



MIC & OpenMP 4

TCG Micro
SSG DPD

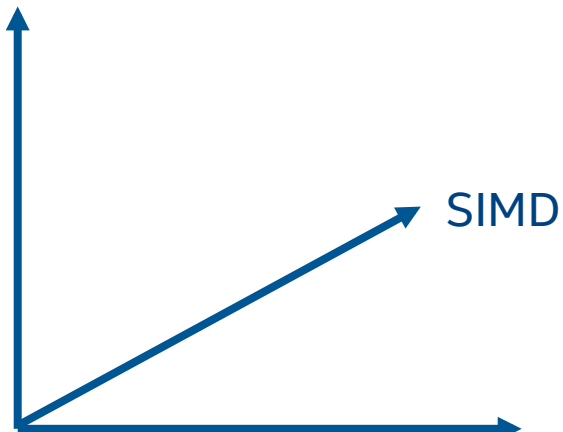
NERSC Threading Workshop, March 2015

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High-performance Parallel Computing

OpenMP*



MPI*

Moving data is expensive!

- Node-node
- Socket-Socket; Processor-(co)processor
- Core-core
- SIMD lanes

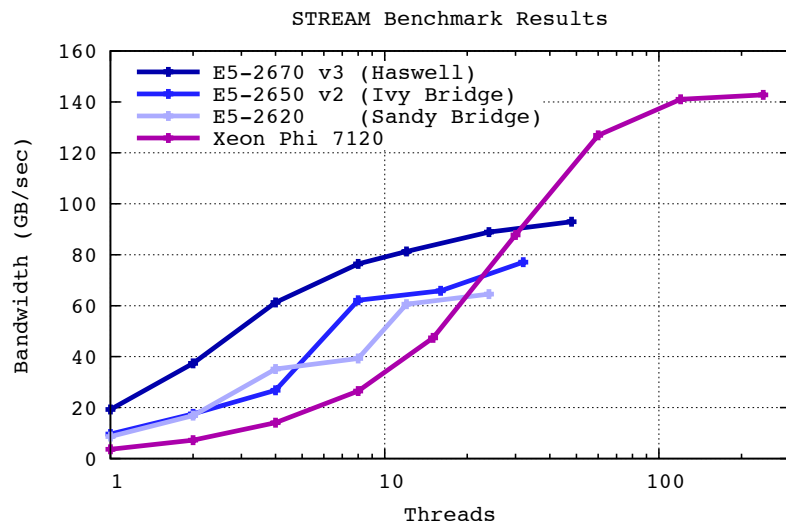
At each parallel level

- Find enough parallelism
- Decide the optimal granularity
- Optimize locality/data movement
- Ensure load balance
- Reduce the impact of coordination and synchronization

All the parallel units have to be coordinated with maximum overlap of data movement and computing.

Programming on 61 cores and 244 threads

	ES-2650 v2 (Ivy Bridge)	Xeon Phi 7120
Clock Rate GHz	2.40	1.24
# Cores/socket	12	61
# Threads/node (core)	48 (2)	244 (4)
# of sockets	2	1
Peak GFLOP/S	460.8	1210.24



Basics of high-performance parallel computing is much more critical on Xeon™ Phi.

† STREAM bandwidth.



NERSC and community resources

Cori

<https://www.nersc.gov/users/computational-systems/cori/>

Trainings

<https://www.nersc.gov/users/NUG/annual-meetings/nug-2015/hack-a-thon/>

<https://www.nersc.gov/users/training/events/OMP-vectorization-oct14/>

The Intel Xeon Phi User's Group (IXPUG)

<https://www.ixpug.org/what-ixpug>

Resources

<https://software.intel.com/en-us/mic-developer>

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Productivity via architecture innovation coupled with familiar software. Intel® Xeon Phi™ coprocessor:



GET SUPPORT

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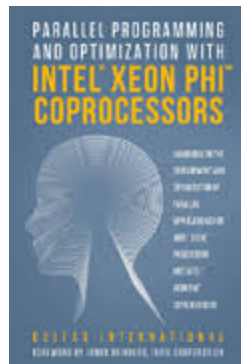
“I need a cookbook”



