adjust environment variables.
- Aggressively investigate different thread initialization options and the possibility of overlapping communication with computation.
- See afternoon section on hybrid programming

Adapted from Helen He LBL-NERSC
Performance Strategies

After isolating portions of code to optimize, what next?

• **Global Performance Strategies**
  - Degree of parallelism over entire code
  - Number of parallel tasks as compared with available numbers of processors
  - Uniformity of tasks / load balancing
  - Synchronization requirements

• **Processor-specific strategies**
  - If cache-based architecture: data locality
  - Parallelism via a “super scalar” processor
  - Pipelining
  - Vector processors

• **But, the way things are progressing, you may want to wait on optimization and instead consider**
  - New languages
  - Auto-tuning options
Rabensiefners Models for Hybrid

**hybrid MPI+OpenMP**
- MPI: inter-node communication
- OpenMP: inside of each SMP node

- **No overlap of Comm. + Comp.**
  - MPI only outside of parallel regions of the numerical application code

- **Overlapping Comm. + Comp.**
  - MPI communication by one or a few threads while other threads are computing

- **Masteronly**
  - MPI only outside of parallel regions
Hybrid Masteronly

Advantages

- No message passing inside of the SMP nodes
- No topology problem

Major Problems

- All other threads are sleeping while master thread communicates!
- What is inter-node bandwidth?
- MPI-lib must support at least MPI_THREAD_FUNNELED

---

```c
for (iteration ....) {
    #pragma omp parallel
    numerical code
    /*end omp parallel */

    /* on master thread only */
    MPI_Send (original data to halo areas in other SMP nodes)
    MPI_Recv (halo data from the neighbors)
} /*end for loop*/
```
Overlapping Communication and Computation

MPI communication by one or a few threads while other threads are computing

```c
if (my_thread_rank < ...) {
    MPI_Send/Recv....
    i.e., communicate all halo data
} else {
    Execute those parts of the application
    that do not need halo data
    (on non-communicating threads)
}

Execute those parts of the application
that need halo data
(on all threads)
```

This can get very complicated.
Looks a little bit more like MPI Programming.
Overlapping Communication and Computation

MPI communication by one or a few threads while other threads are computing

Three problems:

- **the application problem:**
  - one must separate application into:
    - code that can run before the halo data is received
    - code that needs halo data
  ➔ very hard to do !!!

- **the thread-rank problem:**
  - comm. / comp. via thread-rank
  - cannot use work-sharing directives
  ➔ loss of major OpenMP support (see next slide)

- **the load balancing problem**

```c
if (my_thread_rank < 1) {
    MPI_Send/Recv....
} else {
    my_range = (high-low-1) / (num_threads-1) + 1;
    my_low = low + (my_thread_rank+1)*my_range;
    my_high=high+ (my_thread_rank+1+1)*my_range;
    my_high = max(high, my_high)
    for (i=my_low; i<my_high; i++) {
        ....
    }
}
```
Overlapping Communication and Computation

MPI communication by one or a few threads while other threads are computing

Subteams

- **Important proposal for OpenMP 3.x or OpenMP 4.x**

  Barbara Chapman et al.: Toward Enhancing OpenMP’s Work-Sharing Directives.


```c
#pragma omp parallel
{
  #pragma omp single onthreads( 0 )
  {
    MPI_Send/Recv,….
  }
  #pragma omp for onthreads( 1 : omp_get_numthreads()-1 )
  for (……..)
  { /* work without halo information */
    /* barrier at the end is only inside of the subteam */
    ...
  }
  #pragma omp barrier
  #pragma omp for
  for (……..)
  { /* work based on halo information */
    }
} /*end omp parallel */
```
Multi-zone NAS Parallel Benchmarks – Characteristics

• **Aggregate sizes and zones:**
  - Class B: 304 x 208 x 17 grid points, 64 zones
  - Class C: 480 x 320 x 28 grid points, 256 zones
  - Class D: 1632 x 1216 x 34 grid points, 1024 zones
  - Class E: 4224 x 3456 x 92 grid points, 4096 zones

• **BT-MZ:**
  Block tridiagonal simulated CFD application
  - Size of the zones varies widely:
    ▪ large/small about 20
    ▪ requires multi-level parallelism to achieve a good load-balance

• **SP-MZ:**
  Scalar Pentadiagonal simulated CFD application
  - Size of zones identical
    ▪ no load-balancing required

**Expectations:**
- Pure MPI: Load-balancing problems!
- Good candidate for MPI+OpenMP
- Load-balanced on MPI level: Pure MPI should perform best
Sun Constellation Cluster Ranger (1)