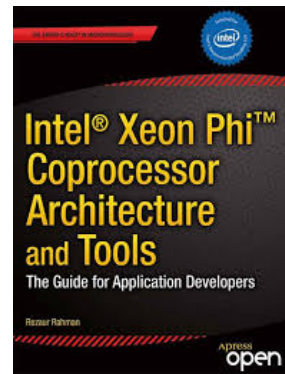
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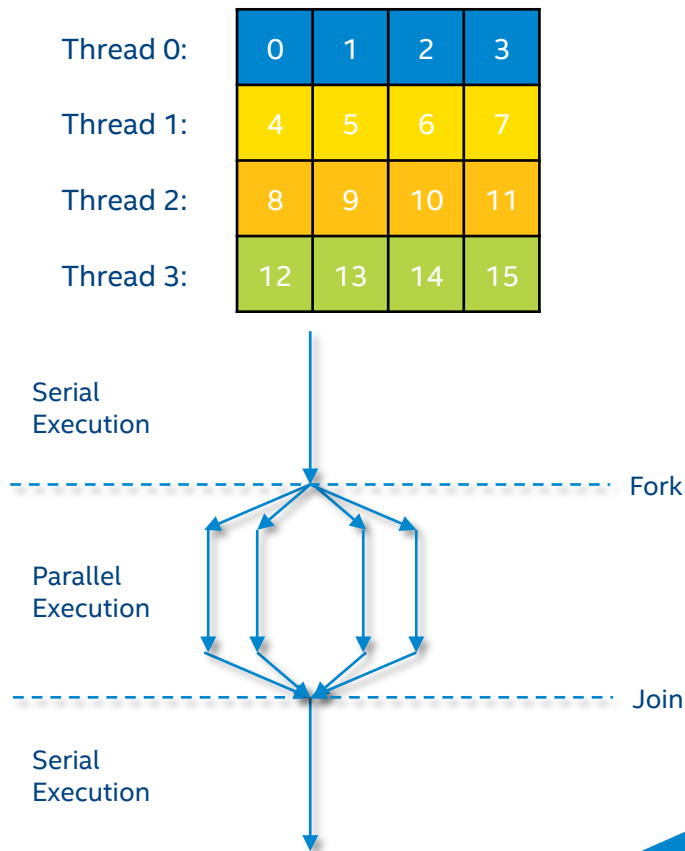


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OpenMP*: Shared Memory Systems

(Basic) OpenMP How-to:

1. Identify loops with independent operations.
2. Insert compiler directives/pragmas.
3. Add thread synchronization and/or restructure code to avoid data races.



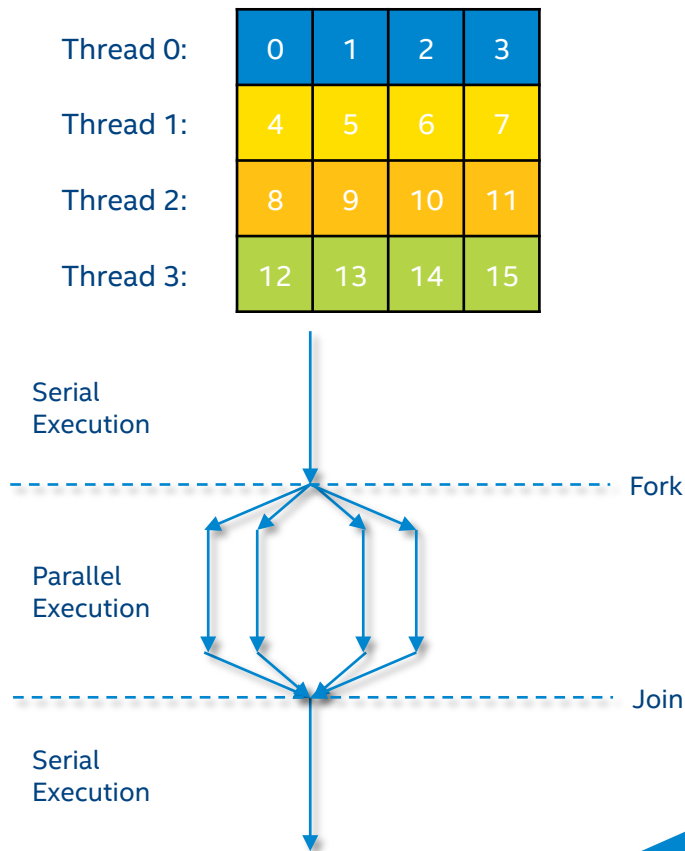
OpenMP*: Shared Memory Systems

Advantages

- Allows incremental development.
- Compiler-driven optimization.
- Support for dynamic load-balancing.

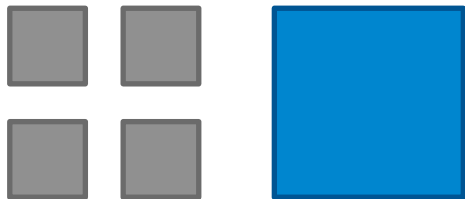
Disadvantages

- Implicit communication (“false sharing”).
- Data races are easy to introduce.
- Encourages “bolted on” parallelism.



Intel® Xeon Phi™ Coprocessor: Programming Models

Native

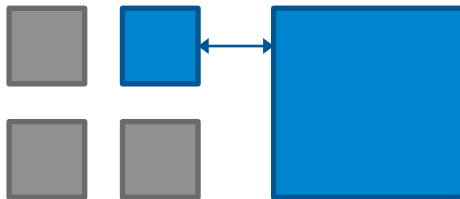


MPI*:
Ranks started on device.

OpenMP*:
Threads spawned per rank.

SIMD:
Vector loops run by threads.

Offload

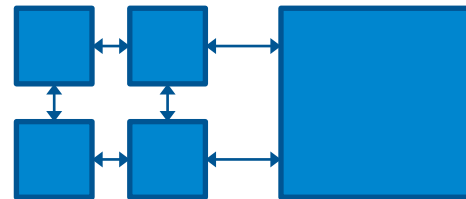


MPI:
Ranks started on host.

OpenMP:
Threads spawned in code
sections offloaded to device.

SIMD:
Vector loops run by threads.

Symmetric

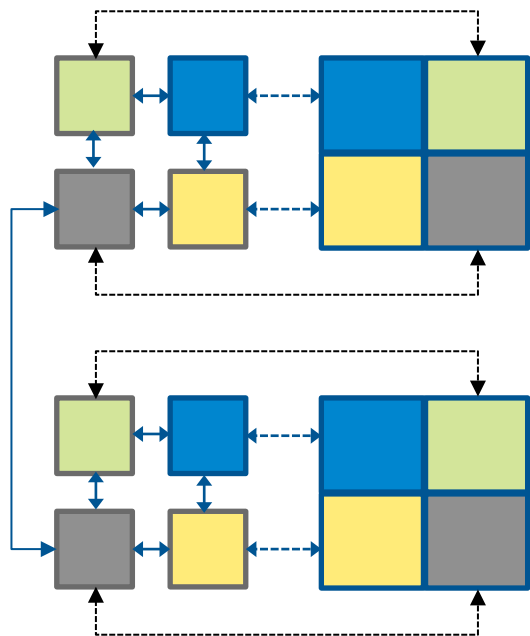


MPI:
Ranks started on host/device.

OpenMP:
Threads spawned per rank.

SIMD:
Vector loops run by threads.

Advanced Offload Use



- Host employs MPI*
- Offload to a part of a device
- Asynchronous computations and communication on the host as usual