- Located at the Texas Advanced Computing Center (TACC), University of Texas at Austin (http://www.tacc.utexas.edu)
- 3936 Sun Blades, 4 AMD Quad-core 64bit 2.3GHz processors per node (blade), 62976 cores total
- 123TB aggregate memory
- Peak Performance 579 Tflops
- InfiniBand Switch interconnect
- Sun Blade x6420 Compute Node:
  - 4 Sockets per node
  - 4 cores per socket
  - HyperTransport System Bus
  - 32GB memory
Sun Constellation Cluster Ranger (2)

**Compilation:**
- PGI pgf90 7.1
- mpif90 -tp barcelona-64 -r8

**Cache optimized benchmarks Execution:**
- MPI MVAPICH
- setenv
  OMP_NUM_THREAD NTHREAD
- Ibrun numactl bt-mz.exe

**numactl controls**
- Socket affinity: select sockets to run
- Core affinity: select cores within socket
- Memory policy: where to allocate memory
NPB-MZ Class E  Scalability on Ranger

- Scalability in Mflops
- MPI/OpenMP outperforms pure MPI
- Use of numactl essential to achieve scalability

**BT**
- Significant improvement (235%): Load-balancing issues solved with MPI+OpenMP

**SP**
- Pure MPI is already load-balanced.
- But hybrid programming 9.6% faster

**Hybrid:**
- **SP:** still scales
- **BT:** does not scale

**Note:** Cannot be built for 8192 processes!
Results reported for Class D on 256-2048 cores

- SP-MZ pure MPI scales up to 1024 cores
- SP-MZ MPI/OpenMP scales to 2048 cores
- SP-MZ MPI/OpenMP outperforms pure MPI for 1024 cores
- BT-MZ MPI does not scale
- BT-MZ MPI/OpenMP scales to 2048 cores, outperforms pure MPI

Expected:
- #MPI processes limited
- Load-Imbalance for pure MPI

Unexpected!
NBER-MZ Class D on IBM Power 6: Exploiting SMT for 2048 Core Results

- Results for 128-2048 cores
- Only 1024 cores were available for the experiments
- BT-MZ and SP-MZ show benefit from Simultaneous Multithreading (SMT): 2048 threads on 1024 cores

Courtesy of Gabriele Jost (TACC/NPS)
Conventional Multi-Threaded

• Threads alternate
  – Nothing shared

Charles Grassl, IBM
Simultaneous Multi-Threading

- Simultaneous execution
  - Shared registers
  - Shared functional units

Charles Grassl, IBM
AMD Opteron Processor

- L2 Cache 1 MB, 16-way assoc
- L1 Instruction Cache 64KB, 2-way assoc
- L1 Data Cache 64KB, 2-way assoc
- 44-entry Load/Store Queue
- Bus Unit
- System Request Queue
- Crossbar
- Memory Controller
- HyperTransport™

- 16 instruction bytes fetched per cycle
- 9-way Out-Of-Order execution
- 36-entry FPU instruction scheduler
- 64-bit/80-bit FP Realized throughput (1 Mul + 1 Add)/cycle: 1.9 FLOPs/cycle
- 32-bit FP Realized throughput (2 Mul + 2 Add)/cycle: 3.4+ FLOPs/cycle

NERSC Users Group Meeting 2009

Courtesy John Levesque
Simplified memory hierarchy on the AMD Opteron

- **Registers**
  - 16 SSE2 128-bit registers
  - 16 64-bit registers
  - 2 x 8 Bytes per clock, i.e. Either 2 loads, 1 load 1 store, or 2 stores (38 GB/s on 2.4 Ghz)

- **L1 data cache**
  - 8 Bytes per clock
  - 64 Byte cache line
  - Complete data cache lines are loaded from main memory, if not in L2 cache
  - If L1 data cache needs to be refilled, then storing back to L2 cache

- **L2 cache**
  - 64 Byte cache line
  - Write back cache: data offloaded from L1 data cache are stored here first until they are flushed out to main memory

- **Main memory**
  - 16 Bytes wide data bus => 6.4 GB/s for DDR400
  - Courtesy John Levesque
Hybrid parallelization affords new opportunities

- Nested Parallelism
- Load-Balancing
- Memory consumption
- Opportunities, if MPI speedup is limited due to "algorithmic" problem
- MPI scaling problems
### Load-Balancing
*(on same or different level of parallelism)*