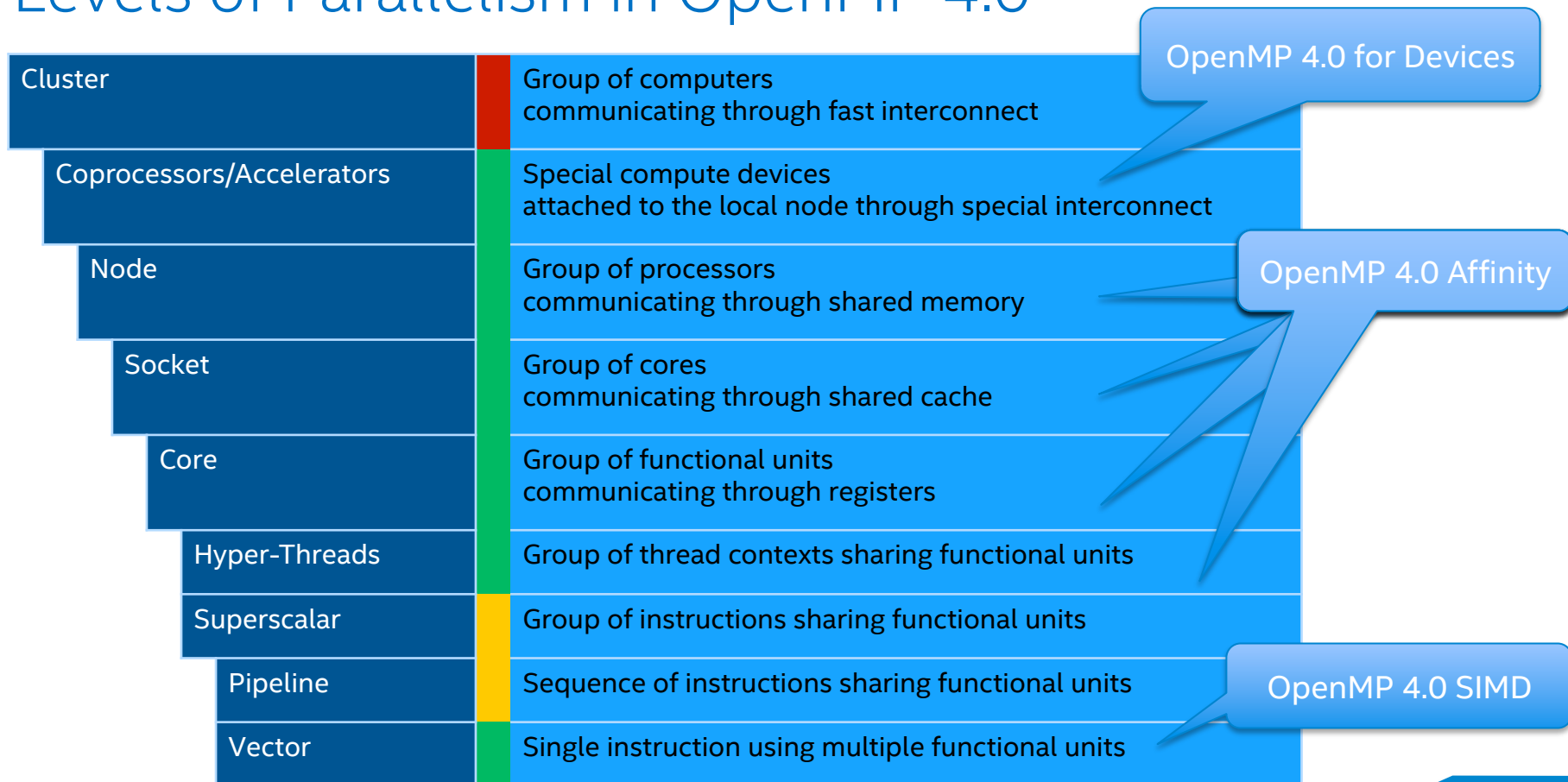
Same with host OpenMP* threads

Skipped MPI paths

OpenMP API

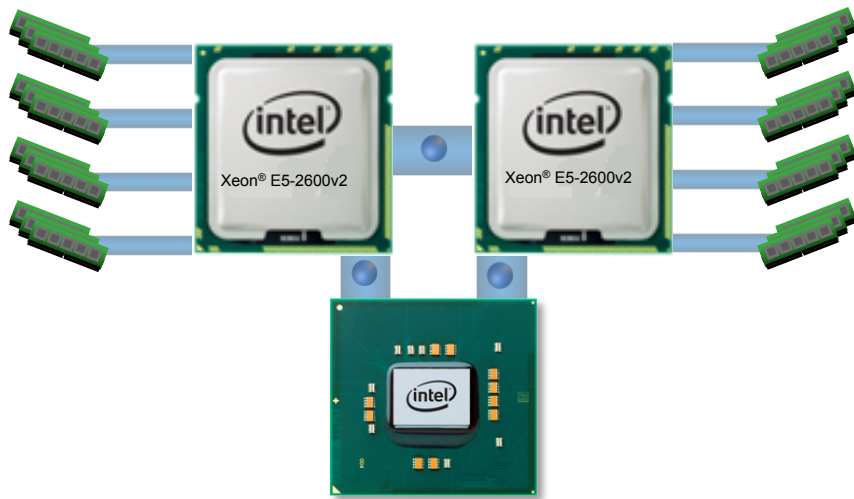
- De-facto standard, OpenMP 4.0 out since July 2013
- API for C/C++ and Fortran for shared-memory parallel programming
- Based on directives (pragmas in C/C++)
- Portable across vendors and platforms
- Supports various types of parallelism

Levels of Parallelism in OpenMP 4.0

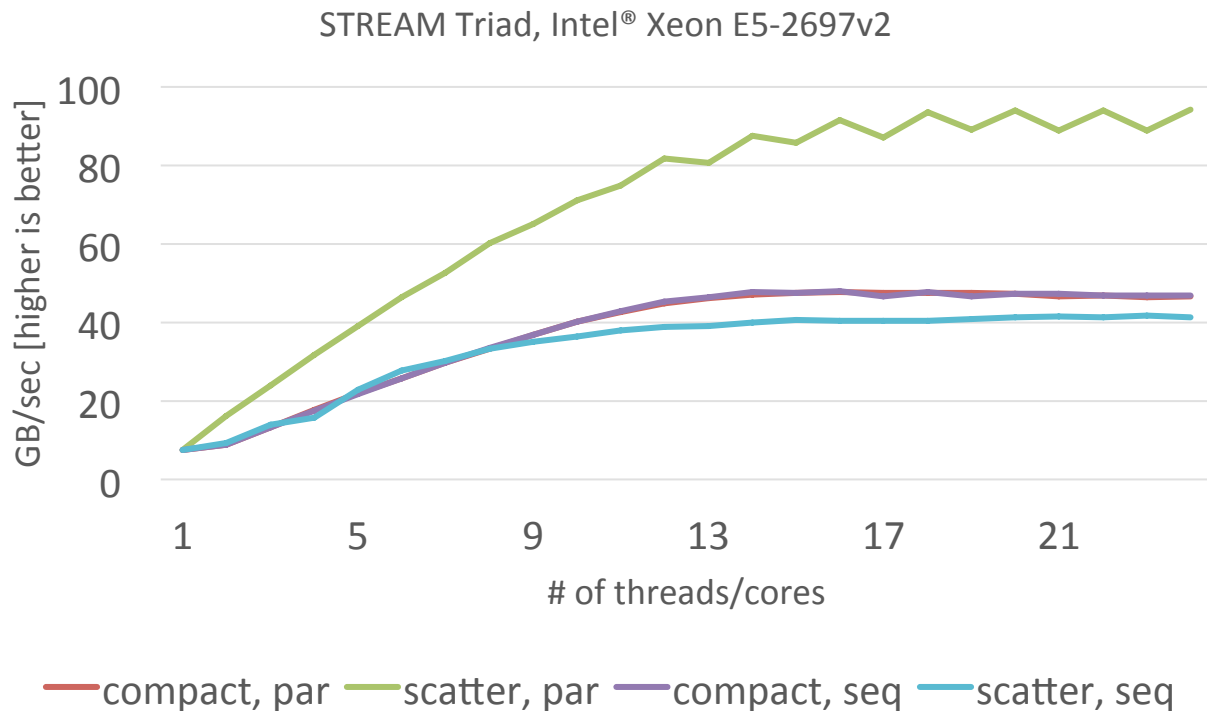


NUMA is here to Stay...

- (Almost) all multi-socket compute servers are NUMA systems
 - Different access latencies for different memory locations
 - Different bandwidth observed for different memory locations
- Example: Intel® Xeon E5-2600v2 Series processor



Thread Affinity – Why It Matters?



Thread Affinity – Processor Binding

- Binding strategies depends on machine and the app
- Putting threads far, e.g. on different packages
 - (May) improve the aggregated memory bandwidth
 - (May) improve the combined cache size
 - (May) decrease performance of synchronization constructs
- Putting threads close together, e.g. on a core sharing cache
 - (May) improve performance of synchronization constructs
 - (May) decrease the available memory bandwidth and cache size (per thread)
- Affinity is critical to MPI.

Thread Affinity in OpenMP* 4.0

OpenMP 4.0 introduces the concept of places...

- set of threads running on one or more processors
- can be defined by the user
- pre-defined places available:
 - threads: one place per hyper-thread
 - cores: one place exists per physical core
 - sockets: one place per processor package

... and affinity policies...

- spread: spread OpenMP threads evenly among the places
- close: pack OpenMP threads near master thread
- master: collocate OpenMP thread with master thread

... and means to control these settings

- Environment variables `OMP_PLACES` and `OMP_PROC_BIND`
- clause `proc_bind` for parallel regions