<table>
<thead>
<tr>
<th><strong>OpenMP enables</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td>- Cheap <em>dynamic</em> and <em>guided</em> load-balancing</td>
</tr>
<tr>
<td>- Just a parallelization option (clause on omp for / do directive)</td>
</tr>
<tr>
<td>- Without additional software effort</td>
</tr>
<tr>
<td>- Without explicit data movement</td>
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</tbody>
</table>

<table>
<thead>
<tr>
<th><strong>On MPI level</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td>- <strong>Dynamic load balancing</strong> requires</td>
</tr>
<tr>
<td>moving of parts of the data structure through the network</td>
</tr>
<tr>
<td>- Significant runtime overhead</td>
</tr>
<tr>
<td>- Complicated software / therefore not implemented</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th><strong>MPI &amp; OpenMP</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td>- Simple static load-balancing on MPI level, dynamic or guided on OpenMP level</td>
</tr>
<tr>
<td></td>
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</tbody>
</table>
Memory consumption

- Shared nothing
  - Heroic theory
  - In practice: Some data is duplicated

- MPI & OpenMP
  With n threads per MPI process:
  - Duplicated data is reduced by factor n
Memory consumption (continued)

- **Future:**
  
  *With 100+ cores per chip the memory per core is limited.*
  
  - Data reduction through usage of shared memory may be a key issue
  - Domain decomposition on each hardware level
    - **Maximizes**
      - Data locality
      - Cache reuse
    - **Minimizes**
      - CCnuma accesses
      - Message passing
    - No halos between domains inside of SMP node
    - **Minimizes**
      - Memory consumption
How many multi-threaded MPI processes per SMP node

- SMP node = with $m$ sockets and $n$ cores/socket
- How many threads (i.e., cores) per MPI process?
  - Too many threads per MPI process
    → overlapping of MPI and computation may be necessary,
    → some NICs unused?
  - Too few threads
    → too much memory consumption (see previous slides)
- Optimum
  - somewhere between 1 and $m \times n$
Opportunities, if MPI speedup is limited due to “algorithmic” problems

- Algorithmic opportunities due to larger physical domains inside of each MPI process
  - If multigrid algorithm only inside of MPI processes
  - If separate preconditioning inside of MPI nodes and between MPI nodes
  - If MPI domain decomposition is based on physical zones
To overcome MPI scaling problems

- Reduced number of MPI messages, reduced aggregated message size compared to pure MPI
- MPI has a few scaling problems
  - Handling of more than 10,000 processes
  - Irregular Collectives: MPI_....v(), e.g. MPI_Gatherv()
    - Scaling applications should not use MPI_....v() routines
  - MPI-2.1 Graph topology (MPI_Graph_create)
    - MPI-2.2 MPI_Dist_graph_create_adjacent
  - Creation of sub-communicators with MPI_Comm_create
    - MPI-2.2 introduces a new scaling meaning of MPI_Comm_create
- Hybrid programming reduces all these problems (due to a smaller number of processes)
Summary of Hybrid Programming

**MPI + OpenMP**
- Significant opportunity \(\rightarrow\) higher performance on fixed number of cores
- NPB-MZ examples
  - BT-MZ \(\rightarrow\) strong improvement (as expected)
  - SP-MZ \(\rightarrow\) small improvement (none was expected)
- Often however, no speedup is obtained, especially for naïve implementations
- Hybrid MPI + OpenMP can solve certain problems with MPI-Everywhere
  - Load balancing
  - Memory consumption
  - Two levels of parallelism
    - Outer \(\rightarrow\) distributed memory \(\rightarrow\) halo data transfer \(\rightarrow\) MPI
    - Inner \(\rightarrow\) shared memory \(\rightarrow\) ease of SMP parallelization \(\rightarrow\) OpenMP
Summary (cont)

MPI+OpenMP – Pitfalls:

• Problems with OpenMP performance remain
  – On ccNUMA → e.g., first touch
  – Pinning of threads on cores

• Problems with combination of MPI & OpenMP
  – topology and mapping problems
  – mismatch problems

• Most hybrid programs → Masteronly style

• Overlapping communication and computation with several threads
  – Requires thread-safety quality of MPI library
  – Loss of OpenMP support → future OpenMP subteam concept
Hybrid Programming: more information

“Hybrid MPI and OpenMP Parallel Programming”
SC09 half-day tutorial M09, Monday, 8:30am – 12:00pm

Reminder, these slides are excerpted various tutorials given by
Rolf Rabenseifner, Gabriele Jost, Rusty Lusk, Alice Koniges, et al.
including
SC08, SC09 (upcoming) ParCFD 2009, SciDAC 2009
We are grateful for the use of these slides at the NUG
User Group Meeting