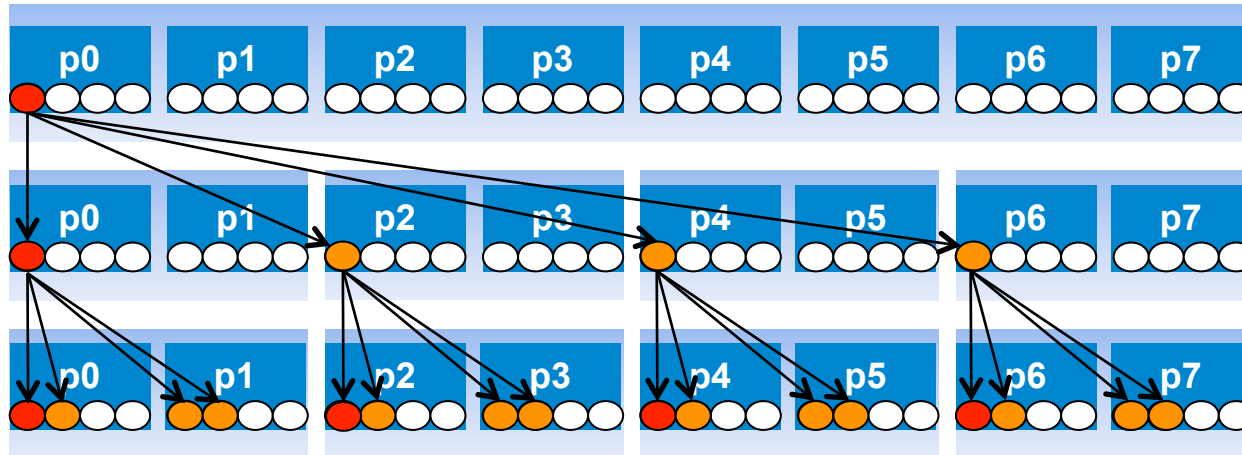
Thread Affinity Example

Example (Intel® Xeon Phi™ Coprocessor): Distribute outer region, keep inner regions close

```
OMP_PLACES=cores(8); OMP_NUM_THREADS=4,4; OMP_PROC_BIND=spread,close
```

Alternatively,

```
#pragma omp parallel proc_bind(spread)  
# pragma omp parallel proc_bind(close)
```

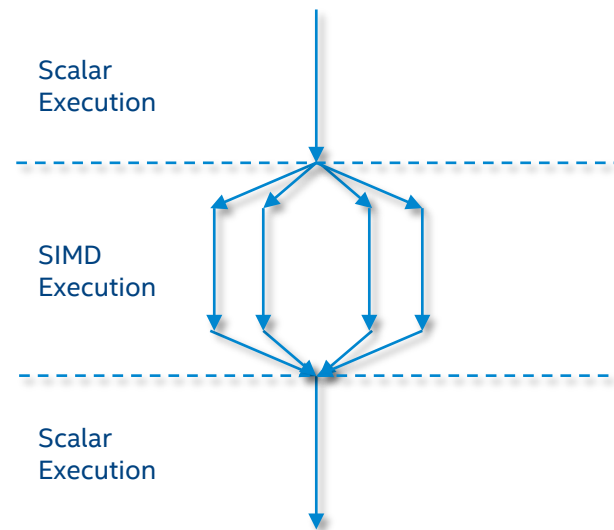


Vectorization: SIMD Machines

OpenMP* 4.0 SIMD How-to:

1. Identify loops with independent operations.
2. Insert compiler directives/pragmas.
3. Follow compiler's recommendations to enable/improve generated vector code.

Lane 0	Lane 1	Lane 2	Lane 3
0	1	2	3
4	5	6	7
8	9	10	11
12	13	14	15



Vectorization: SIMD Machines

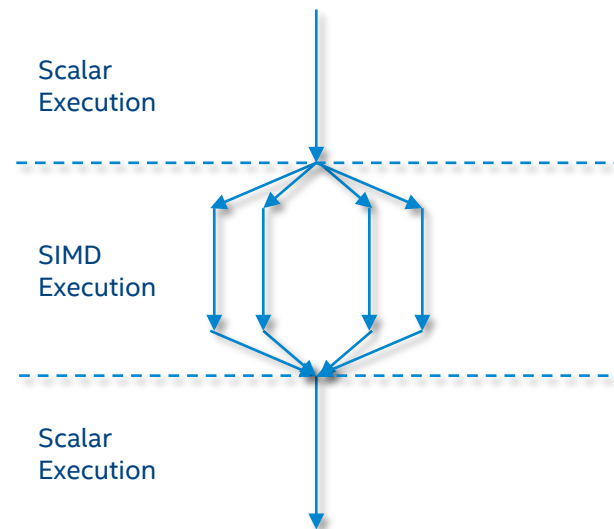
Advantages

- Allows incremental development.
- Compiler-driven optimization.
- Lanes are always synchronized.

Disadvantages

- Data structure/alignment requirements.
- Knowledge of ISA required to ensure efficient scalar to vector conversion.

Lane	Lane	Lane	Lane
0	1	2	3
0	1	2	3
4	5	6	7
8	9	10	11
12	13	14	15





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